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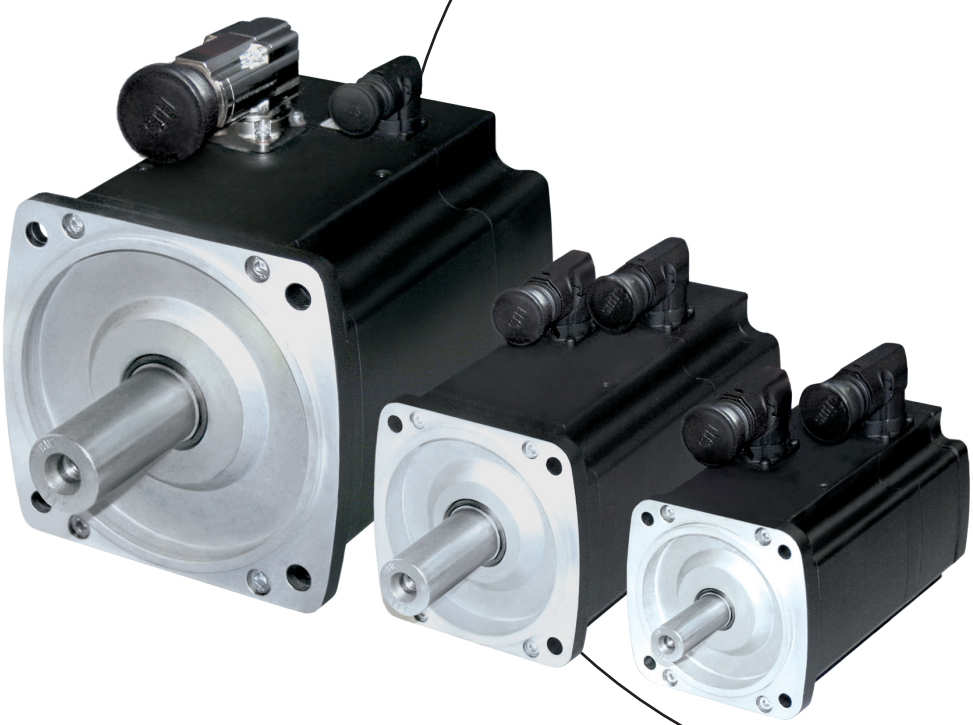

be in motion

Three-phase synchronous motors

DSP1-045-100

Table of contents

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Issue: 11/2016

1. Three-phase synchronous motors DSP1-045-100

For applications with high rotation speed requirements, the DSP1 motors complement the existing DSC series with nominal rotation speeds of up to 6000 min^{-1}. The design is identical to that of the compact DSC synchronous motors and the DSD2 dynamic servo motor series.
DSP motors are particularly well suited for applications in handling axes, processing machines and servo pump drives on account of their good acceleration and overload capacity as well as the increased rotation speed and range of performance.

1.1. General technical data

Version:	IM B5	Horizontal mounting acc. to EN 60034-7
	IM V1	Vertical mounting, shaft end at the bottom acc. to EN 60034-7
	IM V3	Vertical mounting, shaft end at the top acc. to EN 60034-7 In the case of IP64 shaft ends, protection against the ingress of water and dust must be ensured.
Degree of protection:	IP64	Standard: without shaft seal ring, with opposing plugs fitted and fully enclosed terminal boxes
	IP65	Option: with shaft seal ring, with opposing plugs fitted and fully enclosed terminal boxes
	IP65	Without consideration of shaft bushing with opposing plugs fitted and fully enclosed terminal boxes
	IP67	Without consideration of the shaft bushing for IC410 and IC 3W7, fitted with mating connectors, not for motors with terminal box
Connection	Main connection:	See chapter 3.6, 3.7, version speedtec
	Encoder connection	SpeedTec rotating socket, 12-pin
	Brake	Connection in the main connection
	Fan connection	SpeedTec rotating socket, 6-pin
	Temperature sensor	in the main connection by default, optionally in the encoder box
Temperature sensor	PT1000, KTY84–130 optional	Linear temperature sensor for the analysis in the controller
Cooling type	IC 410	Size 045-100 surface-cooled without fan
	IC 416	Size 056-100 surface-cooled with fan
	IC 3W7	Size 071-100 water-cooled machine
Temperature rise	$\Delta\vartheta$ = 105 K	Insulation class F acc. to EN 60034
Environmental conditions for running	Class 3K3/3Z12 as per DIN EN 60721-3-3: however: temperature range 0-40 °C	Represents 0 to 40 °C at 5 % to 85 % rel. humidity and an absolute humidity of 1 g/m³ to 25 g/m³ and an installation height up to approx. 1,400 m.
Environmental conditions for long-term storage	Class 1K2/1M1 DIN EN 60721-3-1: however: temperature range -15-60 °C	Represents -15 to 60 °C at 5 % to 85 % rel. humidity and an absolute humidity of 1 g/m³ to 25 g/m³; at temperatures below 3 °C you should drain the cooling water
Environmental conditions for transport	Class 2K2/2M1 DIN EN 60721-3-2: however: temperature range -15-60 °C	Represents -15 to 60 °C at 5 % to 85 % rel. humidity and an absolute humidity of 1 g/m³ to 25 g/m³; at temperatures below 3 °C you should drain the cooling water
Paint	Black matt	RAL 9005

Bearings	D end	Standard: Ball bearings. Optional: Roller bearings (for size 56-100)
	ND end	Ball bearings, locating bearings
Bearing service life	L_{10h} 20.000h	Approximate value, rolling-contact bearings with long-term grease lubrication
Balance quality	A	Acc. to DIN EN 60034-14 (VDE 0530 Part 14): 2004-09
	B	On request (for ball bearing only)
True running	N	Standard: Normal acc. to DIN 42955
	R	Optional: Reduced acc. to DIN 42955
Vibration-proof up to	3 g radially	10 Hz - 100 Hz according to EN 60068-2-6
	1 g axially	10 Hz - 100 Hz according to EN 60068-2-6 (size 028-036 without brake)
	0.5 g axially	10 Hz - 100 Hz according to EN 60068-2-6
Flange	as per standard IEC standard	Centralization diameter: tolerance j6
Shaft end	Cylindrical	Smooth acc. to DIN 748 (also available with key DIN 6885)
		Centralization with female thread as per DIN 332 Form D
Holding brake	Option	Zero play permanent magnet brake
Speed actual value encoder	Resolver	Standard, see Chapter 3.3
Approvals	CE und cULus	Standard

1.2. General safety instructions

The standard versions of the motors are unsuitable for operation in salty or aggressive atmospheres and are not suitable for erection outdoors.
Suitable steps to reduce bearing currents are to be taken before commissioning the motor, depending on the application and system. The motor manufacturer must be consulted in this regard.

Note:

With allocation of the motor in a specific protection class, it is a standardized brief test procedure. This can vary considerably depending on the actual environmental conditions at the site of installation.
Depending on the environmental conditions, such as the chemical consistency of the dust materials or the cooling media being used at the site of installation, evaluation of the suitability of the motor based on the type of protection is only possible to a limited extent (e.g. electrically conducting dust materials or aggressive coolant vapors or coolant fluids). In these cases the motor must additionally be protected by appropriate measures on the machine side.

1.3. Definition of ratings

1.3.1. Definitions of power ratings for air-cooled machines

The power ratings (torques) listed in the table applies to continuous operation (S1) at the rated speed and a maximum ambient temperature of 40°C, for machines installed below 1,000 m a.m.s.l.
If motors are to be operated at an ambient temperature of more than 40°C, or altitudes above 1,000 m a.m.s.l., the required list power rating P_L (list torque M_r) is calculated from the product of factors k_1 and k_2 (specified in the table below) and the required power rating P (torque M).

Ambient temperature	40°C	45°C	50°C	55°C	60°C
Correction factor k_1	1	1.06	1.13	1.22	1.34
Altitude a.m.s.l. up to	1.000 m	2.000 m	3.000 m	4.000 m	5.000 m
Correction factor k_2	1	1.07	1.16	1.27	1.55

Design changes may be necessary in the case of ambient temperatures above 40°C and installation of motors in an enclosure: For this reason, it is imperative that the manufacturer is contacted.

If, in the case of an increasing site altitude above 1.000 m, the ambient temperature decreases by approx. 10°C per 1.000 m increase, no power correction is necessary (note the minimum operating temperature).

1.3.2. Definitions of power ratings for water-cooled machines

The power ratings (torques) that appear in the list apply to permanent operation S1 at nominal speed, provided the cooling circuit requirements for water-cooled motors are met!

The reduction factors included in the table below must be considered when operating DSP1 motors with higher coolant inlet temperatures:

Coolant inlet temperature	25 °C	30 °C	35 °C	40 °C	45 °C
Percentage of list performance (torque)	100 %	97 %	95 %	92 %	89 %

1.4. Water cooling

1.4.1. Coolant consistency

The coolant must satisfy the following specifications:

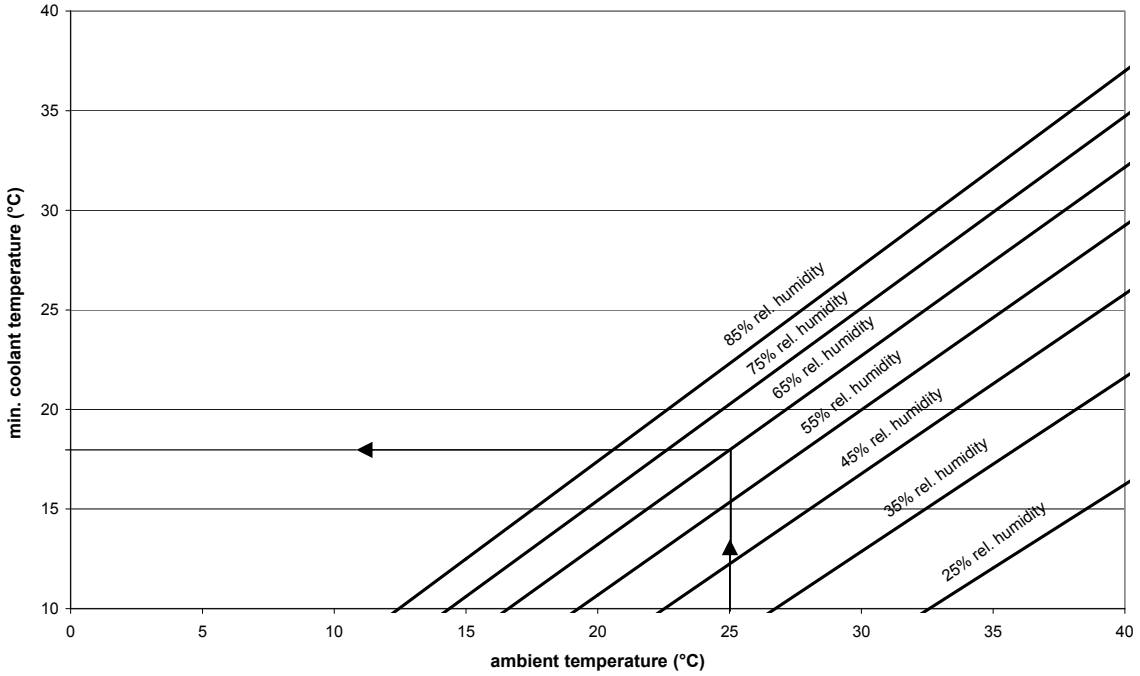
Conditions	Unit	Value
Maximum permitted system pressure	bar	6
Temperature of coolant - for motor	° C	10 to 25
pH value (at 20° C)	---	6.5 to 9
Overall hardness	mmol/l	1.43 to 2.5
Chloride - Cl^-	mg/l	< 200
Sulphate - SO_4^{2-}	mg/l	< 200
Oil	mg/l	< 1
Permitted particle size of solid foreign objects, particles (e.g. sand)	mm	< 0.1

Clean water that is free of dirt and suspended matter must be used as a coolant.

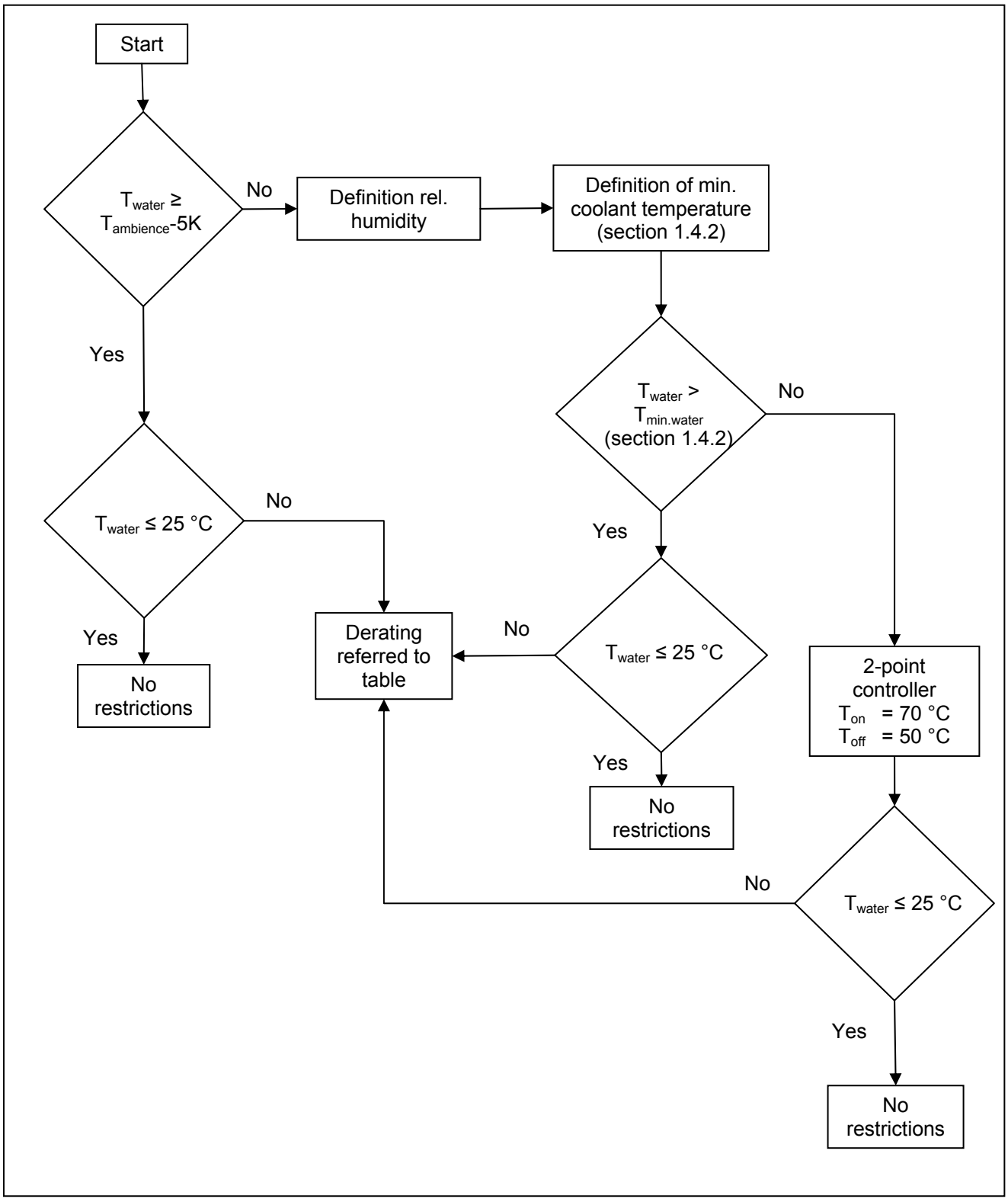
Note:
If the specific heat capacity is reduced by adding glycol for example, in dependance of the mixing ratio is a power reduction in the consequence, which is to be asked for at the manufacturer.

Compared to water cooling in the event of the use of hydraulic oil (HLP 46) a power rating reduction according to the overall length and speed of 20 to 25% arises for sizes 56-100 and 10% for size 132. The base is an inlet temperature of 35°C at both cooling mediums and an identical volume flow rate. The decrease of pressure is higher if using the hydraulic oil. Specific power ratings are available on request.

1.4.2. Min. coolant temperature against ambient temperature and humidity



The allowed coolant temperature depends on relative humidity and ambient temperature. For example with an ambient temperature of 25 °C and a relative humidity of 65% the minimum coolant temperature is 18 °C. Because these are limiting values on practical side a coolant temperature greater than 18 °C should be used. If this minimum coolant temperature will be under run the two- point controller of Baumüller drive must be used to avoid condensation.



Note:
The supply of cooling fluid must be interrupted to prevent condensation when storing for an extended period. In addition, at ambient temperatures < 3°C and if the motor has not run for an extended period, drain the cooling fluid to prevent damage caused by frost. When using anti-freeze you need to consult the manufacturer.

1.4.3. Specifications for required coolant volume flows

Motor type	Volume flow [l/min]	Pressure decrease ± 15 % [bar]	Heating [K]	Max. coolant pressure [bar]	Connection (2x) [mm]
DSP1-071KO64W	5	0.33	3	6	stainless steel tube Ø8x1
DSP1-071SO64W	5	0.4	5	6	stainless steel tube Ø8x1
DSP1-071MO64W	5	0.5	6	6	stainless steel tube Ø8x1

Motor type	Volume flow [l/min]	Pressure decrease ± 15 % [bar]	Heating [K]	Max. coolant pressure [bar]	Connection [mm]
DSP1-100KO64W	5	0.34	3	6	stainless steel tube Ø8x1
DSP1-100SO64W	5	0.4	5	6	stainless steel tube Ø8x1
DSP1-100MO64W	5	0.46	7	6	stainless steel tube Ø8x1
DSP1-100LO64W	5	0.52	9	6	stainless steel tube Ø8x1

Controlling the feed valve individually is possible, depending on the motor temperature measured by the temperature sensor.

Note:
The given cooling volume flows relate to the highest rotary speed of the relevant motor lengths.
It is possible to make an individual cooling unit evaluation on the basis of the motors power loss ($P_V = P_N / \eta_N – P_N$). The cooling unit should be scaled so that its cooling performance matches the motor power loss and so that 100% of the waste heat is diffused by the unit.

Sufficient quantities of additives for corrosion and germ protection must be mixed in. The additive type and dosage are based on recommendations from the additive manufacturer and the prevailing ambient conditions.
A lowering of the specific heating capacity leads to an output reduction in relation to the mixing ratio which should be enquired at the manufacturer.

1.4.4. Materials in the motor that make contact with the product

The following materials that make contact with the medium are used in the motor:

Cooling system: stainless steel

Water connections: According to standard, the motors are supplied with a stainless steel tube Ø8x1 without additional connection technology. The water connection with the John Guest - quick connector SM 040 808 S can be optionally provided (dia 8 by dia 8). Please include this option including the order code when ordering.

1.5. Winding insulation and heating

The motors are designed for operation on converters with intermediate circuit voltages up to 640 V.

Higher intermediate link voltages of ≤ 800 V are possible, if voltage spikes on the motor terminals are limited to <1200V by suitable filters in the motor supply line.

1.6. Explanation of motor data

n_N	Rated speed [rpm]
M_0	Nominal torque [Nm] with speeds ≥ 1 [rpm] without time limit
I_0	nominal current [A] at M_0
$M_{0,max}$	Maximum static torque [Nm] with maximum current [A] and speed = 0, momentarily
$I_{0,max}$	Static current [A] at $M_{o,\ max}$; I_{0max} is the effective value
P_N	Rated output [kW] with M_N and n_N (see Performance definition)
M_N	Rated torque [Nm]
I_N	Rated effective current [A]
$k_{E\ /\ cold}$	Voltage constant (EMF) to [V per 1000 rpm]
f_N	Rated frequency [Hz]
J	Rotor inertia incl. resolver without holding brake [kgm²]
m	Motor mass [kg]

When the converter is operating, the specified rated outputs and torques at the rated speed are achieved with a clocking frequency of ≥ 4 kHz in the power divider. We recommend a cycle frequency of > 6 kHz.
All converters scheduled for use must have the option of field weakening as a mandatory requirement.

The ***sizemaXX*** drive configurator is available at *www.baumueller.de* for designing the motors and the overall drive system.

1.7. Type key

DSP1-XXXXXXXX-XX-XX-XXX-XXX-X-XX-X-XXX	**Motor type**
DSP1-**XXX**XXXXX-XX-XX-XXX-XXX-X-XX-X-XXX	**Size** 045 056 071 100
DSP1-XXX**XX**XXX-XX-XX-XXX-XXX-X-XX-X-XXX	**Length** KO SO MO LO
DSP1-XXXXX**XX**X-XX-XX-XXX-XXX-X-XX-X-XXX	**Degree of protection** 64 - Degree of protection IP64 65 - Degree of protection IP65

DSP1-XXXXXXX**X**-XX-XX-XXX-XXX-X-XX-X-XXX	**Cooling** U - without fan O - with fan, 230 VAC Connection voltage W – water cooling
DSP1-XXXXXXXX-**XX**-XX-XXX-XXX-X-XX-X-XXX	**Rated speed class** 10 - 1000 rpm 20 - 2000 rpm 30 - 3000 rpm 40 - 4000 rpm 60 - 6000 rpm
DSP1-XXXXXXXX-XX-**XX**-XXX-XXX-X-XX-X-XXX	**DC link voltage** 54 - 540 V
DSP1-XXXXXXXX-XX-XX-**X**XX-XXX-X-XX-X-XXX	**Encoder type** A – Resolver, 2-pin M - Resolver, 2-pin (Safety) Z – Resolver, 8-pin
DSP1-XXXXXXXX-XX-XX-X**X**X-XXX-X-XX-X-XXX	**Brake** O - Without brake B - With PE-brake
DSP1-XXXXXXXX-XX-XX-XX**X**-XXX-X-XX-X-XXX	**Shaft options** A - smooth shaft B - with key
DSP1-XXXXXXXX-XX-XX-XXX-**X**XX-X-XX-X-XXX	**Main connection type** K – Terminal box (KTY on main connection) T – Terminal box (KTY on encoder socket) M – Terminal box (PT1000 on main connection) Signal socket speedtec N – Terminal box (PT1000 on encoder socket) Signal socket speedtec B – Connector socket speedtec (PT1000 on main connection) D – Connector socket speedtec (PT1000 on the encoder socket)
DSP1-XXXXXXXX-XX-XX-XXX-X**X**X-X-XX-X-XXX	**Main connection outflow** L - Left with a view toward D side on the shaft end R - Right with a view toward D side on shaft end D - DE (D side) N - NDE (N side) P - Pivoted (rotating)

DSP1-XXXXXXXX-XX-XX-XXX-XX**X**-X-XX-X-XXX	**Encoder connection outlet** L - Left with a view toward D side on the shaft end R - Right with a view toward D side on shaft end D - DE (D side) N - NDE (N side) P - Pivoted (rotating)
DSP1-XXXXXXXX-XX-XX-XXX-XXX-**X**-XX-X-XXX	**Bearings** K - Ball bearing (Kugellager) D side R - Roller bearing D side
DSP1-XXXXXXXX-XX-XX-XXX-XXX-X-**X**X-X-XXX	**Vibration class** A - Vibration class A B - Vibration class B
DSP1-XXXXXXXX-XX-XX-XXX-XXX-X-X**X**-X-XXX	**True running** N - Normal R - Reduced
DSP1-XXXXXXXX-XX-XX-XXX-XXX-X-XX-**X**-XXX	**Transmission / pump mounting** O - without transmission mounting and without pump mounting A - BPE - Transmission B - BPEF - Transmission C - BPEA - Transmission D - BPN - Transmission E - BPNA - Transmission F - BPNF - Transmission G - BPV - Transmission H - BPVF - Transmission
DSP1-XXXXXXXX-XX-XX-XXX-XXX-X-XX-X-**XXX**	**Special design** 000 - No special version 040 - Water connection with connector 041 - Fan with 24 VDC supply voltage 042 – Fan with 115 VAC supply voltage XXX - Special version (internal coding) Special coding is made alphanumeric

- Example configuration: DSP1-071MO64W-60-54-AOA-MNP-K-AN-O-000

2. Technical data

2.1. DSP1-045

DSP1-045..64U-..-..-A/Z (Resolver, without fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated out-put[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated fre-quen-cy	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
6000	DSP1-045KO64U-60-54	2.2	2.8	8.7	13.4	1.2	2	2.6	56.1	400	1.3	4
	DSP1-045SO64U-60-54	4	4.8	17	26.1	2.1	3.4	4.2	57.6	400	2.0	5.5
	DSP1-045MO64U-60-54	5.1	6.6	26	41.4	2.5	4	5.4	54.6	400	2.8	7

[1] Coil overtemperature $\Delta T < 105K$; direct flange mounting (mounting plate 250 x 250 x 10 mm)
[2] Rotor inertia moment with PE brake: +0.6 kgcm²
[3] Weight with PE brake: +1.0 kg

2.2. DSP1-056

DSP1-056..64U-..-..-A/Z (Resolver, without fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated out-put[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated fre-quen-cy	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
4000	DSP1-056MO64U-40-54	12	10.3	47	49.6	3.7	8.9	7.8	82.9	266.6	9.8	12
6000	DSP1-056KO64U-60-54	4.8	6.2	16	24.8	2.5	3.9	5.3	55.3	400	4	7
	DSP1-056SO64U-60-54	8.8	10.8	31	47.3	4	6.4	8	58	400	6.9	9.5
	DSP1-056MO64U-60-54	12	15.1	47	73	4.5	7.1	9.2	56.7	400	9.8	12

DSP1-056..64O-..-..-A/Z (Resolver, with fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated out-put[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated fre-quen-cy	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
4000	DSP1-056MO64O-40-54	16	13.8	47	49.6	5.7	14	11.8	82.9	266.6	9.8	15
6000	DSP1-056KO64O-60-54	6.1	7.8	16	24.8	3.2	5.1	6.7	55.3	400	4	10
	DSP1-056SO64O-60-54	12	14	31	47.3	5.9	9.4	11.6	58	400	6.9	12.5
	DSP1-056MO64O-60-54	16	20.2	47	73	7.9	13	16	56.7	400	9.8	15

[1] Coil overtemperature $\Delta T < 105K$; direct flange mounting (mounting plate 450 x 400 x 30 mm)
[2] Rotor inertia moment with PE brake: +2.9 $kgcm^2$
[3] Weight with PE brake: +2.0 kg

2.3. DSP1-071

DSP1-071..64U-..-..-A/Z (Resolver, without fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated output[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated frequency	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
4000	DSP1-071MO64U-40-54	24	22.9	79	94	5.9	14	13.8	73.3	266.6	27.8	18.8
6000	DSP1-071KO64U-60-54	8.7	12.5	26	45.7	4.4	7	10.3	50.2	400	12	9.6
	DSP1-071SO64U-60-54	17	23.6	53	91	6.2	9.8	14.4	50.2	400	20	14.2
	DSP1-071MO64U-60-54	24	33.9	79	139	5.1	8.2	12.4	49.6	400	27.8	18.8

DSP1-071..64O-..-..-A/Z (Resolver, with fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated output[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated frequency	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
4000	DSP1-071MO64O-40-54	31	30.4	80	94	11	25	24.8	73.3	266.6	27.8	21.9
6000	DSP1-071KO64O-60-54	11	16.2	27	45.7	5.4	8.6	12.5	50.2	400	12	12.7
	DSP1-071SO64O-60-54	21	30.7	53	91	10	16	23.3	50.2	400	20	17.3
	DSP1-071MO64O-60-54	31	44.9	79	139	14	23	32.8	49.6	400	27.8	21.9

DSP1-071..64W-..-..-A/Z (Resolver, water cooled)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated output[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated frequency	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
4000	DSP1-071MO64W-40-54	48	48.5	79	94	19	45	45.1	71.9	266.6	27.8	20.4
6000	DSP1-071KO64W-60-54	15	21.2	27	45.7	8.3	13	19.2	49.2	400	12	11.7
	DSP1-071SO64W-60-54	31	44.7	53	91	17	28	40.4	49.2	400	20	16.1
	DSP1-071MO64W-60-54	48	72	79	139	27	43	64	48.6	400	27.8	20.4

[1] Coil overtemperature $\Delta T < 105K$; direct flange mounting (mounting plate 450 x 400 x 30 mm)
[2] Rotor inertia moment with PE brake: +7.9 $kgcm^2$
[3] Weight with PE brake: +3.0 kg

2.4. DSP1-100

DSP1-100..64U-..-..-A/Z (Resolver, without fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated out-put[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated fre-quen-cy	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
1000	DSP1-100LO64U-10-54	56	16.6	150	55	5.2	50	14.8	245	66.7	108	40.2
2000	DSP1-100LO64U-20-54	56	32.1	150	106	9.1	44	25	127	133.3	108	40.2
3000	DSP1-100MO64U-30-54	45	36.3	115	112	9.5	30	24.3	90	200	84	33
	DSP1-100LO64U-30-54	56	42.9	150	142	12	37	28.6	94.6	200	108	40.2
4000	DSP1-100KO64U-40-54	18	20.1	39	53	4.9	12	13.4	63.4	266.7	35.6	18.5
	DSP1-100SO64U-40-54	33	35	77	99	8.6	21	21.9	67.6	266.7	60	25.7
	DSP1-100MO64U-40-54	45	46	115	142	11	26	26.4	71	266.7	84	33
	DSP1-100LO64U-40-54	56	50	150	165	13	30	27.6	81.1	266.7	108	40.2
6000	DSP1-100KO64U-60-54	18	28.7	39	76	5.2	8.2	13.6	44.4	400	35.6	18.5
	DSP1-100SO64U-60-54	33	46.7	77	132	9	14	20.8	50.7	400	60	25.7
	DSP1-100MO64U-60-54	45	54	115	165	11	18	22	60.8	400	84	33

DSP1-100..64O-..-..-A/Z (Resolver, with fan)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated out-put[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated fre-quen-cy	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
1000	DSP1-100LO64O-10-54	74	22.2	155	55	7.2	69	20.7	245	66.7	108	47
2000	DSP1-100LO64O-20-54	74	42.9	155	106	13	64	36.9	127	133.3	108	47
3000	DSP1-100MO64O-30-54	55	44.9	115	112	14	46	37.2	90	200	84	36.9
	DSP1-100LO64O-30-54	74	57	150	142	18	58	45.1	94.6	200	108	47
4000	DSP1-100KO64O-40-54	22	25.4	39	53	7.1	17	19.7	63.4	266.7	35.6	22.4
	DSP1-100SO64O-40-54	39	42.1	77	99	13	31	33.3	67.6	266.7	60	29.6
	DSP1-100MO64O-40-54	55	51	115	128	18	42	39.5	78.6	266.7	84	36.9
	DSP1-100LO64O-40-54	74	67	150	165	22	52	47.3	81.1	266.7	108	47
6000	DSP1-100KO64O-60-54	22	36.3	39	76	9.2	15	24.6	44.4	400	35.6	22.4
	DSP1-100SO64O-60-54	39	56	77	132	17	27	38.6	50.7	400	60	29.6
	DSP1-100MO64O-60-54	55	66	115	165	22	36	42.8	60.8	400	84	36.9

[1] Coil overtemperature $\Delta T < 105K$; direct flange mounting (mounting plate 450 x 400 x 30 mm)
[2] Rotor inertia moment with PE brake: +17.6 $kgcm^2$
[3] Weight with PE brake: +6.0 kg

DSP1-100..64W-..-..-A/Z (Resolver, water cooled)

3 AC 400 V mains voltage for converters with unregulated supply

Nom. speed	Motor type	Stand-still torque[1]	Stand-still current[1]	max. static torque	Max. static current	Rated out-put[1]	Rated torque[1]	Rated current[1]	Voltage constant	Rated fre-quen-cy	Rotor inertia (motor)[2]	Weight[3]
n_N		M_0	I_0	$M_{0.max}$	$I_{0.max}$	P_N	M_N	I_N	$k_{E/cold}$	f_N	J	m
min^{-1}		Nm	A	Nm	A	kW	Nm	A	$V/_{10001/min}$	Hz	$kgcm^2$	kg
1000	DSP1-100LO64W-10-54	115	36.6	150	55	12	110	35.7	245	66.7	108	45.2
2000	DSP1-100LO64W-20-54	115	71	150	106	22	105	67	127	133.3	108	45.2
3000	DSP1-100MO64W-30-54	84	74	115	112	24	75	66	90	200	84	37.2
	DSP1-100LO64W-30-54	115	95	150	142	32	100	86	94.6	200	108	45.2
4000	DSP1-100KO64W-40-54	27	32.2	39	53	11	25	30.3	63.4	266.7	35.6	21.2
	DSP1-100SO64W-40-54	55	63	77	99	21	50	56	67.6	266.7	60	29.2
	DSP1-100MO64W-40-54	84	94	115	142	30	72	80	71	266.7	84	37.2
6000	DSP1-100KO64W-60-54	27	46	39	76	15	25	41.8	44.4	400	35.6	21.2
	DSP1-100SO64W-60-54	55	84	77	132	29	46	70	50.7	400	60	29.2

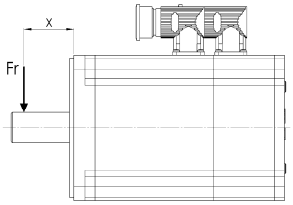
[1] Coil overtemperature Δ T < 105K; direct flange mounting (mounting plate 450 x 400 x 30 mm)
[2] Rotor inertia moment with PE brake: +17.6 kgcm²
[3] Weight with PE brake: +6.0 kg

2.5. Radial force diagrams

All bearings are designed for a service life of 20,000 h L_{10h}. The load values specified below may thereby not be exceeded. The permissible radial forces F_R are valid only for the horizontal installation of the motor without additional axial forces.
Furthermore, the specified average speeds must be adhered to reach the grease consumption period of 20,000 h under the following conditions:

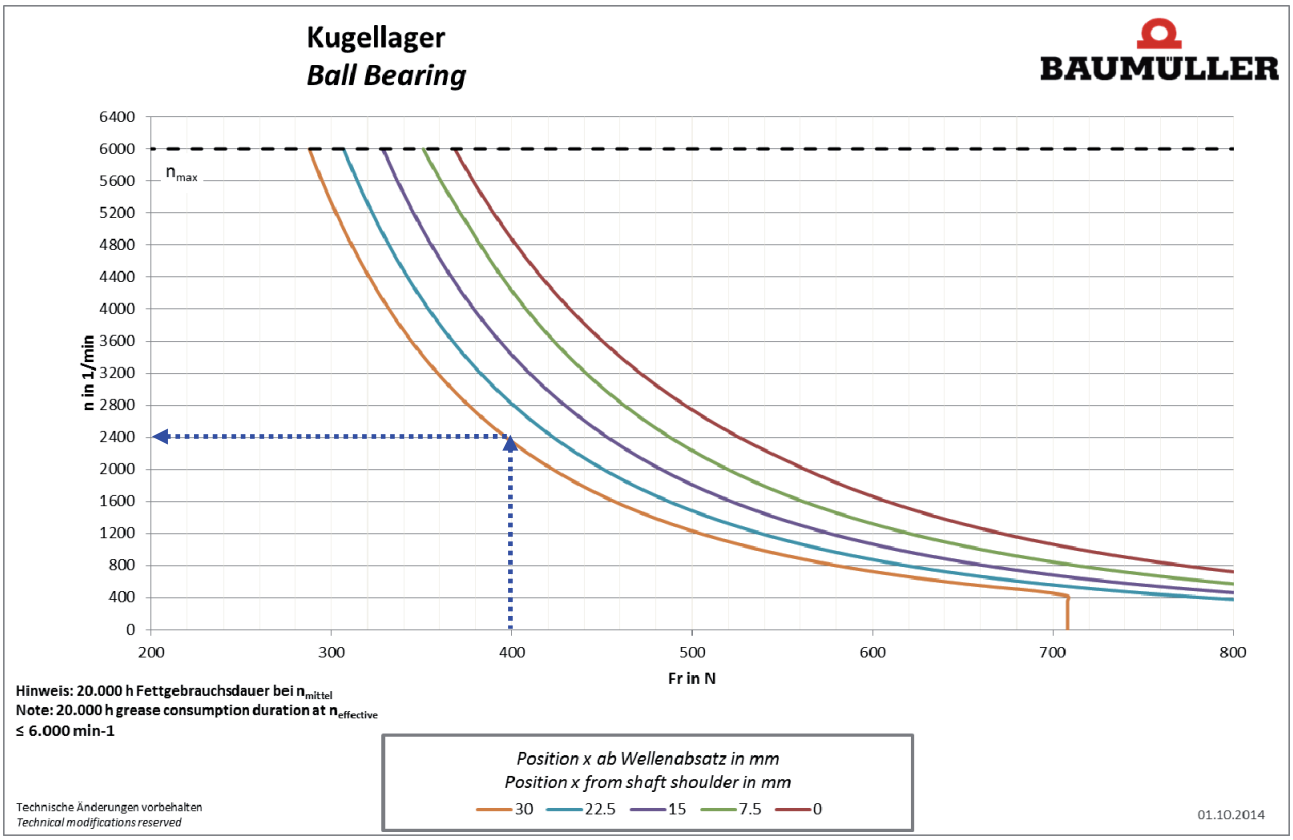
- low-vibration applications
- horizontal installation
- oscillatory bearing motion in which at least one pivot angle of 180° is performed
- Continuous bearing temperatures <120° C.

Axial loading on the motor shaft is generally not permitted.
No axial forces may develop when mounting clutches, pulleys, etc. on the motor shaft!



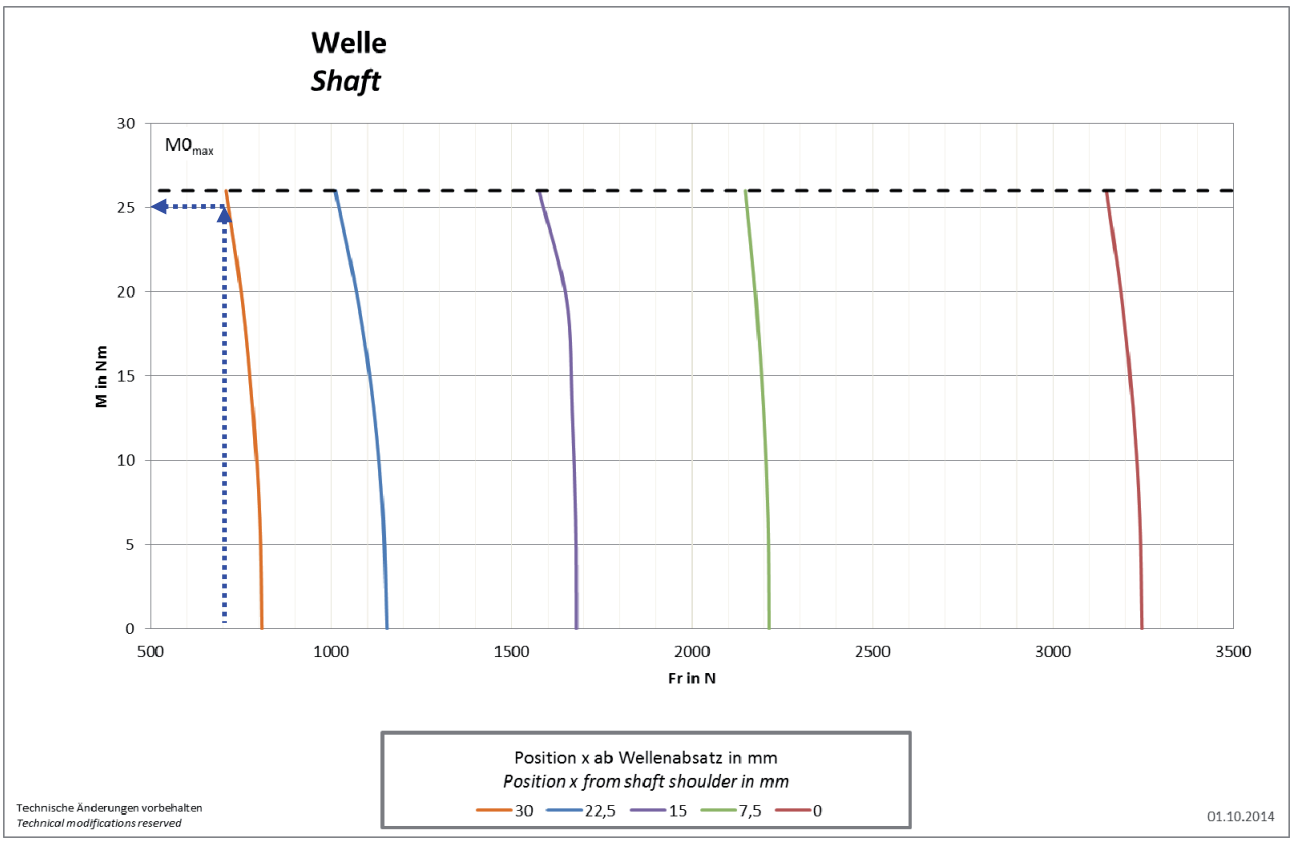
2.5.1. Sample diagram

Sample diagrams:
Driving forces x = 30 mm from the shaft shoulder
Bearing service life 20,000 h, shaft with parallel key groove



Explanation of the sample chart:

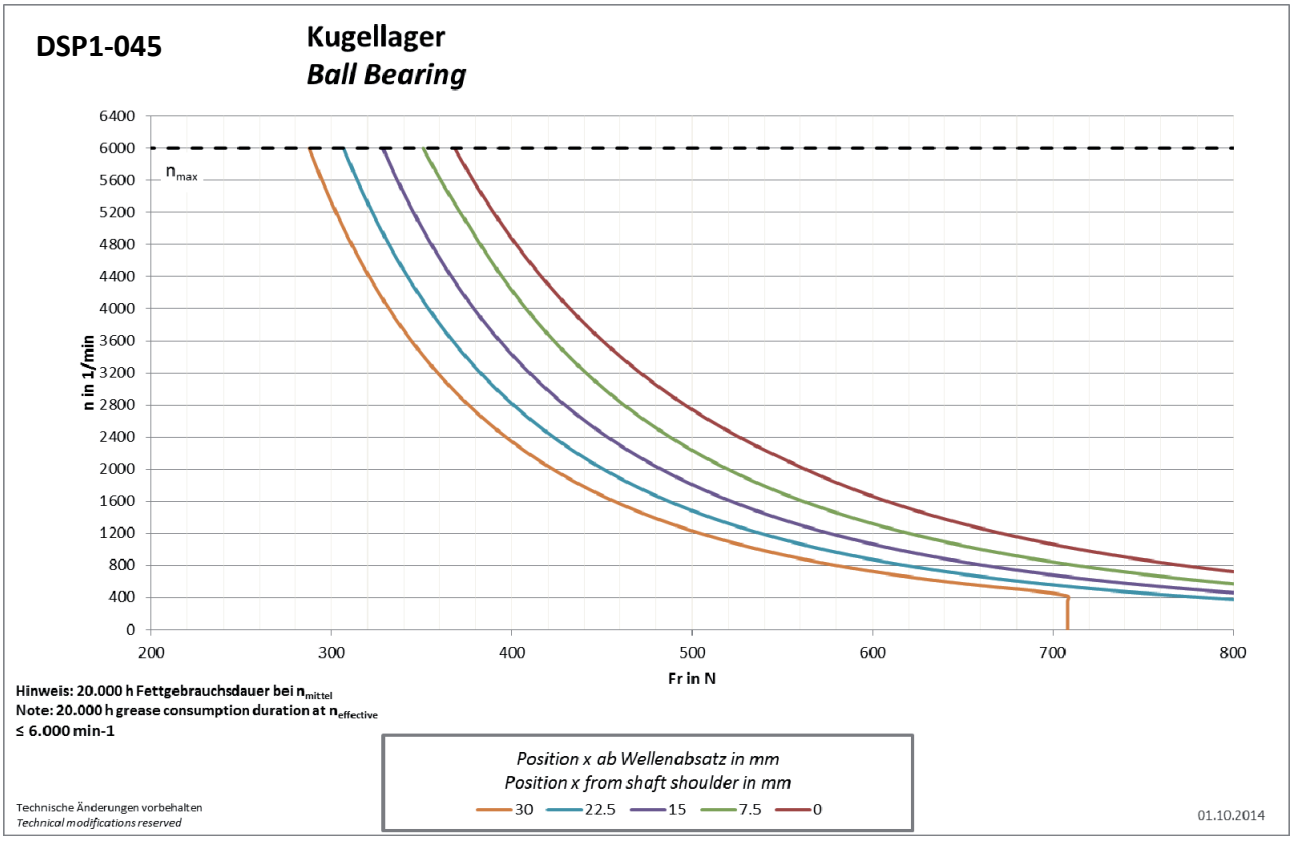
The potential maximum speed of the bearing can be calculated via radial force Fr of the application in characteristic "ball bearing".
At a radial force of 400 N with a driving force point of x = 30 mm from the shaft shoulder, a maximum speed of 2400 rpm results.

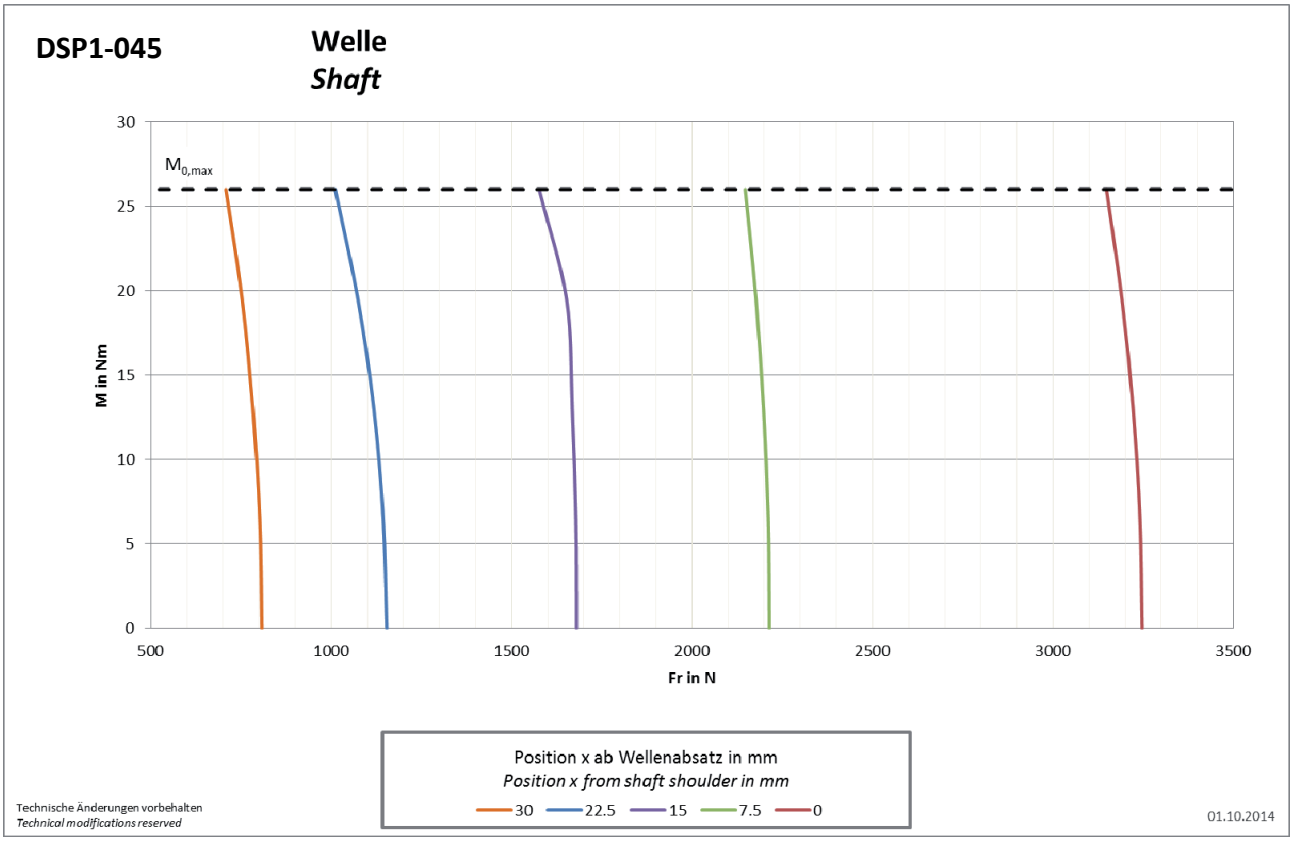


Explanation of the sample chart:

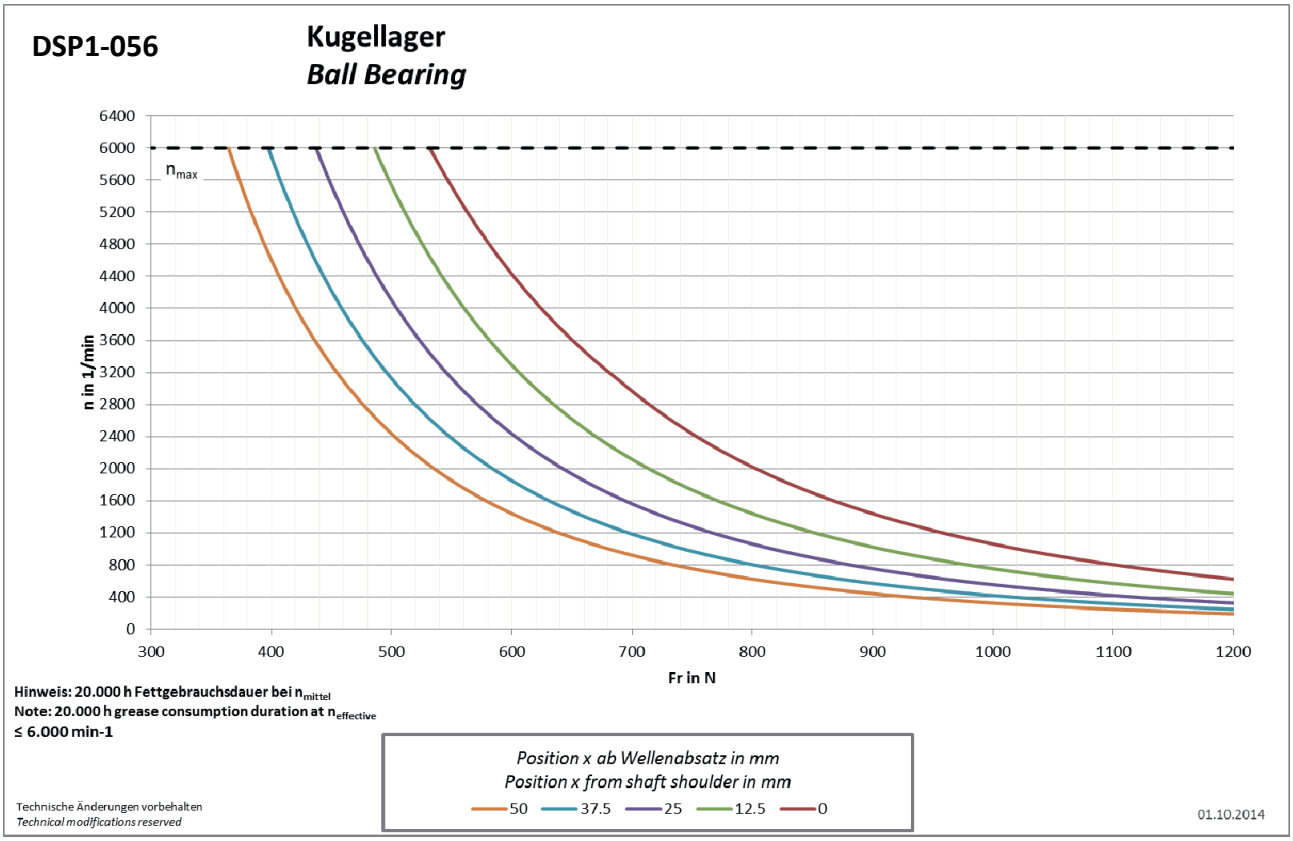
The maximum torque to be still transmitted results from the characteristic "shaft".
At a centrifugal force of 700 N with a driving force point of x = 30 mm from the shaft shoulder, a torque to be still transmitted of 25Nm results.

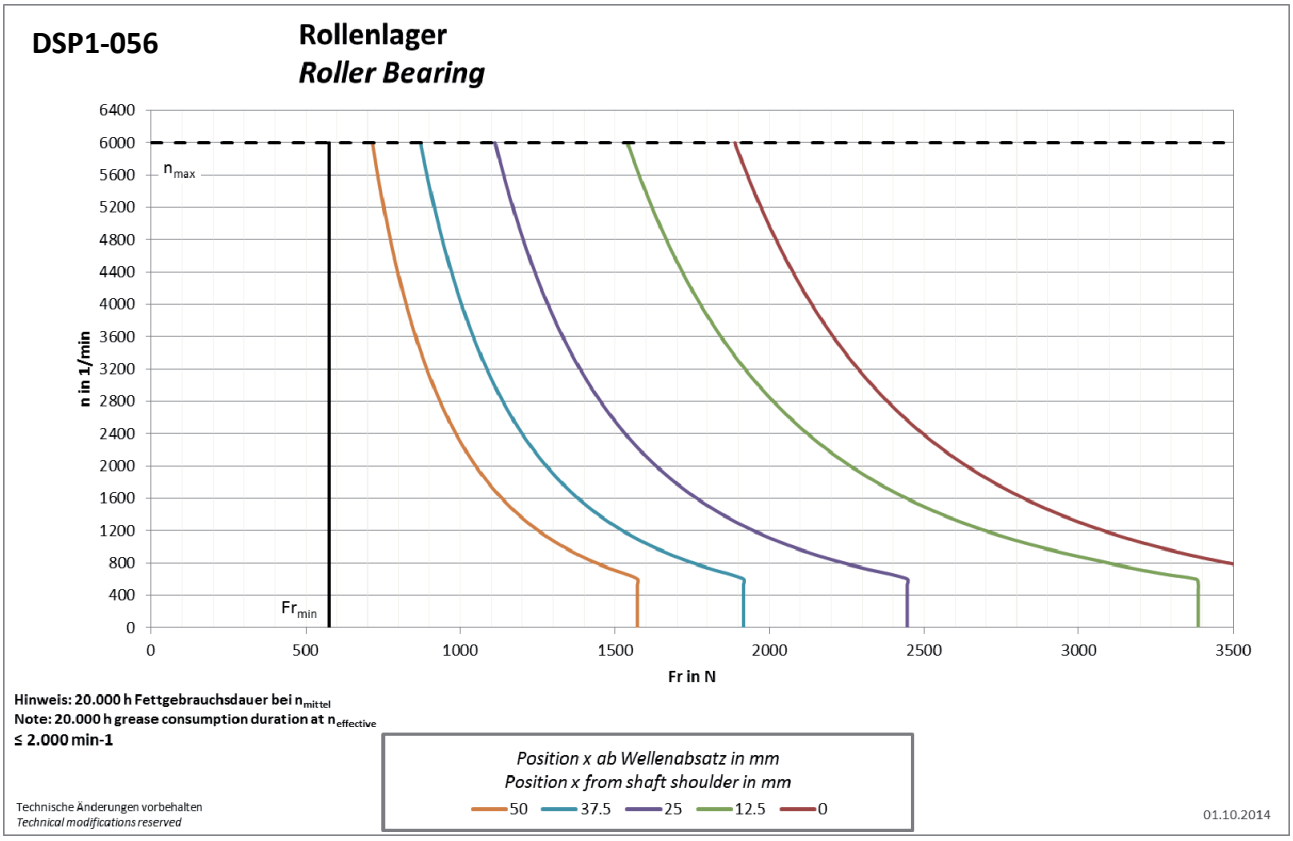
2.5.2. Diagram DSP1-045

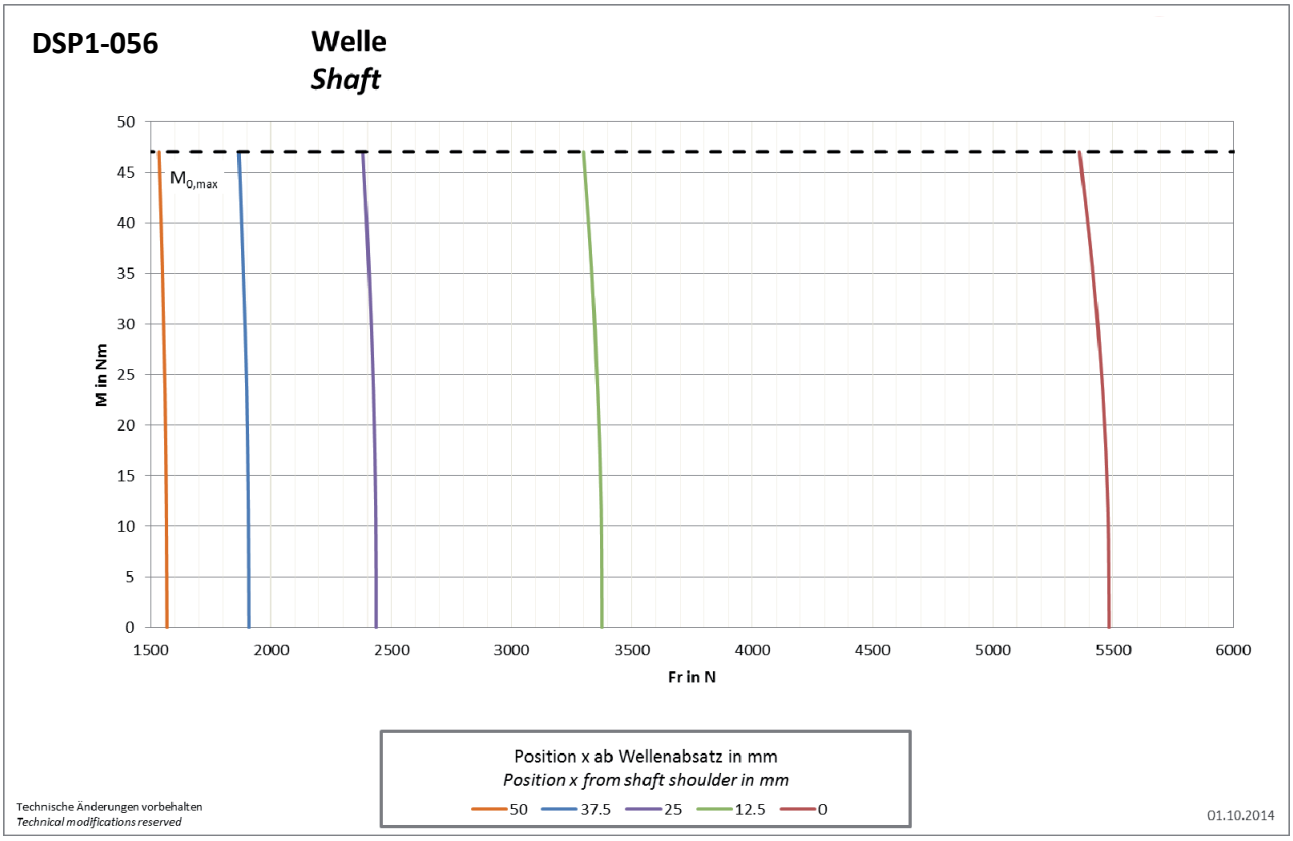




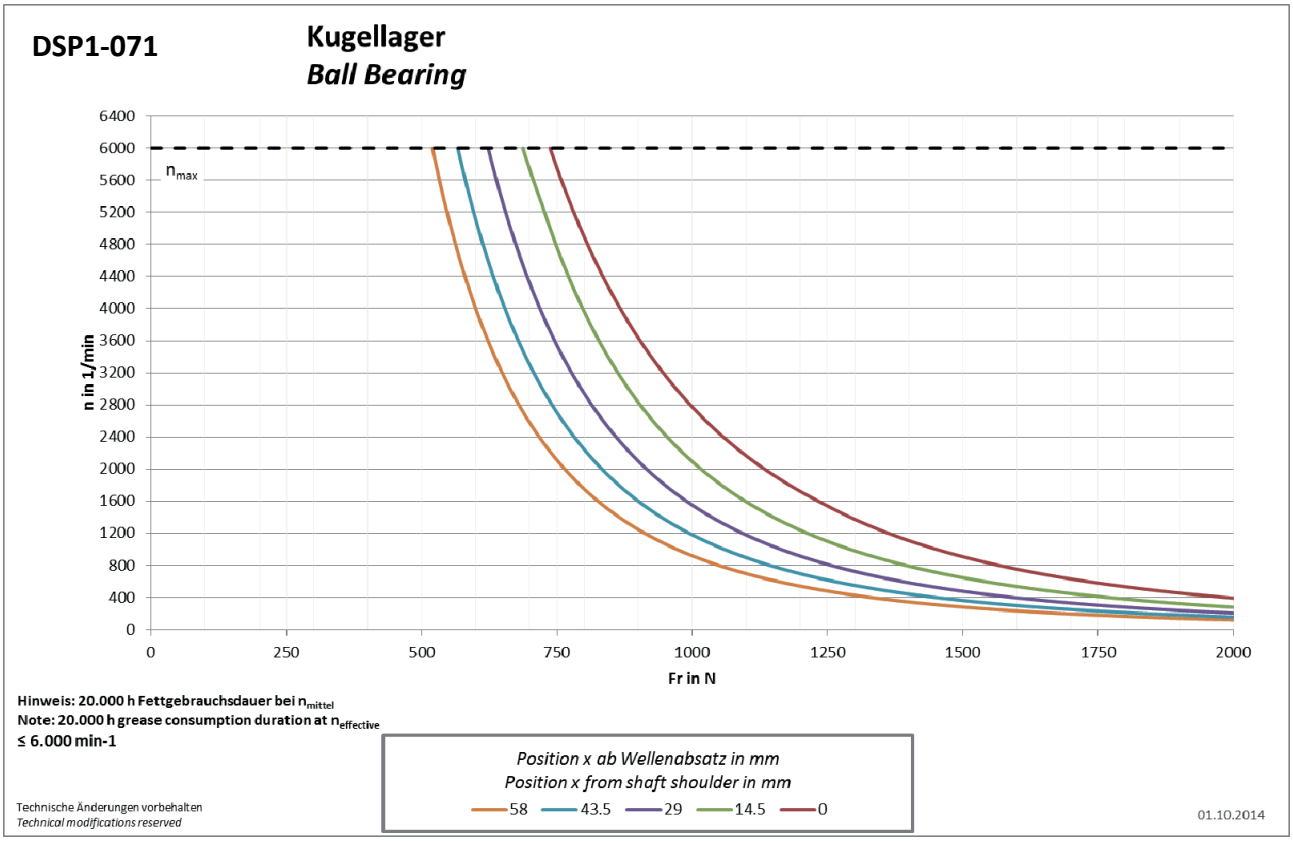
2.5.3. Diagram DSP1-056

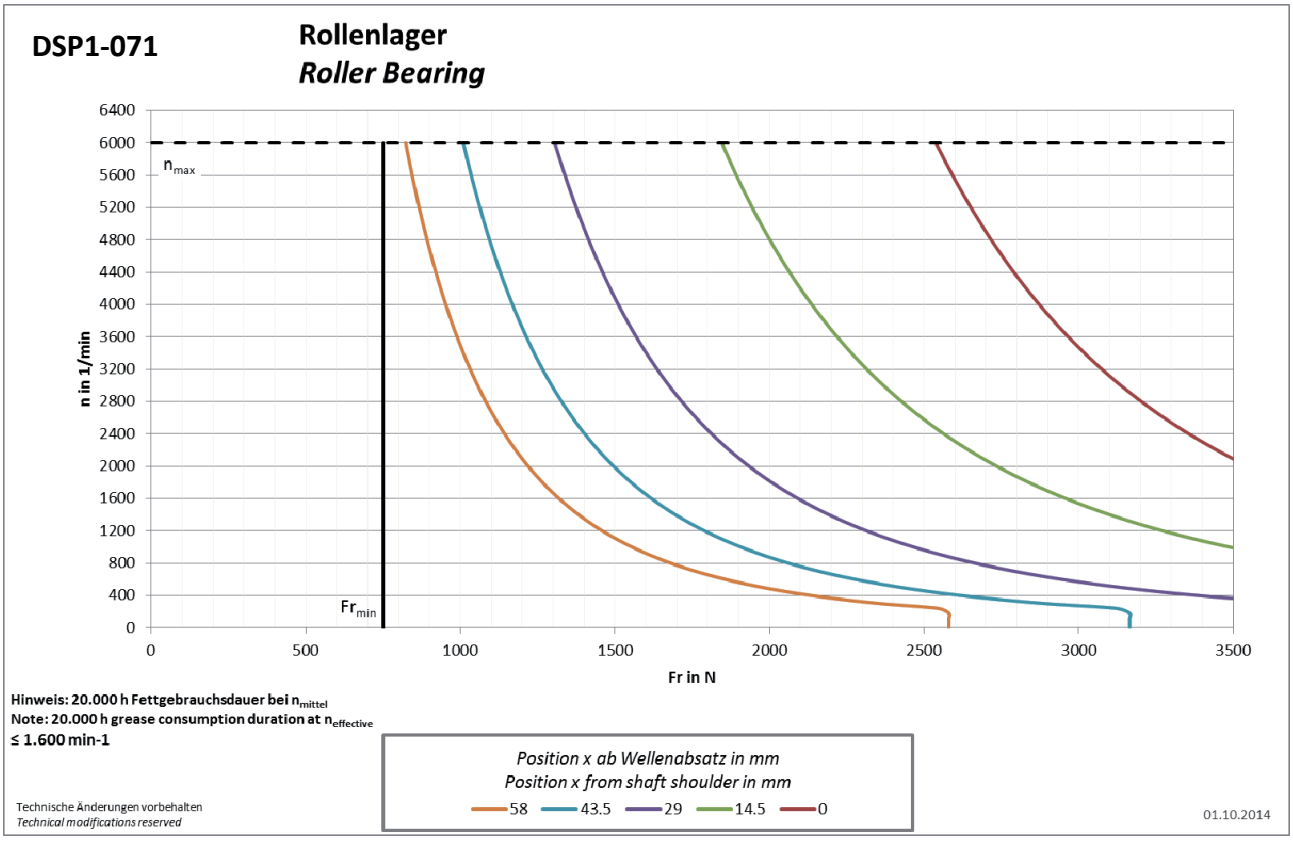


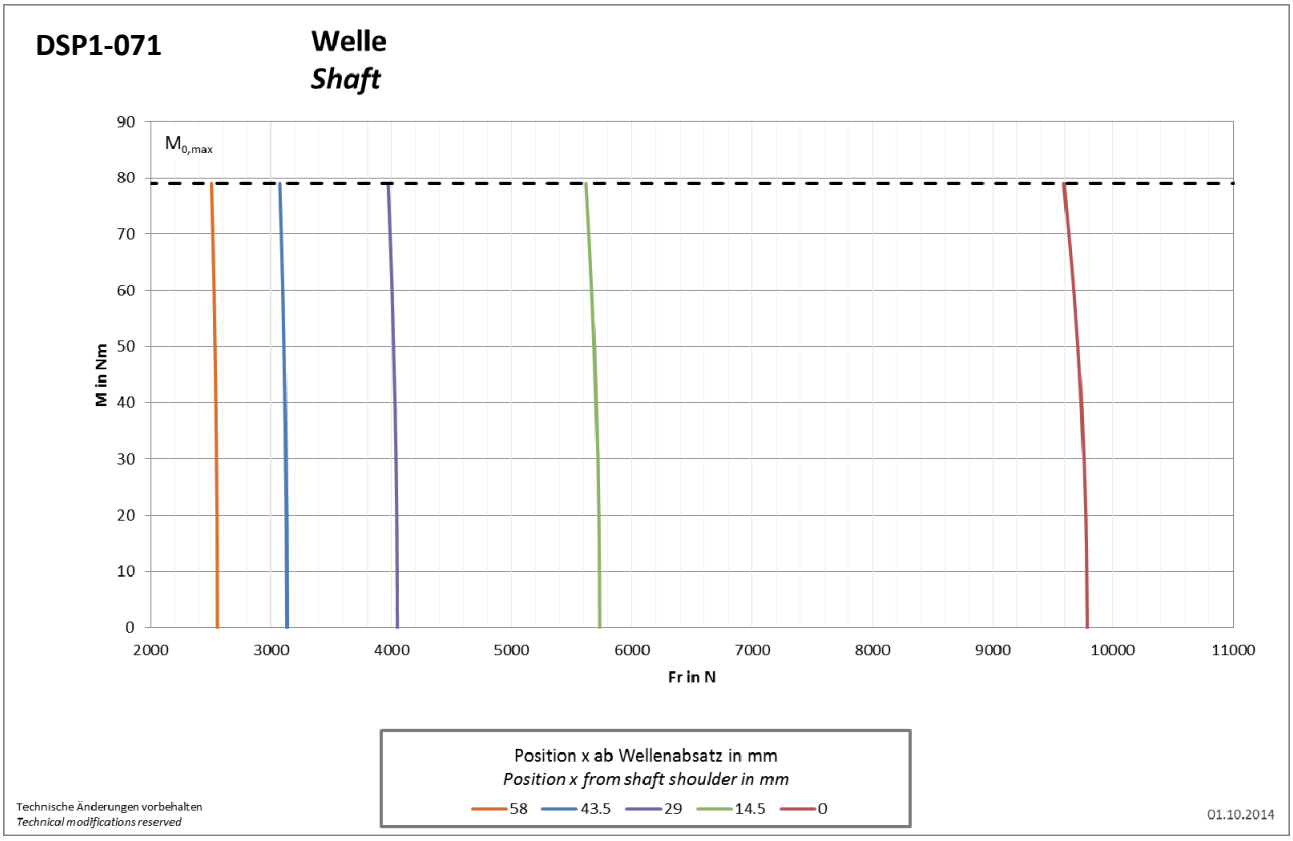



DSP1-056
Welle
Shaft
M0,max
M in Nm
Fr in N
50
45
40
35
30
25
20
15
10
5
0
1500
2000
2500
3000
3500
4000
4500
5000
5500
6000
Position x ab Wellenabsatz in mm
Position x from shaft shoulder in mm
50
37.5
25
12.5
0
Technische Änderungen vorbehalten
Technical modifications reserved
01.10.2014

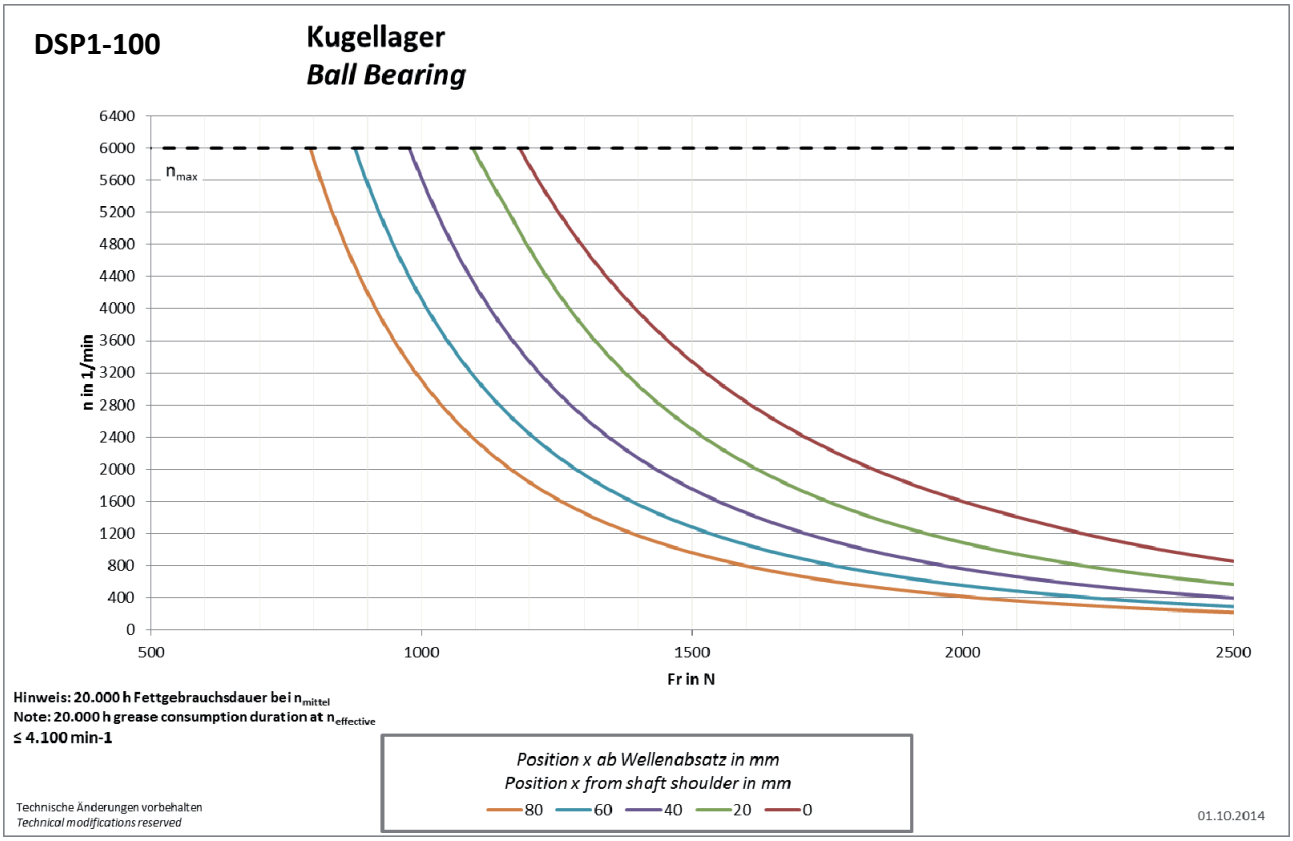
2.5.4. Diagram DSP1-071

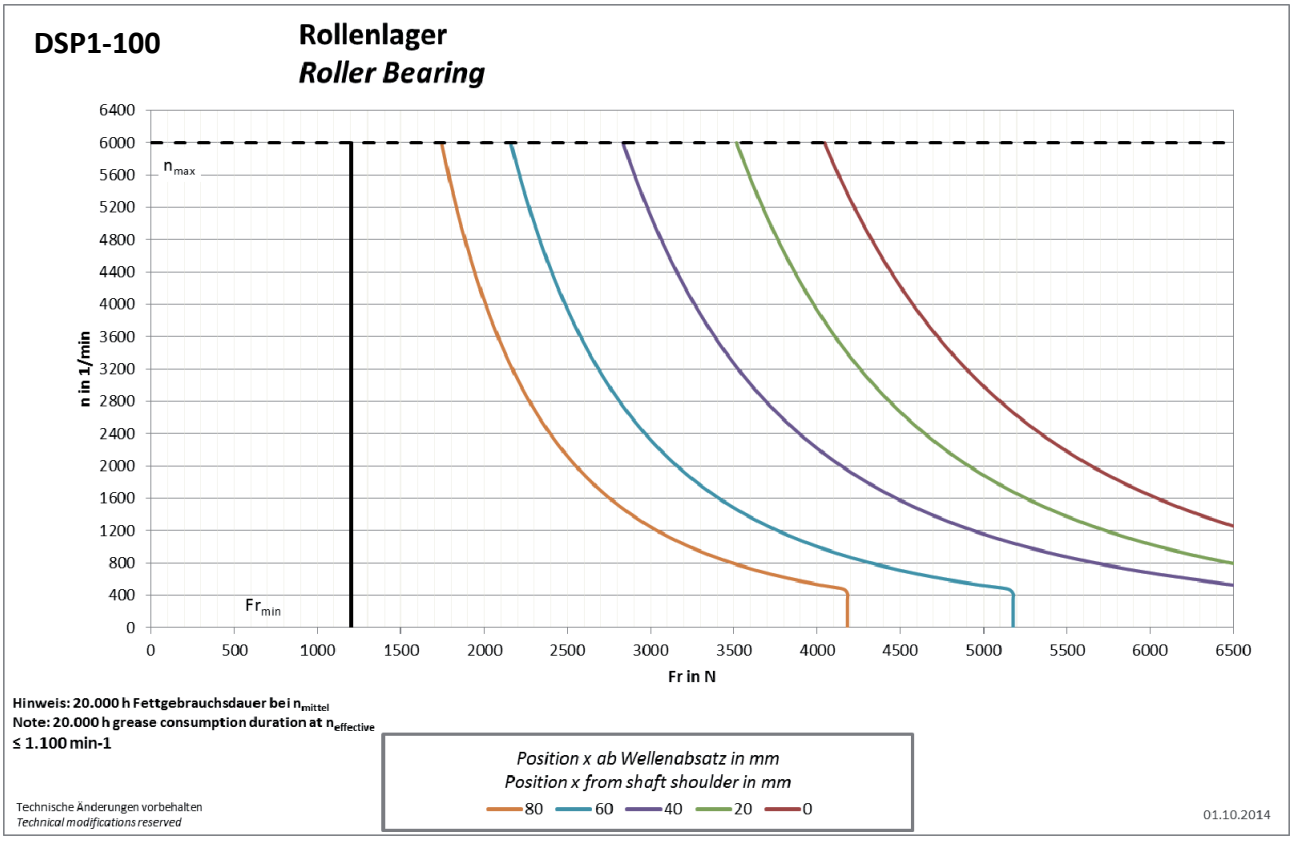


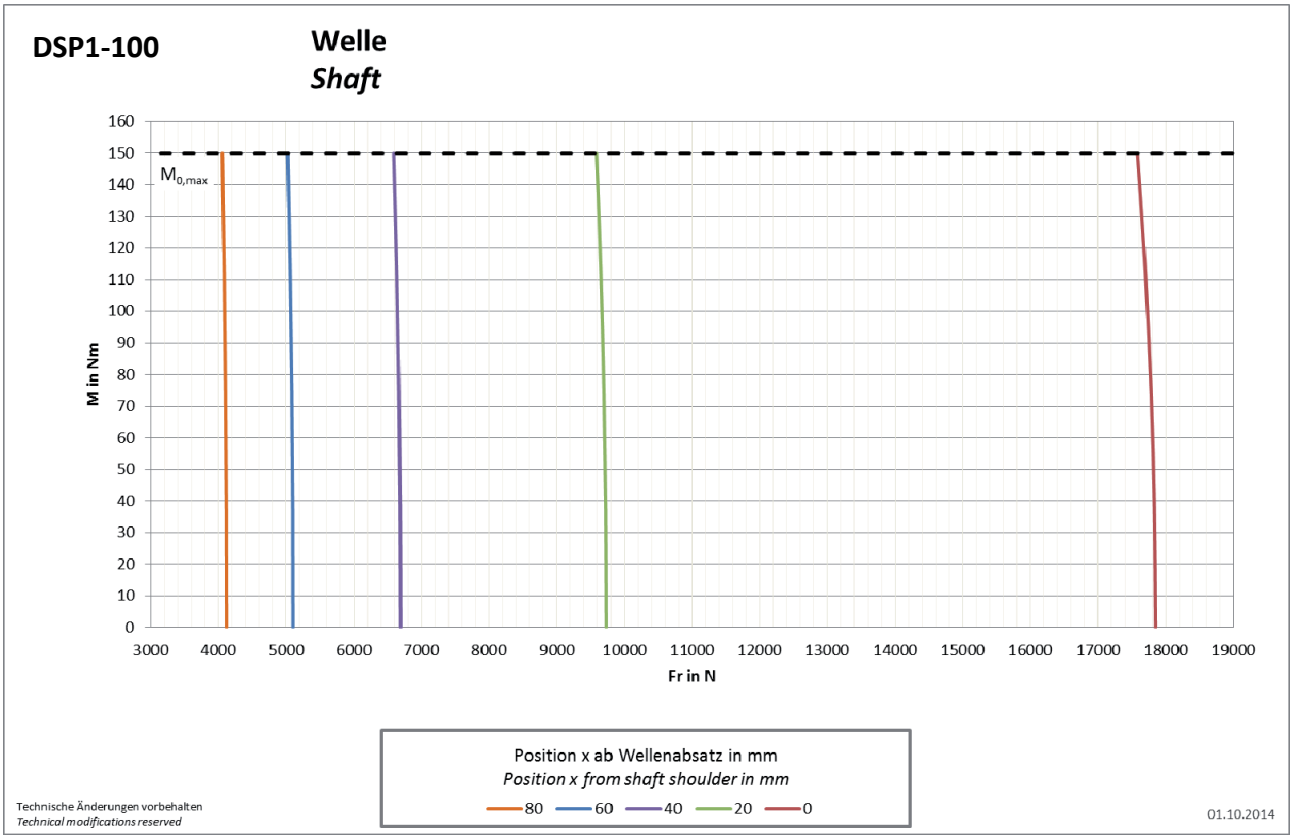



DSP1-071
Welle
Shaft
$M_{0,max}$
M in Nm
Fr in N
90
80
70
60
50
40
30
20
10
0
2000
3000
4000
5000
6000
7000
8000
9000
10000
11000
Position x ab Wellenabsatz in mm
Position x from shaft shoulder in mm
58
43.5
29
14.5
0
Technische Änderungen vorbehalten
Technical modifications reserved
01.10.2014

2.5.5. Diagram DSP1-100






DSP1-100
Welle
Shaft
M0,max
M in Nm
Fr in N
Position x ab Wellenabsatz in mm
Position x from shaft shoulder in mm
80
60
40
20
0
Technische Änderungen vorbehalten
Technical modifications reserved
01.10.2014

3. Motor components (options)

3.1. Holding brake

The motors can be optionally equipped with a holding brake. The holding brake is a backlash-free permanent magnetic brake. The brakes work according to the closed current principle, i.e. the brake is applied when switched off (or at a failure of the operating voltage). The brakes are designed for an operating voltage of 24 VDC. The specifications by the brake manufacturer apply at room temperature.

The motors are available with the following holding brakes:

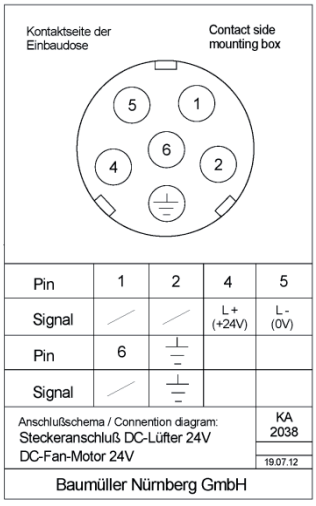
Motor type	DSP1-045	DSP1-056	DSP1-071	DSP1-100
Minimal static holding torque [Nm] at 120 °C.	10	20	45	105
Nominal dynamic holding torque [Nm] at 120 °C.	8	18	25	45
Maximum switching energy [J] per braking from n = 3,000 rpm	270	320	1400	2800
Connection values [V] (+6 % / -10 %)	24	24	24	24
Power consumption [W]	18	20	28	50
Moment of inertia [$kgcm^2$]	0.6	2.9	7.9	17.6
Switching time On [ms] Ventilation; with basic air gap	40	65	100	200
Switching time Off [ms] Braking; with basic air gap	20	30	40	50

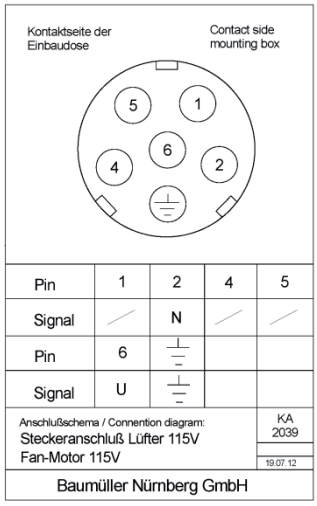
All brakes are not fail safe brakes in the sense that a torque reduction cannot occur due to uninfluenceable malfunction factors. Depending on the application, the relevant accident prevention regulations, as well as basic health and safety requirements of Annex I of the Machinery Directive and the harmonized European standards must be observed.
For emergency stops or power failures, approximately 2,000 brake processes can be performed.
(Condition: maximum external inertia = motor inertia and n_{max} type-related;
Max. braking / hour <20; evenly distributed).

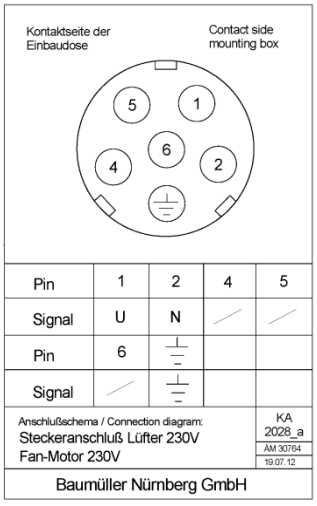
3.2. Fan

	DSP1-056..100			
Rated voltage [V]	24 V DC	115 V AC	230 V AC	
Rated frequency [Hz]	-	60	50	60
Rated current [A]	0,52	0,47	0,22	0,20
Rated speed [rpm]	2758	2394	2385	2099
Power rating [W]	12,4	35	32	30
Connection	6 - pole plug			
Protection type	IP65			

Fan connection 24 V DC / 115 V AC / 230 V AC







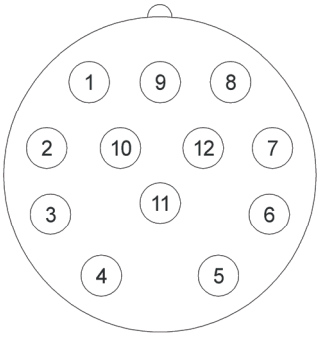
View on the contact side of the receptacle

3.3. Encoder

3.3.1. (Resolver)

Pole pair number	1	4
Transmission ratio	0.5 ± 0.05	0.5 – 0.05
Frequency	5 kHz	8 kHz
Rotor resistance	48 Ω ± 10%	34 Ω ± 10%
Stator resistance	31 Ω ± 15%	188 Ω ± 10%
Rotor impedance at no-load speed	70 + j 74Ω ± 15%	70 + j 125Ω
Rotor impedance with short circuit	62 + j 66Ω ± 15%	68 + j 122Ω
Stator impedance at no-load speed with minimum coupling	108 + j 206Ω ± 15%	433 + j 1381Ω
Stator impedance with short circuit and maximum coupling	97 + j 183Ω ± 15%	422 + j 1345Ω
Phase shift	8° ± 3°	6° ± 3°
Zero voltage	30 mV	30 mV
Angle error in relation to $(\Delta\varphi_{max}+\Delta\varphi_{min})/2$	± 6’	± 6’
Shock according to DIN EN 60068-2-27 (11 ms)	≤ 1000 m/s²	≤ 1000 m/s²
Vibration according to DIN EN 60068-2-6	≤ 500 m/s² (55-2000 Hz)	≤ 500 m/s² (10-500 Hz)

Resolver connection



View on the contact side of the receptacle

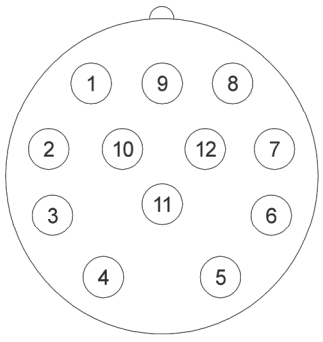
Pin	Signal	Option for allocation PT1000 R1/R2) or KTY (K+/K-) on encoder socket
1	cos -	cos -
2	-	-
3	-	-
4	-	-
5	sin -	sin -
6	sin +	sin +
7	-	K – or R2
8	cos +	cos +
9	-	K + or R1
10	ref +	ref +
11	-	-
12	ref -	ref -

NOTE:
Use only at low demands on the true running characteristics of the motor.
The specifications are information by the encoder manufacturer.

3.3.2. Resolver for safety-related applications

Motor installation size	DSP1-045-100
Pole pair number	1
Transmission ratio	0.5 ± 0.05
Frequency	5 kHz
Safety integrity level	SIL 3 (IEC 61508) in combination with b maXX5000
Performance Level	PL e (EN ISO 13849) in combination with b maxx5000
Maximum angular acceleration	100.000 rad/s²
Effective input power at no-load speed	112 mW
Nominal input voltage	7 V_{rms}
Current consumption at no-load speed	70 mA
Max. output voltage at no-load speed	3.5 V ± 10%
Voltage constant	61 mV/°
Rotor resistance	48 Ω ± 10%
Stator resistance	31 Ω ± 15%
Rotor impedance at no-load speed	70 + j 74Ω ± 15%
Rotor impedance with short circuit	62 + j 66Ω ± 15%
Stator impedance at no-load speed with minimum coupling	108 + j 206Ω ± 15%
Stator impedance with short circuit and maximum coupling	97 + j 183Ω ± 15%
Phase shift	8° ± 3°
Zero voltage	30 mV
Angle error related to $(\Delta\varphi_{max}+\Delta\varphi_{min})/2$	± 6’
Shock according to DIN EN 60068-2-27 (11 ms)	≤ 1000 m/s²
Vibration according to DIN EN 60068-2-6	≤ 500 m/s² (55-2000 Hz)

Resolver connection



Pin	Signal	Option for allocation PT1000 (R1/R2) or KTY (K+/K-) at encoder socket
1	cos -	cos -
2	-	-
3	-	-
4	-	-
5	sin -	sin -
6	sin +	sin +
7	-	K - or R2
8	cos +	cos +
9	-	K + or R1
10	ref +	ref +
11	-	-
12	ref -	ref -

View of the contact side of the receptacle

NOTE:
Use only at low demands on the true running characteristics of the motor.
The technical data is the specifications of the encoder manufacturer.
The configuration options for the safety encoders with different engine versions can be found in the product configurator.

3.4. Encoder cables for b maXX 4000

General Information
A prefabricated encoder cable is used for all encoder systems. The connection at the motor end consists of a 12-pole circular signal connector. The connection at the controller side consists of a 15-pole D-Sub connector.

The dragable cable is suitable for mobile applications such as drag chains, for example. Unlike non-dragable cables made from PVC, the cable sheath is made from durable PU (suitable for environments where acids and bases are present).

3.4.1. Technical data

Technical description - non-dragable
- LiYCY, 5x (2x0.14mm²) + 2 x 0.5mm² copper strand, twisted pairs
- PVC sheath, grey; inscription with Baumüller logo, black
- 1st side: 12-pole circular signal plug connector with 12 socket contacts
- 2nd side: 15-pole D-Sub plug connector with pin contacts and locking screws 4-40UNC
- Outer diameter 9.0 mm (+/- 0.3mm)
- Bending radius: $r \geq 60$ mm (fixed routing), $r \geq 135$ mm (flexible use)
- Nominal voltage: $250V_{AC}$

Technical description - dragable
- Li12YC11Y, 5x (2x0.14mm²) + 2 x 0.5mm² copper strand, twisted pairs
- PU sheath, black; inscription with Baumüller logo, white
- 1st side: 12-pole circular signal plug connector with 12 socket contacts
- 2nd side: 15-pole D-Sub plug connector with pin contacts and locking screws 4-40UNC
- Outer diameter 9.0 mm (+/- 0.3mm)
- Bending radius: $r \geq 70$ mm (fixed routing), $r \geq 100$ mm (flexible use)
- Nominal voltage: $300V_{AC}$

3.4.2. Application references

- **Operating temperature of encoder cable**

	Dragable	Not dragable
Limit temperature	on the surface	on the surface
Static use/minimal movement	- 40 °C to + 80 °C	- 30 °C to + 80 °C
Permanent movement	- 30 °C to + 80 °C	- 5 °C to + 70 °C

Routing of cable on motor

The cables must not touch the surface of the motor.

3.4.3. Order information for encoder cables

Encoder cables for resolver - prefabricated cables with connector

Not dragable, prefabricated
Cable 5 x (2x0.14mm^2) + 2 x 0.5 mm^2 with plug connector

Length in [m]	Item Number
1	243601
2	211338
3	219333
4	231166
5	209879
6	220197
7	216455
8	220429
10	210052
15	215716
20	218568
25	218569
30	217094
35	216444
40	217095
45	217567
50	217568
55	217569
60	217570
70	232088

Dragable, prefabricated
Cable 5 x (2x0.14mm^2) + 2 x 0.5 mm^2 with plug connector

Length in [m]	Item Number	Item Number (Speed Tec)
3	246658	448944
4	243379	448945
5	239540	448948
6	242954	448946
8	239541	448949
10	239542	448956
15	239543	448962
20	239544	448967
25	239545	448970
30	239546	448971
35	239547	448973
40	240520	448976
45	240521	448978
50	240522	448980
55	244033	448981
60	245484	448982

3.5. Encoder cables for b maXX 5000

A prefabricated encoder cable is used for all encoder systems. The connection at the motor end consists of a 12-pole circular signal. The connection at the controller side consists of a 26-pole D-Sub connector.

3.5.1. Technical data

Technical description - dragable

- Li9YC, 1 x (2 x 0,25) + Li9Y, 2 x (2x0,25) + Li9YC11Y, 1 x (2 x 0,34), copper strand, twisted pairs
- PUR sheat, green; inscription with Baumüller Nürnberg and encoder cable Resolver
- 1st side: 12-pole circular signal plug connector with 12 socket contacts
- 2nd side: 26-pole D-Sub plug connector with pin contacts and locking screws 4-40UNC
- Outer diameter 7.3 mm (+/- 0.3mm)
- Bending radius: $r \geq 4 \times D$ (fixed routing), $r \geq 10 \times D$ (flexible use)

Application references

Operating temperature of encoder cable

Limit temperature	on the surface
Static use/minimal movement	- 40 °C to + 80 °C
Permanent movement	- 20 °C to + 60 °C

Routing of cable on motor

The cables must not touch the surface of the motor.

3.5.2. Order information for encoder cables

Encoder cable - prefabricated

For Resolver

Length [m]	Item Number	Item Number. (Speed Tec)
1	429914	448746
2	429915	448747
3	429916	448748
5	429917	448749
7	429918	448750
10	429919	448751
15	429920	448752
20	429921	448753
25	429922	448754
30	429923	448755
35	429924	448756
40	429925	448757
50	429926	448758
75	429927	448759

3.6. Motor cables

The motor cables are highly flexible trailing cables with overall shielding. They comply with VDE, UL and CSA regulations. The control cables are integrated as star quads. The brake control and the temperature sensor are connected via the main connector. The cables are particularly suited for the optimum use of cable racks thanks to their small cross-section, low weight, and non-impeding surface. As a result, they can be used efficiently in trailing chains. The overall shielding with an optical coverage of more than 85% makes the cable non-critical from an EMC perspective.

3.6.1. Technical data

- Sheath resistance to media such as coolants and machine and gearbox oils
- Abrasion resistance thanks to a special surface in cable racks and trailing chains
- Highly flexible trailing cable, minimum bending radius for flexible use: 12 x D
- Non-blocking sheath surface with satin finish
- Shield made of tinned copper braid with optical coverage of ≥ 85%
- Core insulation made from TPE or polyester, sheath material: Halogen-free PUR
- Cable is CFC and silicone-free
- Behavior in the event of fire: Fire-inhibiting, halogen-free
- Cable color RAL 1028, melon yellow
- Label features Baumüller logo and VDE, UL and CSA marks

Rated voltage
- Uo/U 600/1.000 V (power cores)
- U 24 V DC (control cores)

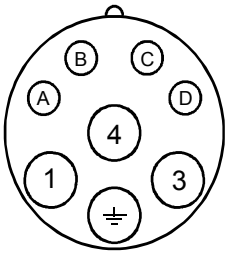
Core labeling
- Power cores U, VV, WWW
- Colored control cable pairs as star quads in red, white, black, yellow

Assignment of pairs: (note the polarity)
- Red – black (brake)
- white – yellow (temperature)

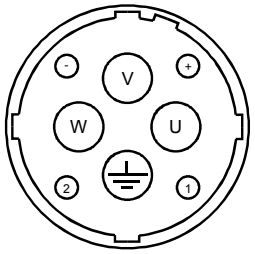
3.6.2. Main connection via connector

Note:
The connector size is determined by the standstill current I_0 of the motor used.
Motors with a standstill current of ≤ 20A feature a size 1 main connector.
For standstill currents of 20 A< I_0 ≤ 36 A, a size 1.5 main connector is used.
A terminal box must be used at a I_0 > 36A.

Poles of the female main connectors:

		Pin	Signal	Color/labeling
Size 1 $I_0 \leq 20$ A		1	Phase U	U
		⏚	PE	Green/yellow
		3	Phase V	V V
		4	Phase W	W W W
		A	B+	Red
		B	B-	Black
		C	K+	White
		D	K-	Yellow

View of contact side of female connector

		Pin	Signal	Color/labeling
Size 1.5 $I_0 \leq 36$ A		U	Phase U	U
		V	Phase V	V V
		W	Phase W	W W W
		⏚	PE	green / yellow
		+	B+	Red
		-	B-	Black
		1	K-	White
		2	K+	Yellow

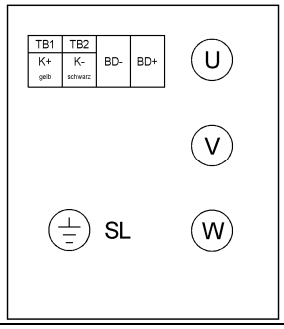
View of contact side of female connector

Cable cross-section [2]	**Rated current [A]** [1) 2)]	**Connector 540 V Size** [2]	**Cable diameter** [2] **[mm]**
4×1.5 mm² + 4×0.75 mm²	15	1	11.7 – 12.3
4×2.5 mm² + 4×0.75 mm²	20	1	12.7 – 14.6
4×4 mm² + 4×0.75 mm²	28	1.5	14.2 – 15.4
4×6 mm² + 4×0.75 mm²	36	1.5	16.6 – 17.9
4x10 mm² + 4x0.75 mm²	50	1.5	20.5 – 21.5
4x16 mm² + 4x0.75 mm²	66	-	23.0-25.8
4x25 mm² + 2x(2x1.5 mm²)	84	-	26.3-29.7
4x35 mm² + 2x(2x1.5 mm²)	104	-	30.8-32.5

1) Current carrying capacity acc, to Table 5, laying type C or E VDE 0113/EN 60204 Part 1 issue 1997) Ambient temperature 40 °C

2) Deviating regulations apply for cULus approved motors

3.6.3. Main connection via terminal boxes



Connection diagram

U V W	Power connection
K+ / K-	Temperature sensor
BD+ / BD-	Brake
SL	Earth wire

3.6.4. Application notes

Operating temperature
The cables can be operated within a temperature range of between -20 °C and +80 °C

Cable laying at the motor
The cables must not touch the motor surface

Smallest permissible bending radii
12x outer cable diameter

3.6.5. Ordering data for main connection cables

Rated current: 15 A
Cable 4 x 1.5 mm² + 4 x 0.75 mm²
With connector size 1

Length in m	Item Number Speed Tec
5	445872
7	445887
10	445889
15	447675
20	447676
25	447677
30	447678
35	447679
40	447680
50	447681
75	447682
100	447683

Rated current: 20 A
Cable 4 x 2.5 mm² + 4x 0.75 mm²
With connector size 1

Length in m	Item Number Speed Tec
5	447684
7	447687
10	447688
15	447692
20	447698
25	447852
30	447853
35	447854
40	447855
50	447856
75	447857
100	447858

Rated current: 21 A
Cable 4 x 2.5 mm² + 4x 0.75 mm²
With connector size 1.5

Length in m	Item Number Speed Tec
5	447686
7	447689
10	447690
15	447691
20	447693
25	447694
30	447695
35	447696
40	447697
50	447699
75	448060
100	448061

Rated current: 28 A
Cable 4 x 4 mm² + 4x 0.75 mm²
With connector size 1.5

Length in m	Item Number Speed Tec
5	448063
7	448064
10	448065
15	448066
20	448067
25	448069
30	448070
35	448071
40	448072

Rated current 36 A
Cable 4 x 6 mm² + 4x 0.75 mm²
With connector size 1.5

Length in m	Item Number Speed Tec
5	448080
7	448118
10	448119
15	448120
20	448121
25	448122
30	448123
35	448124
40	448125

Rated current: 50 A
Cable 4 x 10 mm² + 4x 0.75 mm²
With connector size 1.5

Length in m	Item Number Speed Tec
5	448129
7	448131
10	448132
15	448133
20	448134
25	448135
30	448136
35	448137
40	448138

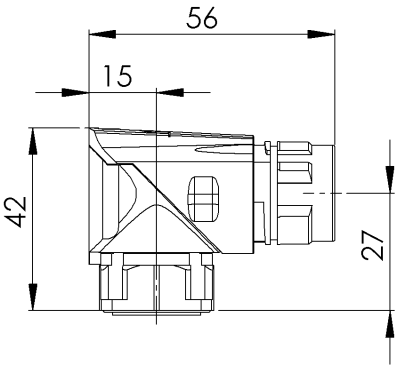
Mating plug:

Type	Item Number Speed Tec
Gr. 1 f. 4x1.5mm^2 o. x2.5mm^2	445486
Gr. 1.5 f. 4x2.5mm^2 bis 4x6mm^2	445487
Gr. 1.5 f. 4x10mm^2	445488

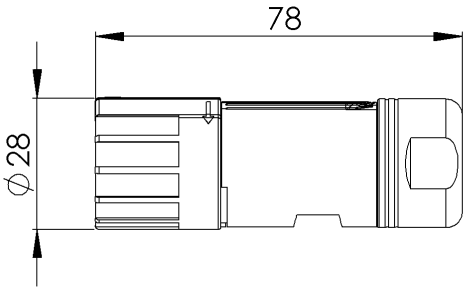
3.7. Dimensional drawings for equipment socket and plug

3.7.1. Main connection:

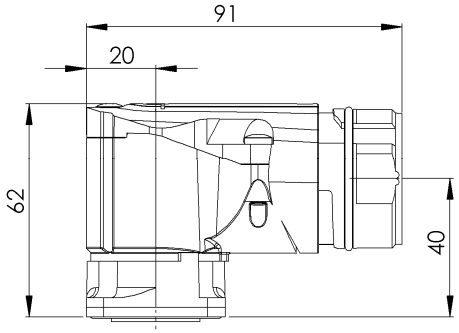
Speed-Tec - rotary angle socket
(Size 1 for Current I_0 up to 20 A)



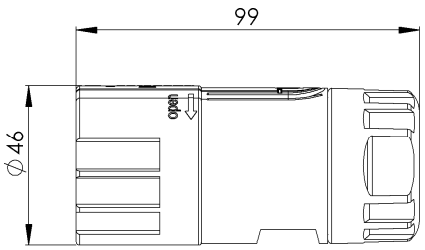
Speed-Tec - mating connector
(Size 1 for Current I_0 up to 20 A)



Speed-Tec - rotary angle socket
(Size 1.5 for Current I_0 up to 36 A)

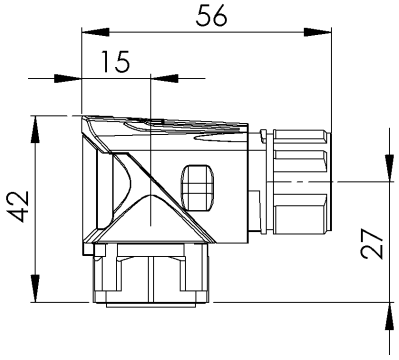


Speed-Tec - mating connector
(Size 1.5 for Current I_0 up to 36 A)

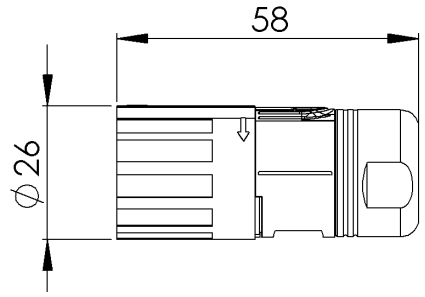


3.7.2. Encoder connection

Speed-Tec - rotary angle socket

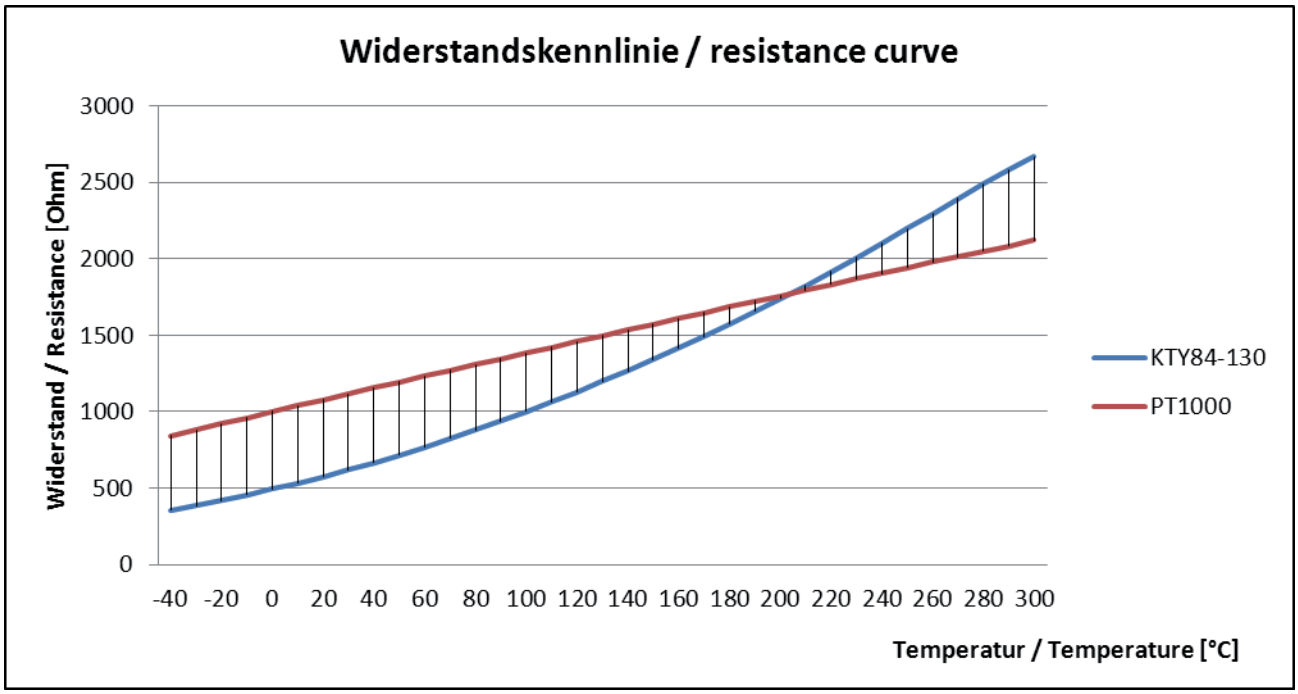


Speed-Tec - mating connector



3.8. Thermal sensor

As standard, the motors are equipped with a thermal sensor in the stator winding, the data of which is evaluated in the motor controller. Additional PTCs or thermal sensors can be fitted on request. They are connected through the terminal box.

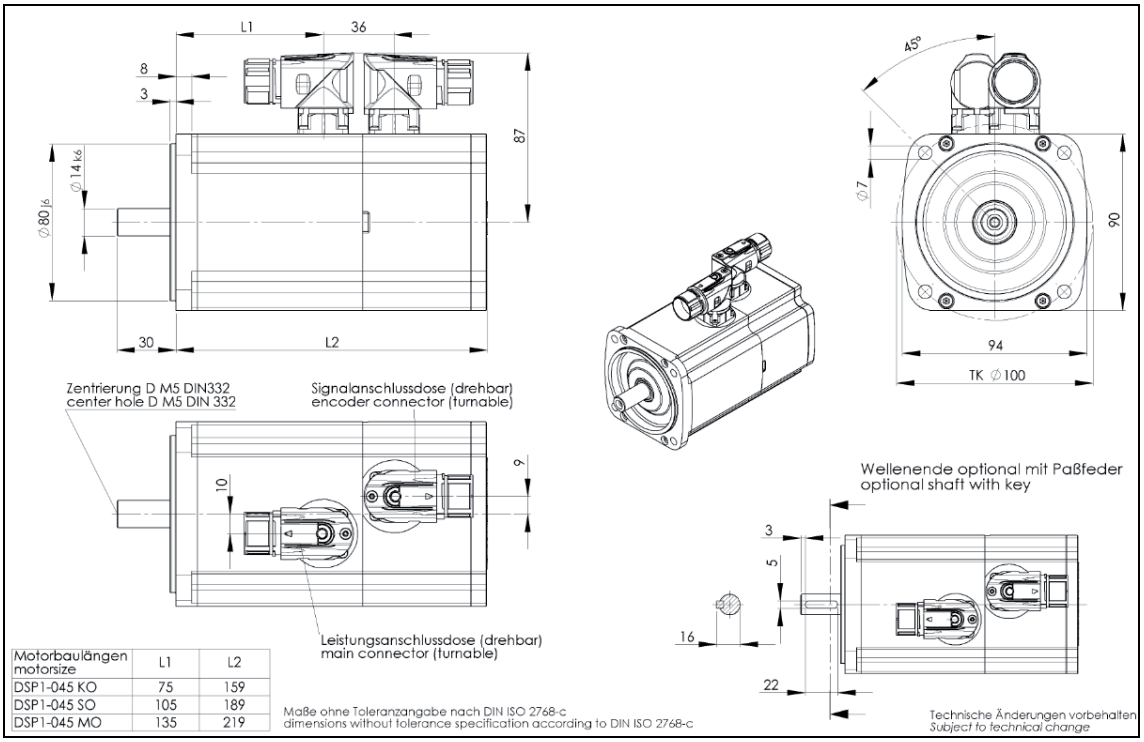


The temperature sensor KTY84-130 continuously monitors the motor temperature. If the sensor is supplied with a measured current of 2 mA the above shown resistance curve results.

4. Dimension drawings

4.1. Dimension drawings DSP1-045

Dimension drawing DSP1-045….U-..-..-.O.-SPP-.-..-O-000
Version IM B5

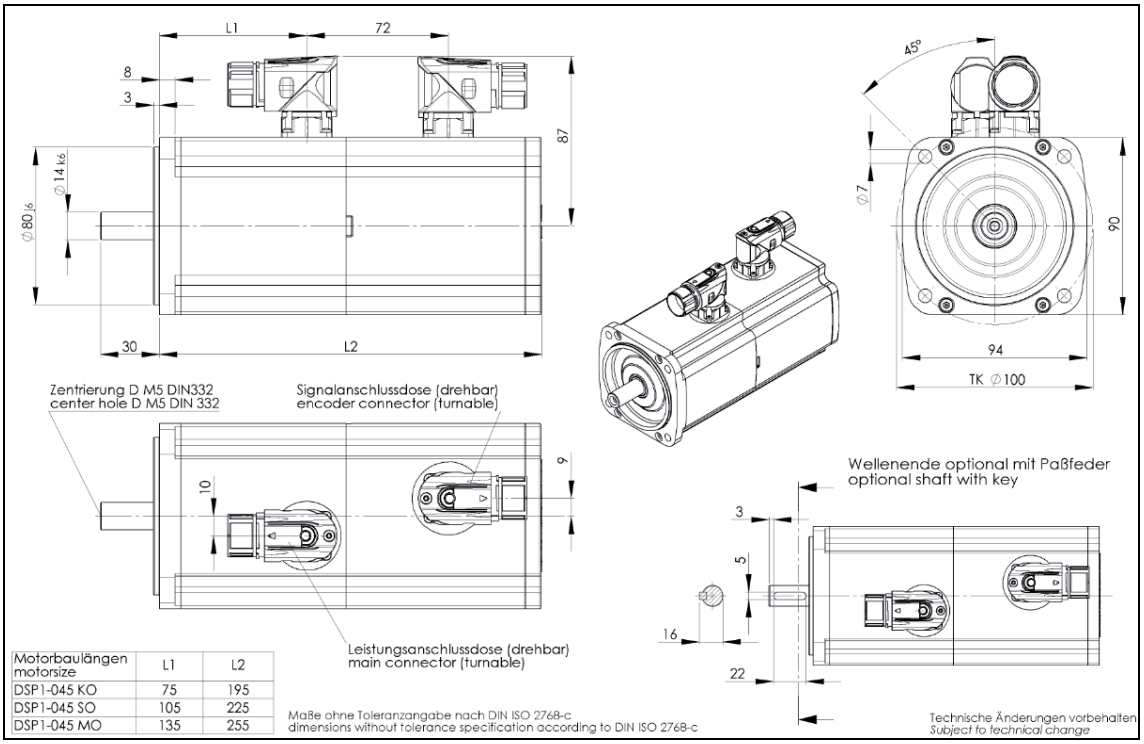


Motorbaulängen motorsize	L1	L2
DSP1-045 KO	75	159
DSP1-045 SO	105	189
DSP1-045 MO	135	219

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-045….U-..-..-.B.-SPP-.-..-O-000
Version IM B5



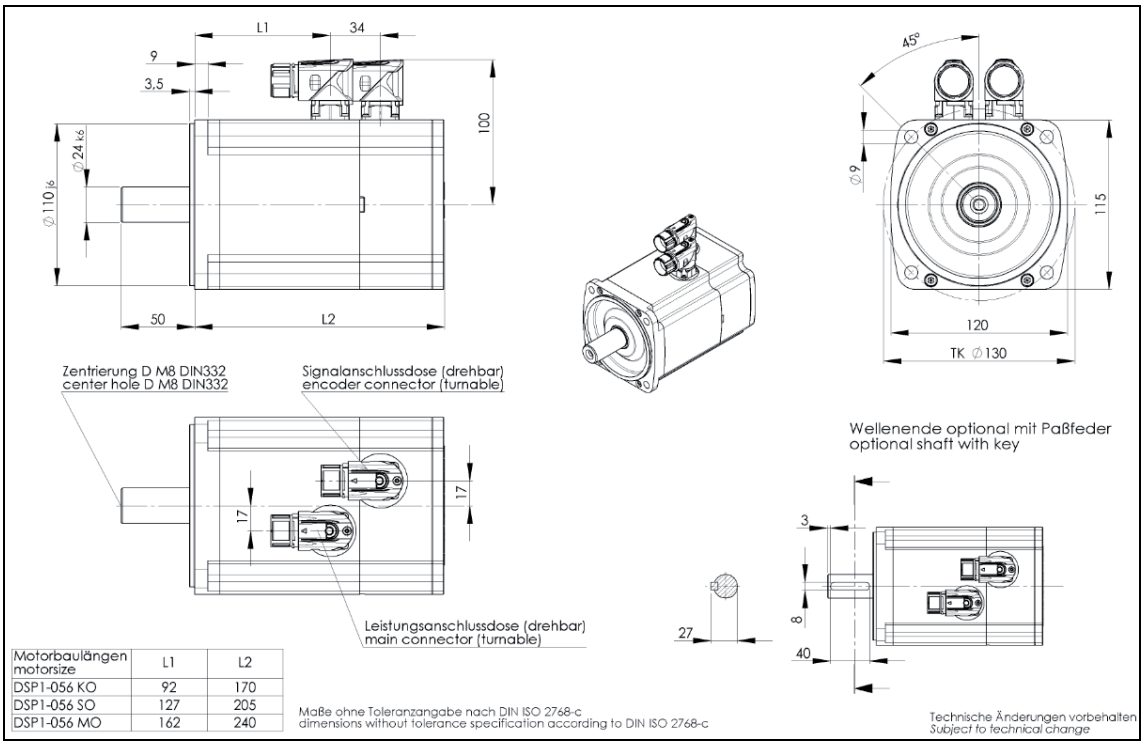
Motorbaulängen motorsize	L1	L2
DSP1-045 KO	75	195
DSP1-045 SO	105	225
DSP1-045 MO	135	255

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

4.2. Dimension drawings DSP1-056

Dimension drawing DSP1-056….U-..-..-.O.-SPP-.-..-O-000
Version IM B5

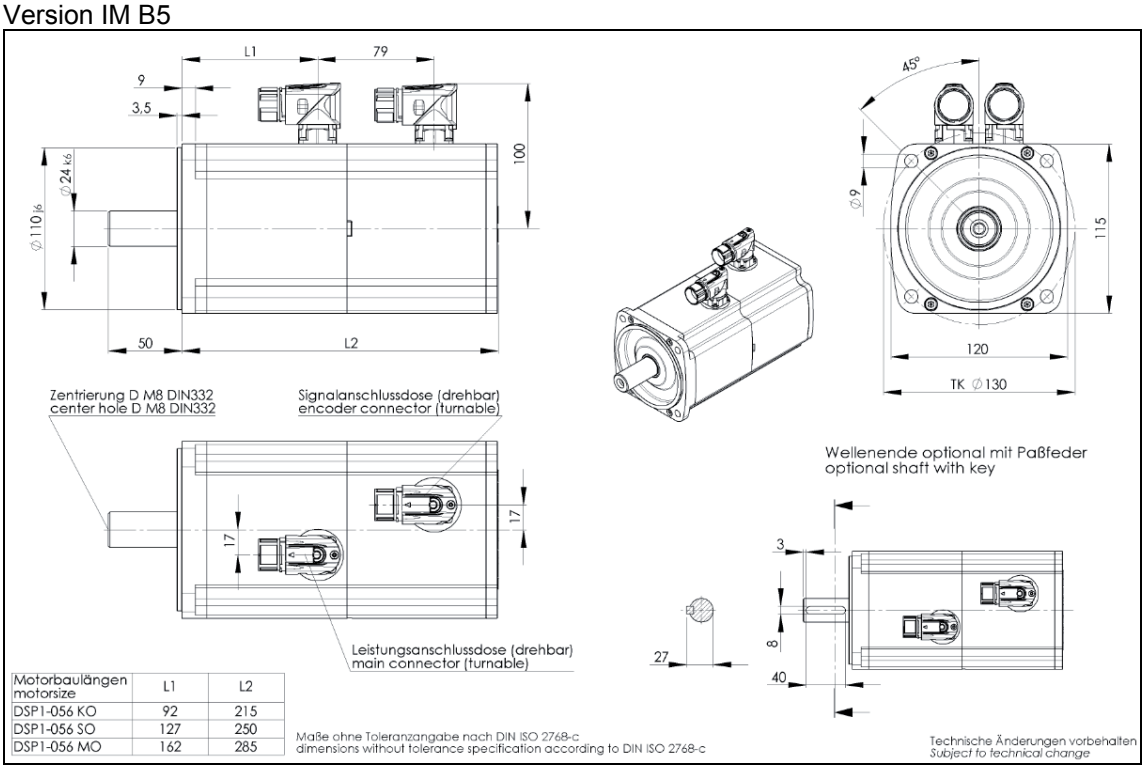


Motorbaulängen motorsize	L1	L2
DSP1-056 KO	92	170
DSP1-056 SO	127	205
DSP1-056 MO	162	240

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-056….U-..-..-.B.-SPP-.-..-O-000
Version IM B5

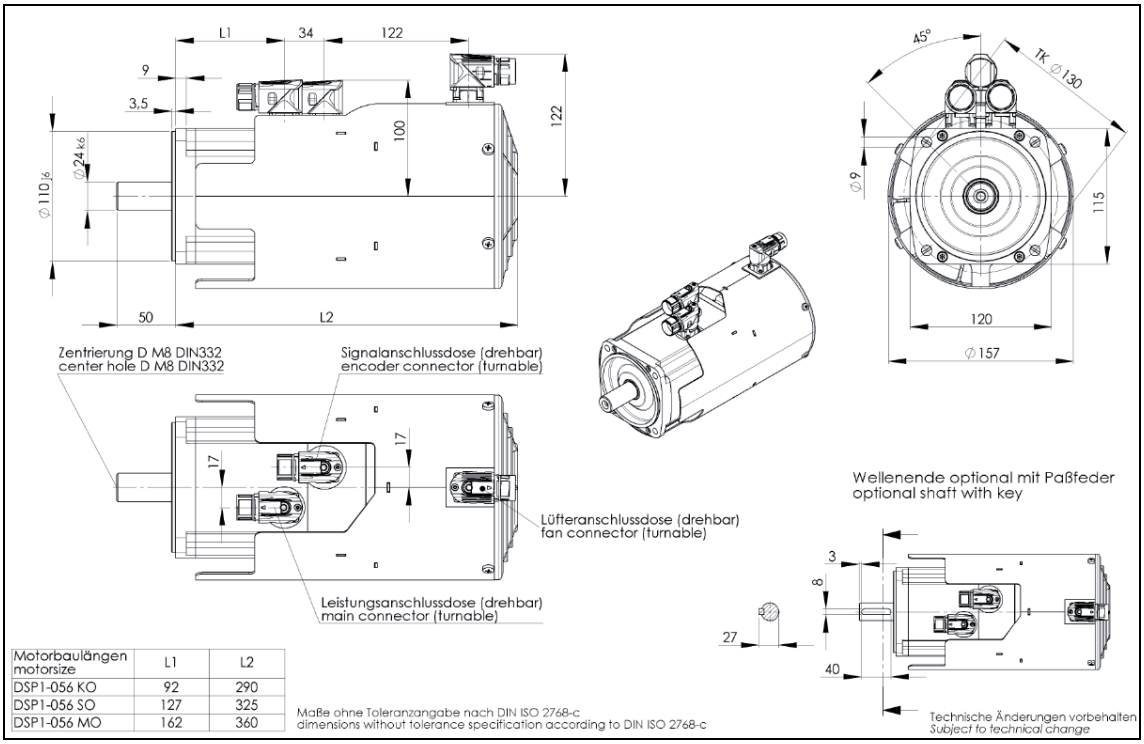


Motorbaulängen motorsize	L1	L2
DSP1-056 KO	92	215
DSP1-056 SO	127	250
DSP1-056 MO	162	285

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

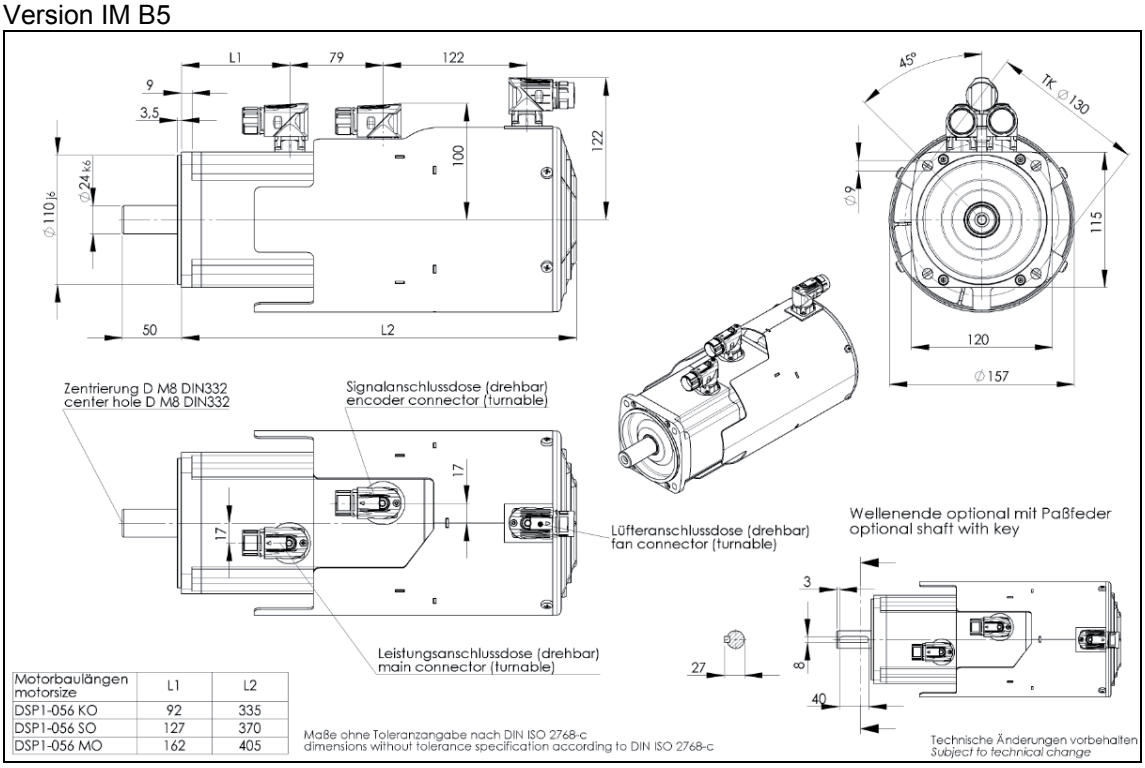
Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-056….O-..-..-.O.-SPP-.-..-O-000
Version IM B5



Motorbaulängen motorsize	L1	L2
DSP1-056 KO	92	290
DSP1-056 SO	127	325
DSP1-056 MO	162	360

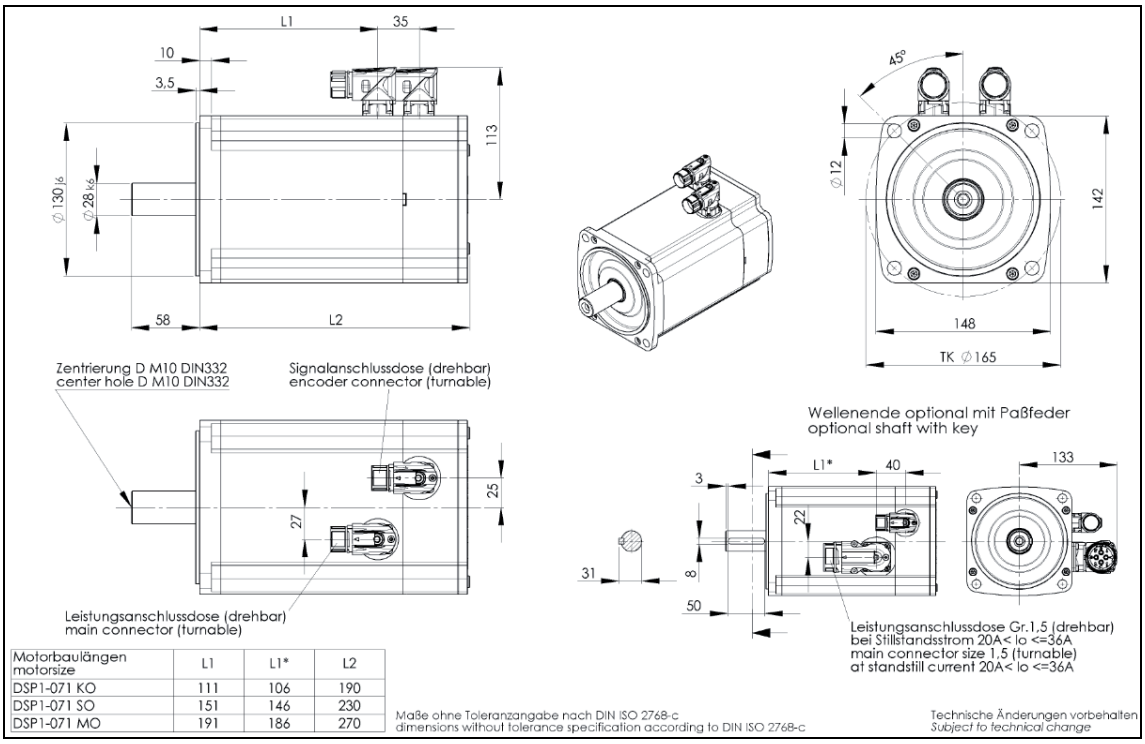
Dimension drawing DSP1-056….O-..-..-.B.-SPP-.-..-O-000
Version IM B5



Motorbaulängen motorsize	L1	L2
DSP1-056 KO	92	335
DSP1-056 SO	127	370
DSP1-056 MO	162	405

4.3. Dimension drawings DSP1-071

Dimension drawing DSP1-071….U-..-..-.O.-SPP-.-..-O-000
Version IM B5

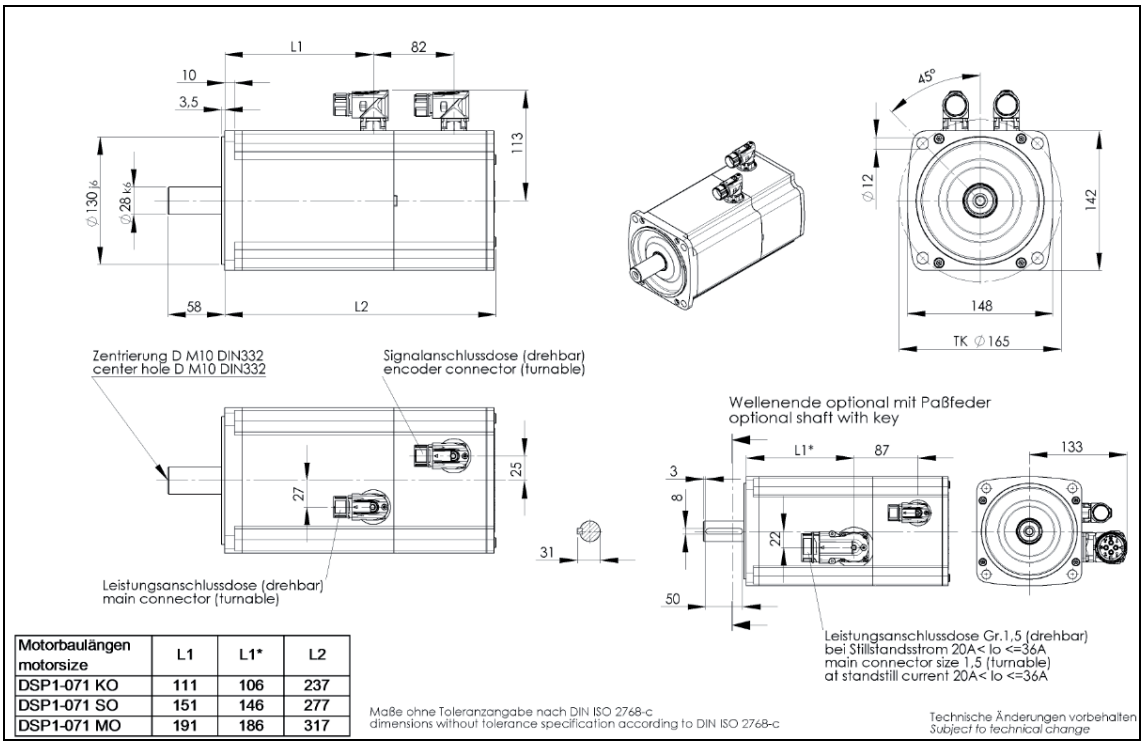


Motorbaulängen motorsize	L1	L1*	L2
DSP1-071 KO	111	106	190
DSP1-071 SO	151	146	230
DSP1-071 MO	191	186	270

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-071….U-..-..-.B.-SPP-.-..-O-000
Version IM B5

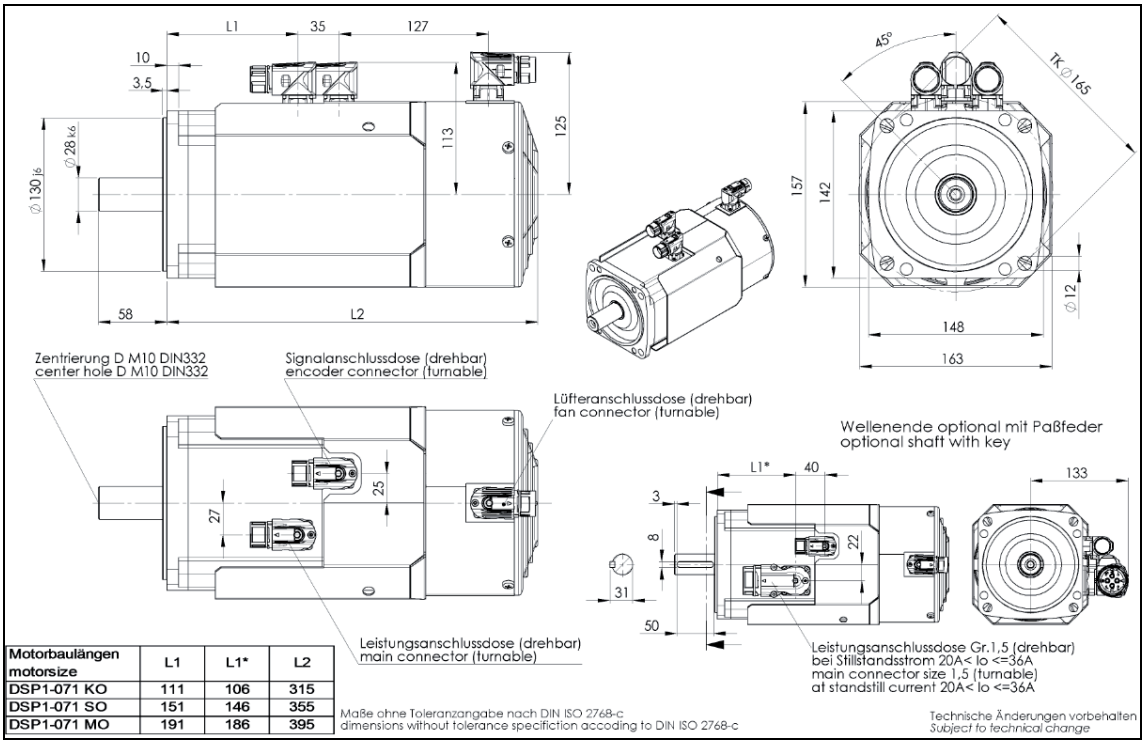


Motorbaulängen motorsize	L1	L1*	L2
DSP1-071 KO	111	106	237
DSP1-071 SO	151	146	277
DSP1-071 MO	191	186	317

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

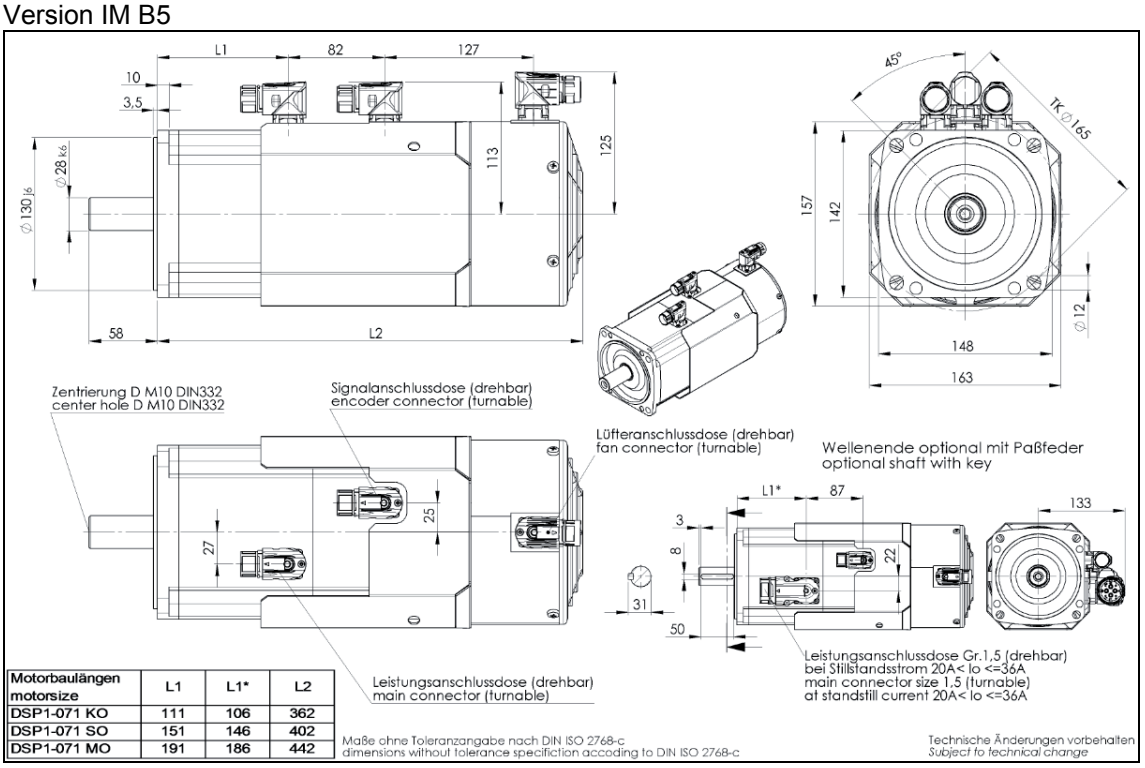
Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-071….O-..-..-.O.-SPP-.-..-O-000
Version IM B5



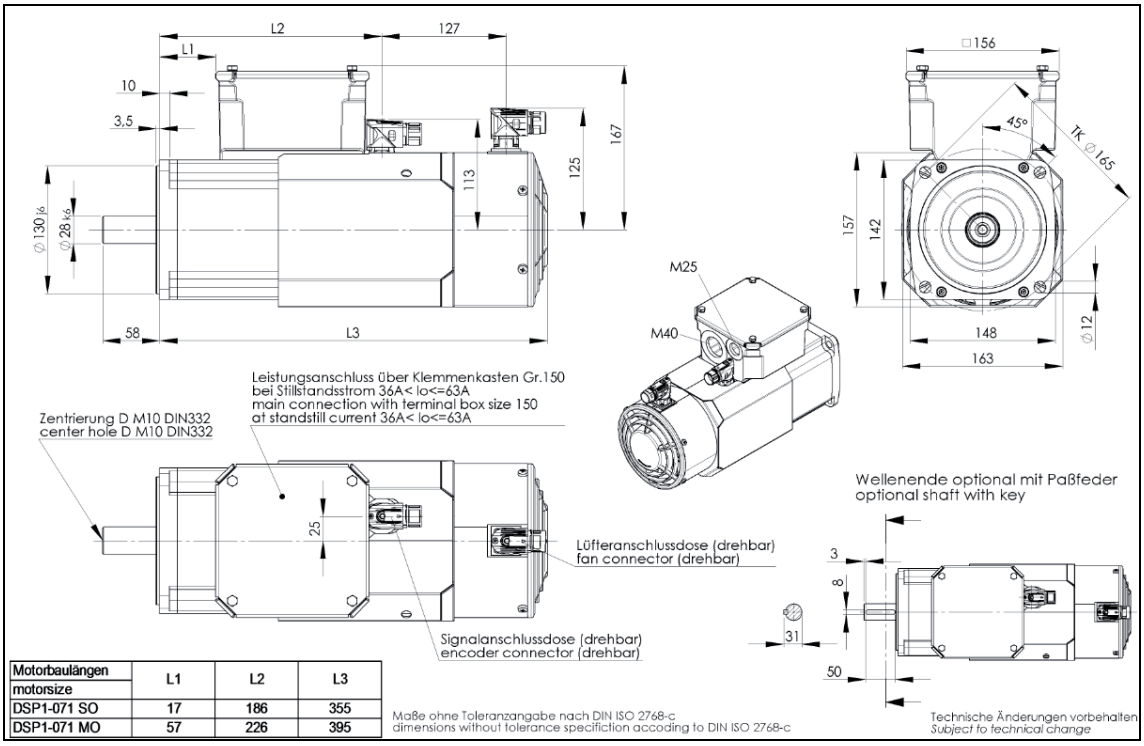
Motorbaulängen motorsize	L1	L1*	L2
DSP1-071 KO	111	106	315
DSP1-071 SO	151	146	355
DSP1-071 MO	191	186	395

Dimension drawing DSP1-071….O-..-..-.B.-SPP-.-..-O-000
Version IM B5



Motorbaulängen motorsize	L1	L1*	L2
DSP1-071 KO	111	106	362
DSP1-071 SO	151	146	402
DSP1-071 MO	191	186	442

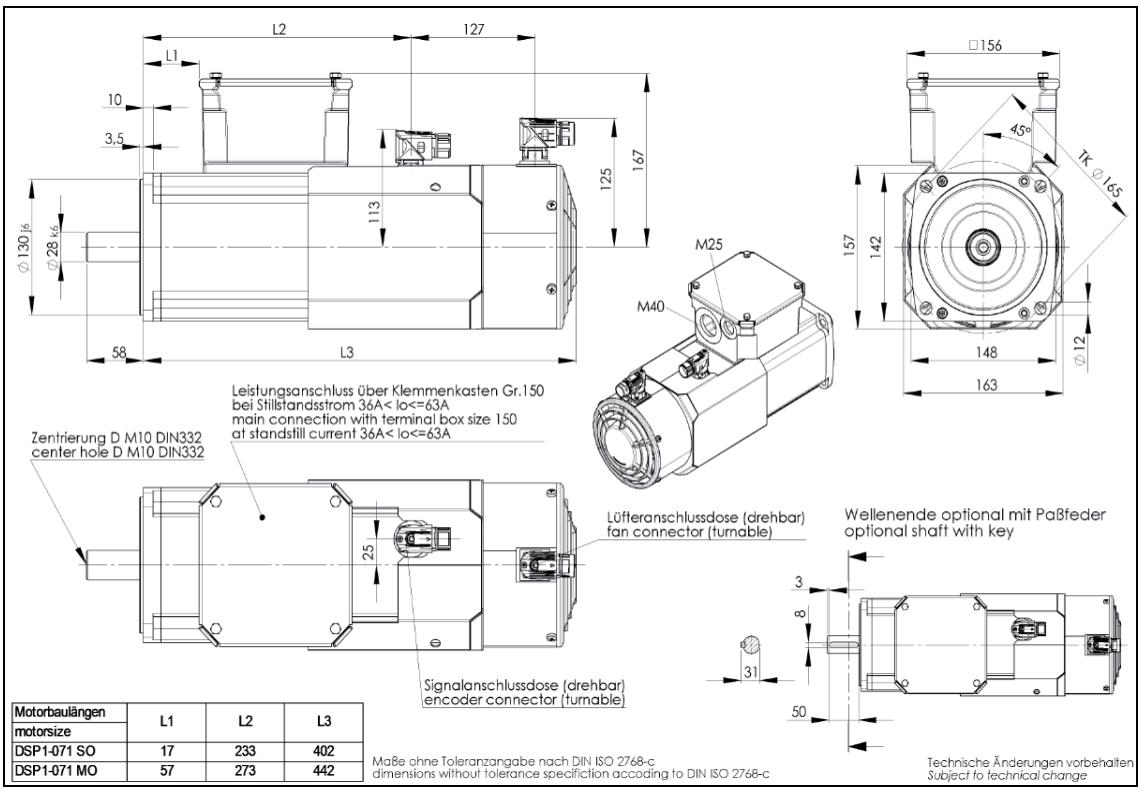
Dimension drawing DSP1-071….O-..-..-.O.-KNP-.-..-O-000
Version IM B5



Motorbaulängen / motorsize	L1	L2	L3
DSP1-071 SO	17	186	355
DSP1-071 MO	57	226	395

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specifiction accoding to DIN ISO 2768-c

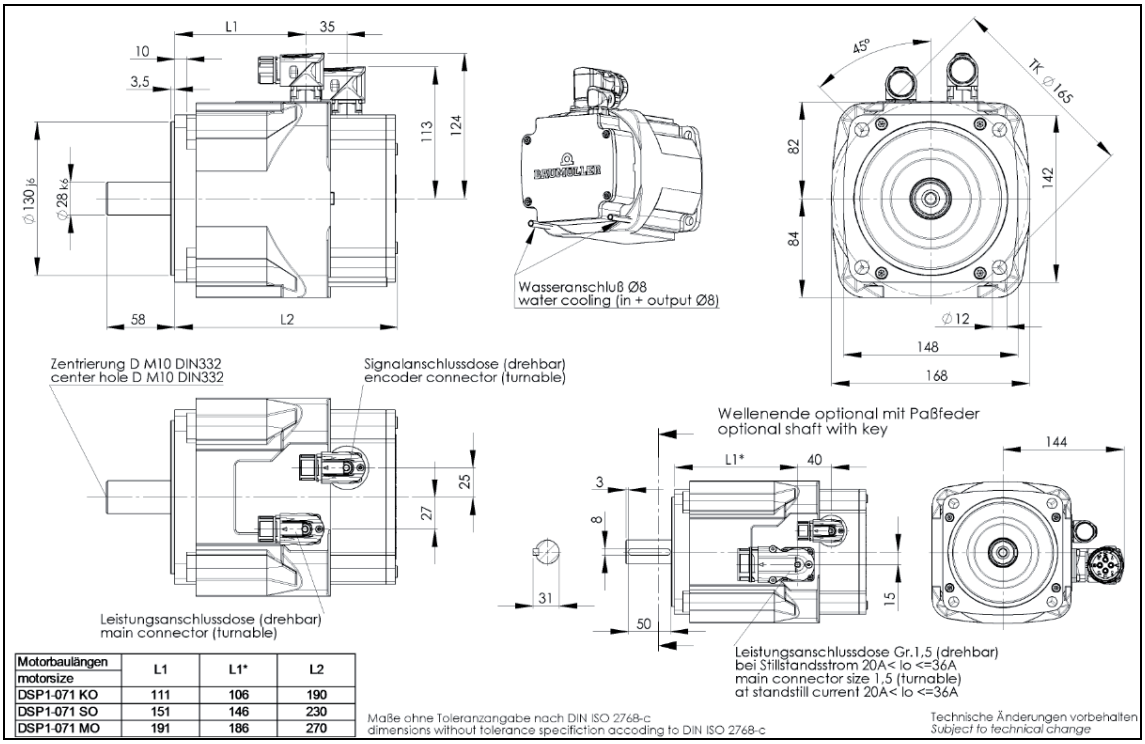
Dimension drawing DSP1-071….O-..-..-.B.-KNP-.-..-O-000
Version IM B5



Motorbaulängen / motorsize	L1	L2	L3
DSP1-071 SO	17	233	402
DSP1-071 MO	57	273	442

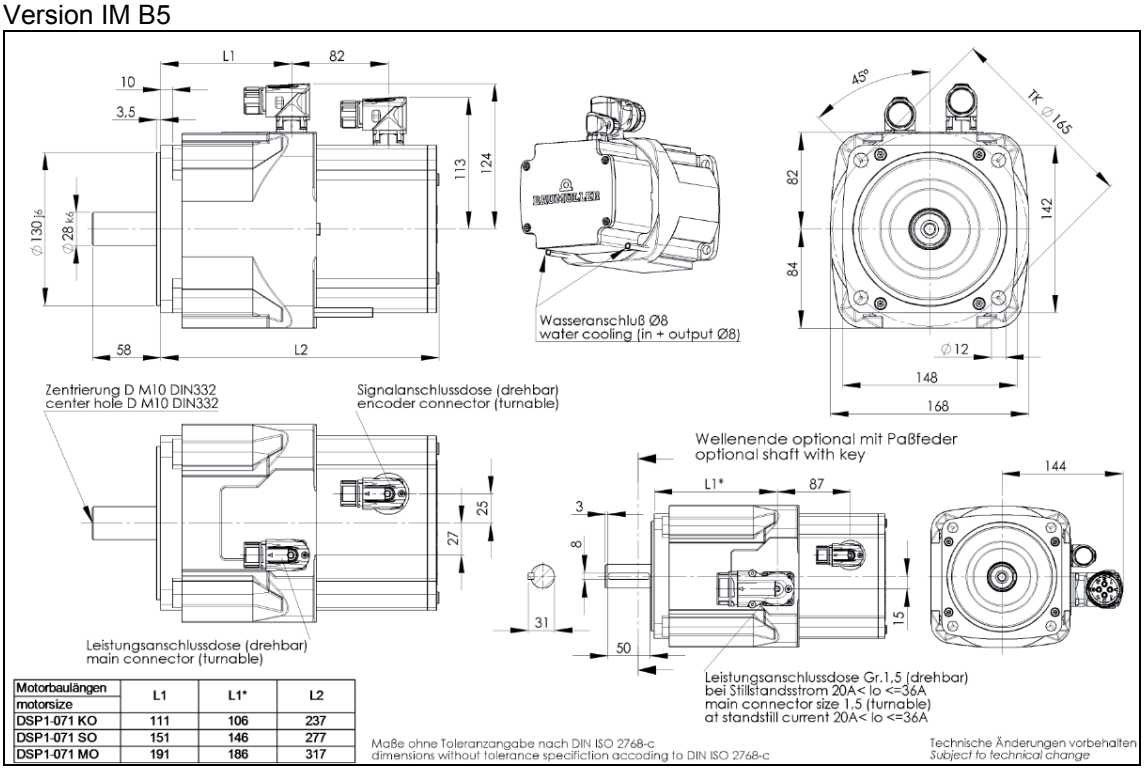
Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specifiction accoding to DIN ISO 2768-c

Dimension drawing DSP1-071….W-..-..-.O.-SPP-.-..-O-000
Version IM B5



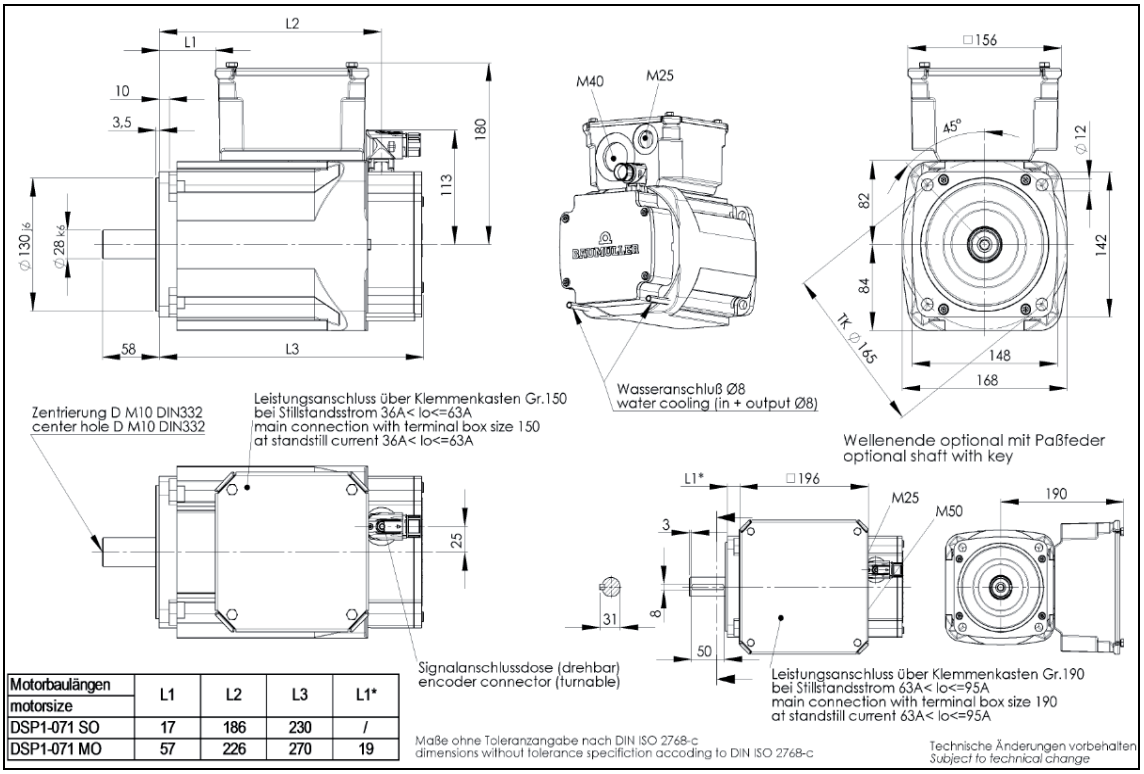
Motorbaulängen / motorsize	L1	L1*	L2
DSP1-071 KO	111	106	190
DSP1-071 SO	151	146	230
DSP1-071 MO	191	186	270

Dimension drawing DSP1-071….W-..-..-.B.-SPP-.-..-O-000
Version IM B5



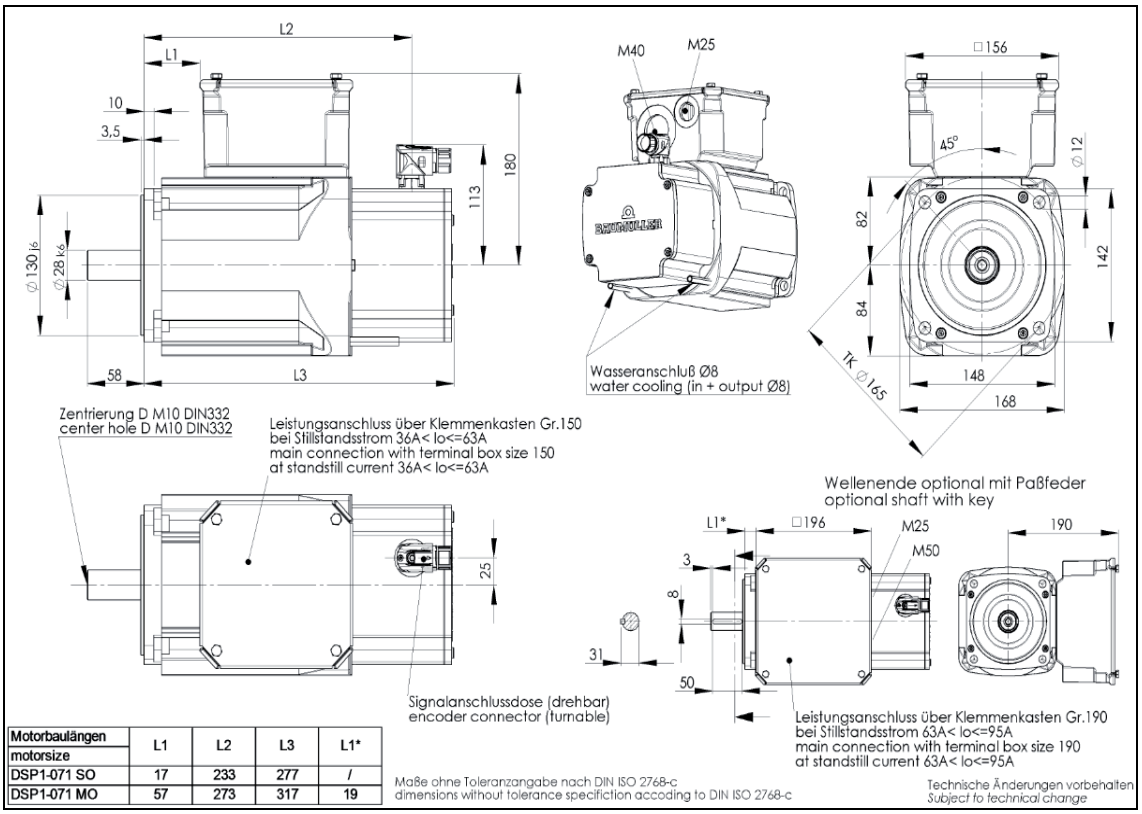
Motorbaulängen / motorsize	L1	L1*	L2
DSP1-071 KO	111	106	237
DSP1-071 SO	151	146	277
DSP1-071 MO	191	186	317

Dimension drawing DSP1-071….W-..-..-.O.-KNP-.-..-O-000
Version IM B5



Motorbaulängen / motorsize	L1	L2	L3	L1*
DSP1-071 SO	17	186	230	/
DSP1-071 MO	57	226	270	19

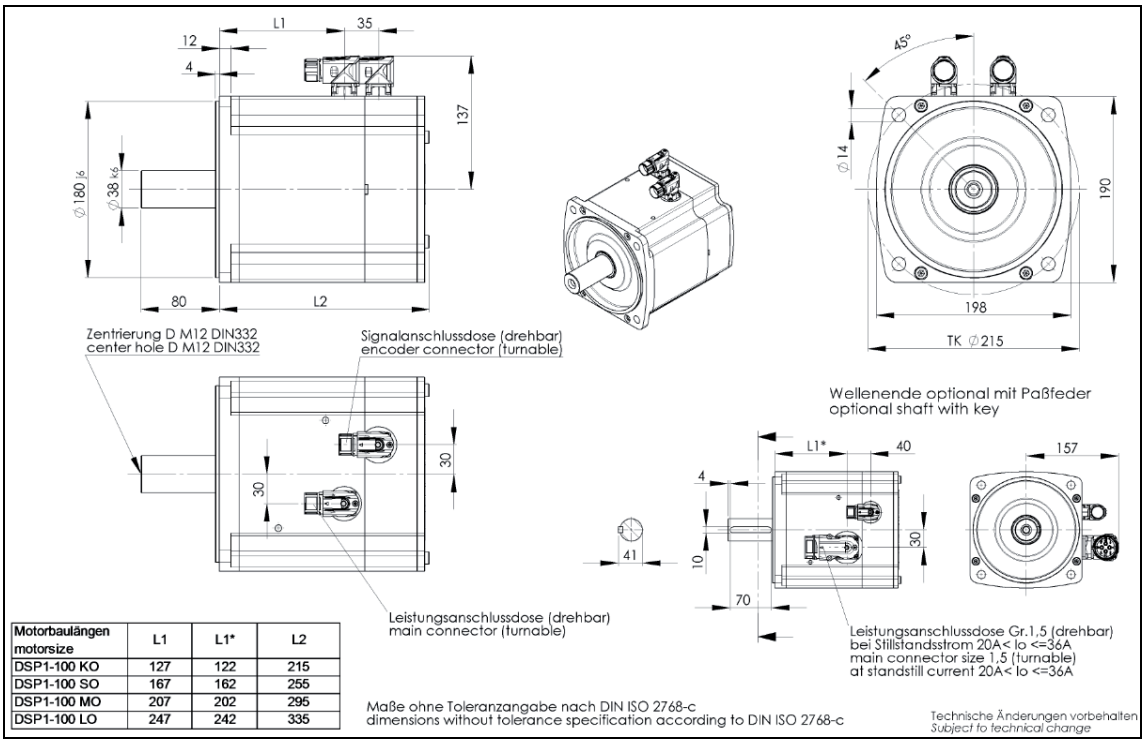
Dimension drawing DSP1-071….W-..-..-.B.-KNP-.-..-O-000
Version IM B5



Motorbaulängen / motorsize	L1	L2	L3	L1*
DSP1-071 SO	17	233	277	/
DSP1-071 MO	57	273	317	19

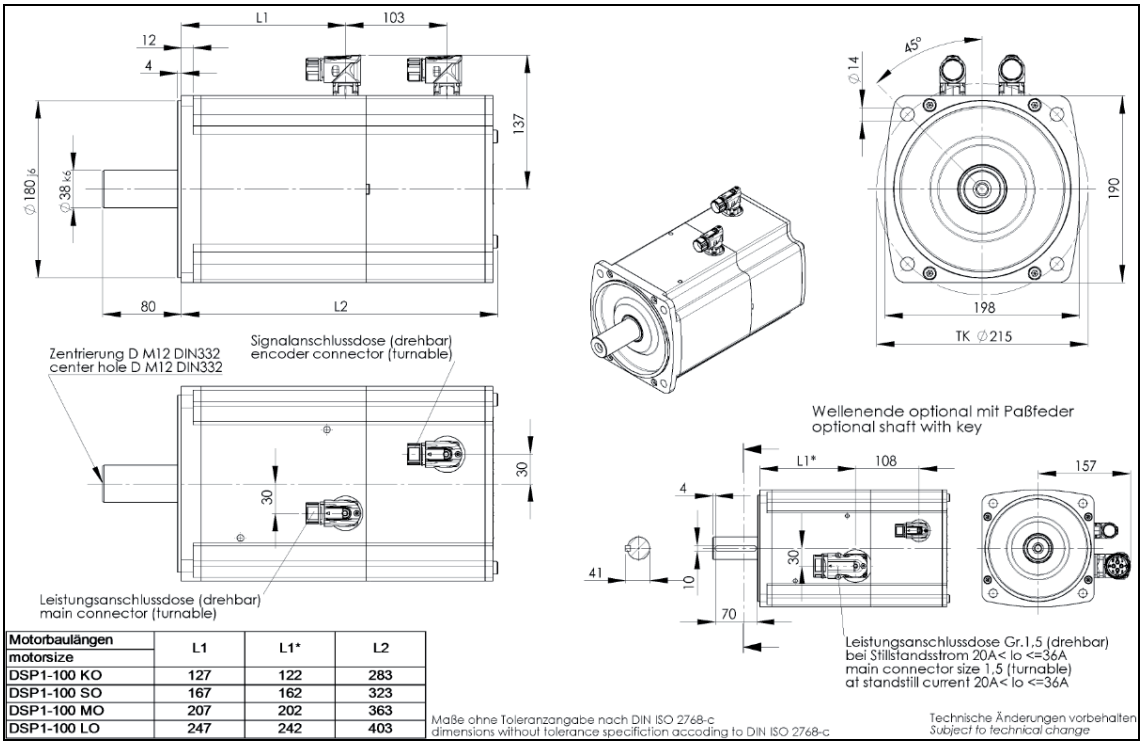
4.4. Dimension drawings DSP1-100

Dimension drawing DSP1-100….U-..-..-.O.-SPP-.-..-O-000
Version IM B5



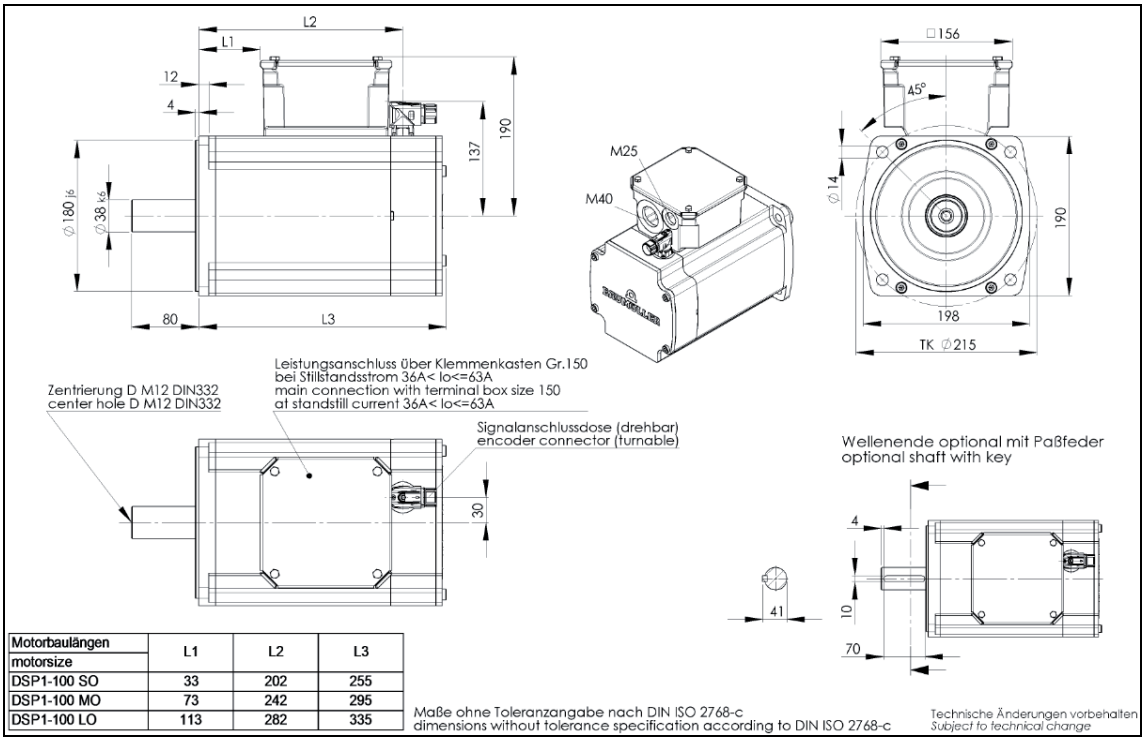
Motorbaulängen motorsize	L1	L1*	L2
DSP1-100 KO	127	122	215
DSP1-100 SO	167	162	255
DSP1-100 MO	207	202	295
DSP1-100 LO	247	242	335

Dimension drawing DSP1-100….U-..-..-.B.-SPP-.-..-O-000
Version IM B5



Motorbaulängen motorsize	L1	L1*	L2
DSP1-100 KO	127	122	283
DSP1-100 SO	167	162	323
DSP1-100 MO	207	202	363
DSP1-100 LO	247	242	403

Dimension drawing DSP1-100….U-..-..-.O.-KNP-.-..-O-000
Version IM B5

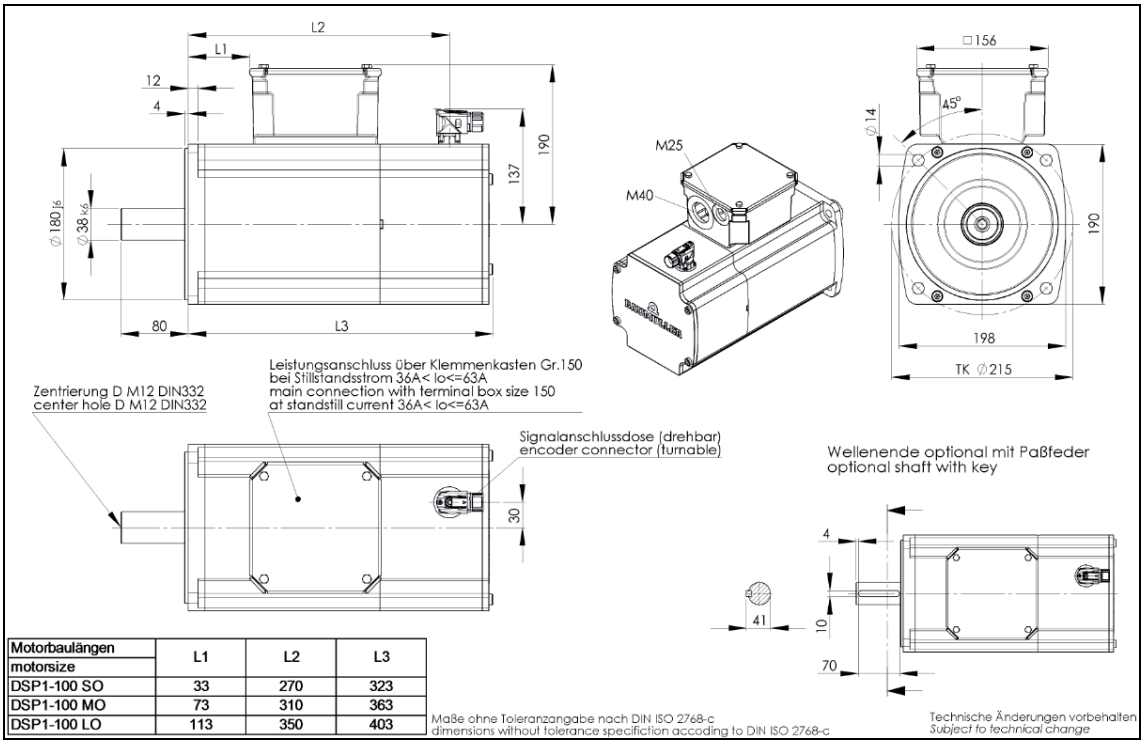


Motorbaulängen / motorsize	L1	L2	L3
DSP1-100 SO	33	202	255
DSP1-100 MO	73	242	295
DSP1-100 LO	113	282	335

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-100….U-..-..-.B.-KNP-.-..-O-000
Version IM B5

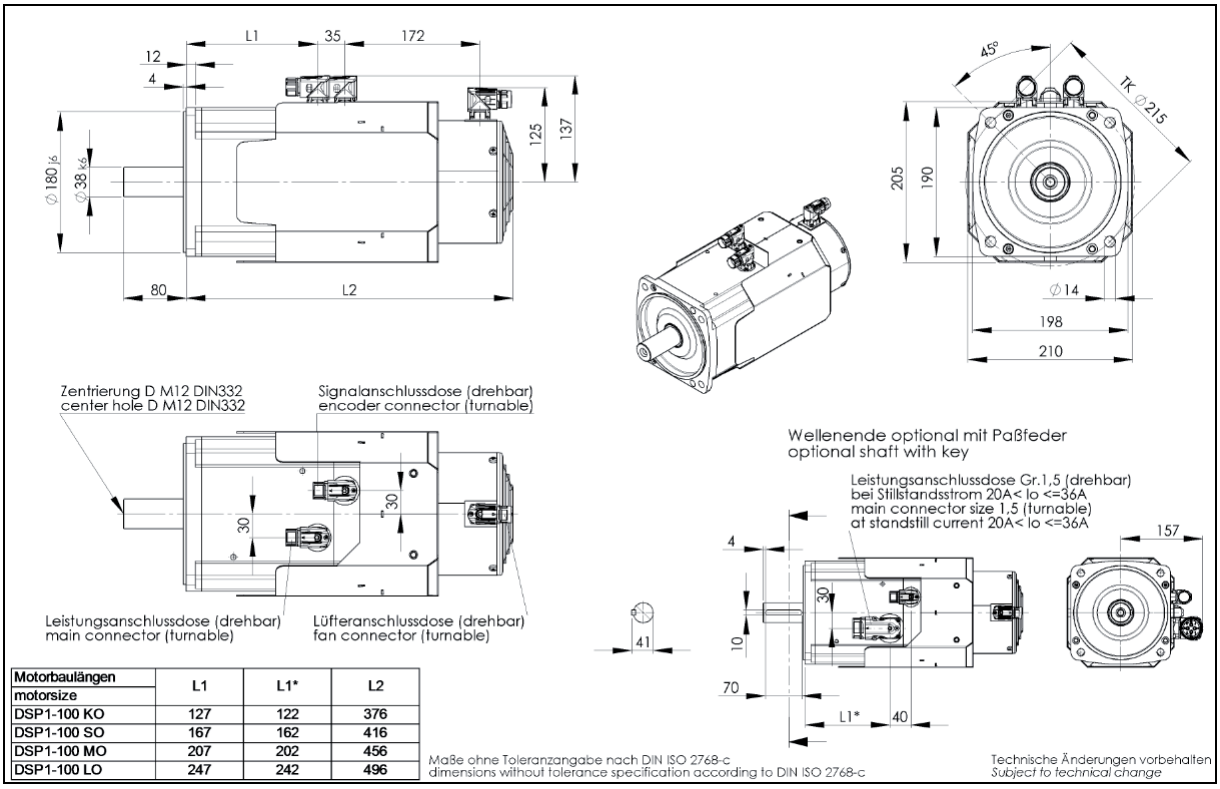


Motorbaulängen / motorsize	L1	L2	L3
DSP1-100 SO	33	270	323
DSP1-100 MO	73	310	363
DSP1-100 LO	113	350	403

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specifiction accoding to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-100….O-..-..-.O.-SPP-.-..-O-000
Version IM B5

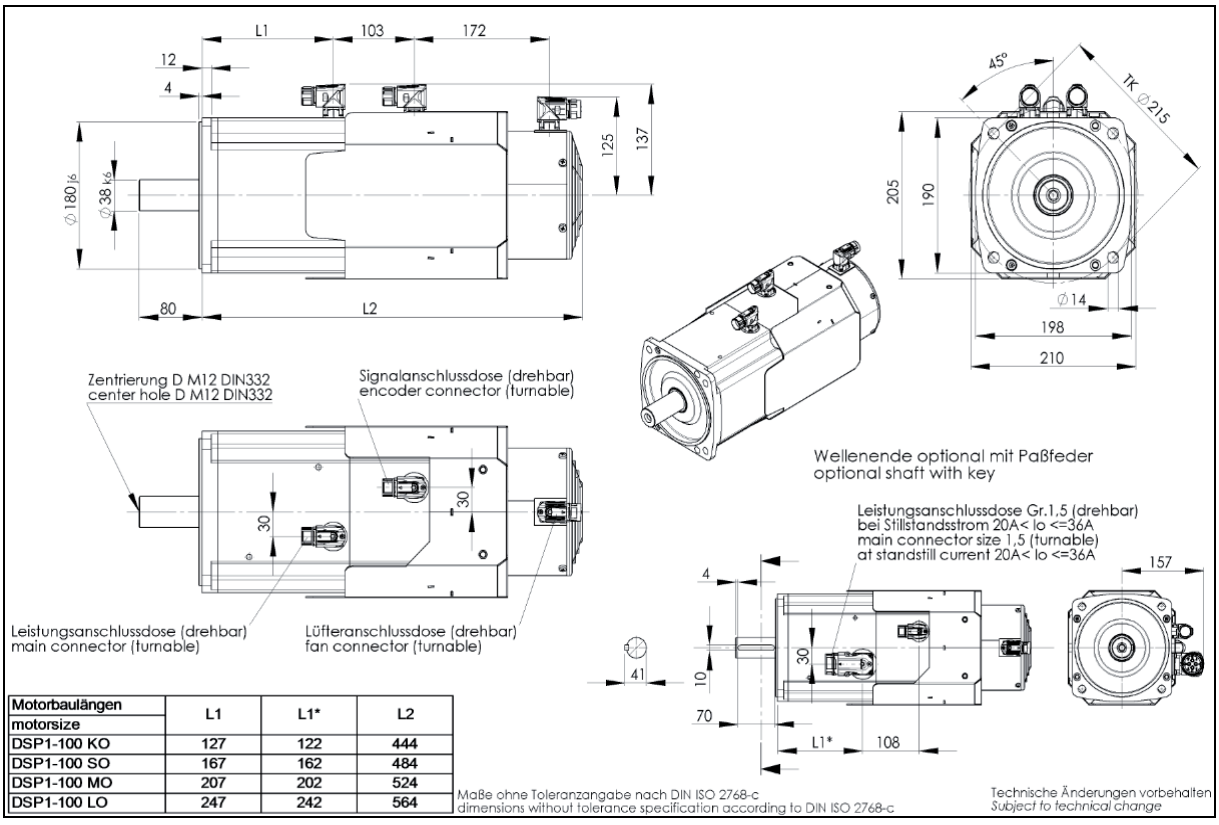


Motorbaulängen / motorsize	L1	L1*	L2
DSP1-100 KO	127	122	376
DSP1-100 SO	167	162	416
DSP1-100 MO	207	202	456
DSP1-100 LO	247	242	496

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-100….O-..-..-.B.-SPP-.-..-O-000
Version IM B5

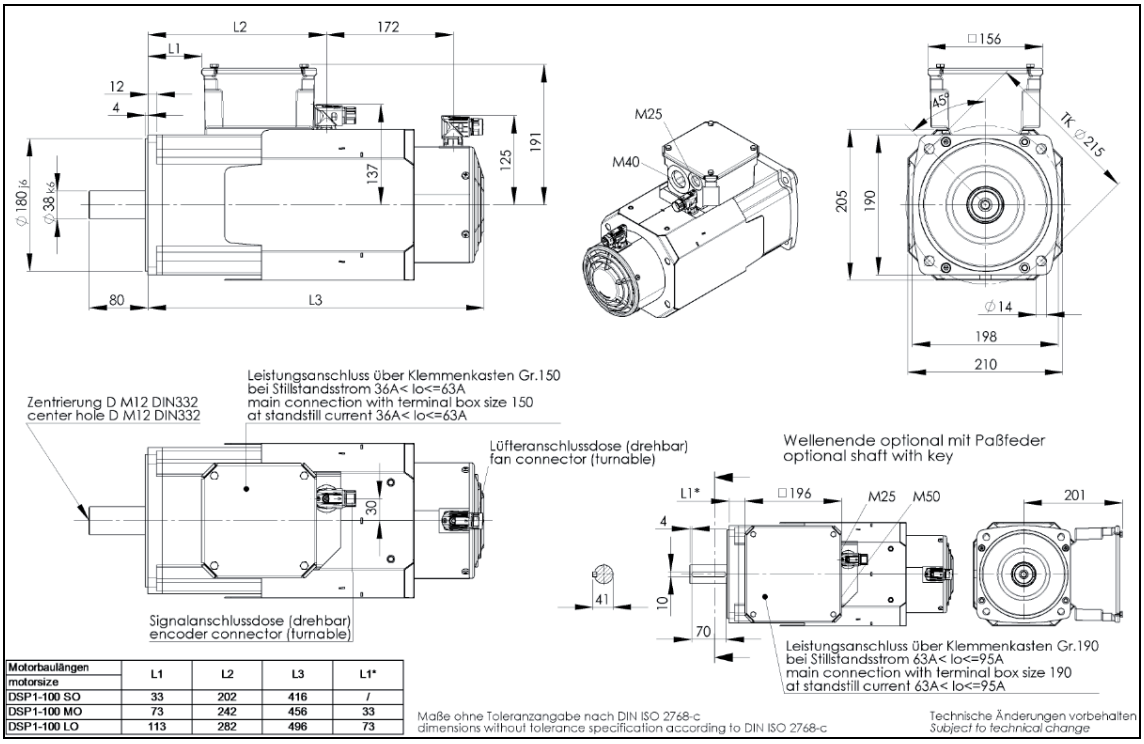


Motorbaulängen / motorsize	L1	L1*	L2
DSP1-100 KO	127	122	444
DSP1-100 SO	167	162	484
DSP1-100 MO	207	202	524
DSP1-100 LO	247	242	564

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-100….O-..-..-.O.-KNP-.-..-O-000
Version IM B5

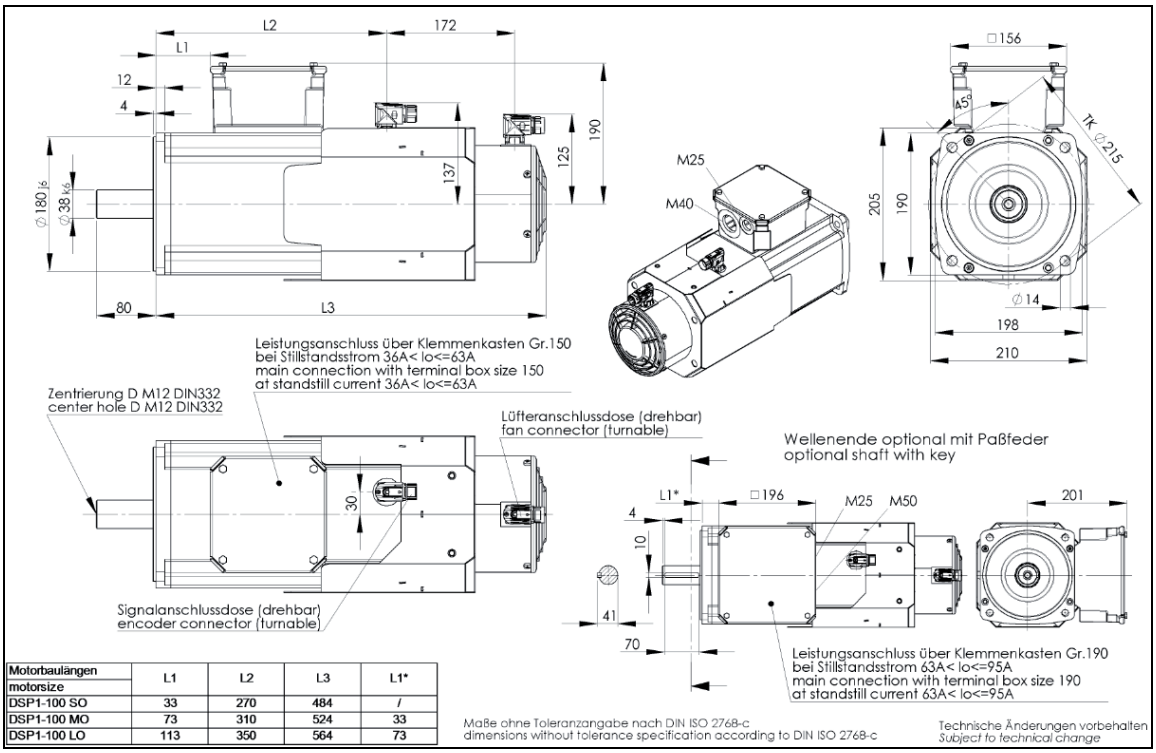


Motorbaulängen motorsize	L1	L2	L3	L1*
DSP1-100 SO	33	202	416	/
DSP1-100 MO	73	242	456	33
DSP1-100 LO	113	282	496	73

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-100….O-..-..-.B.-KNP-.-..-O-000
Version IM B5

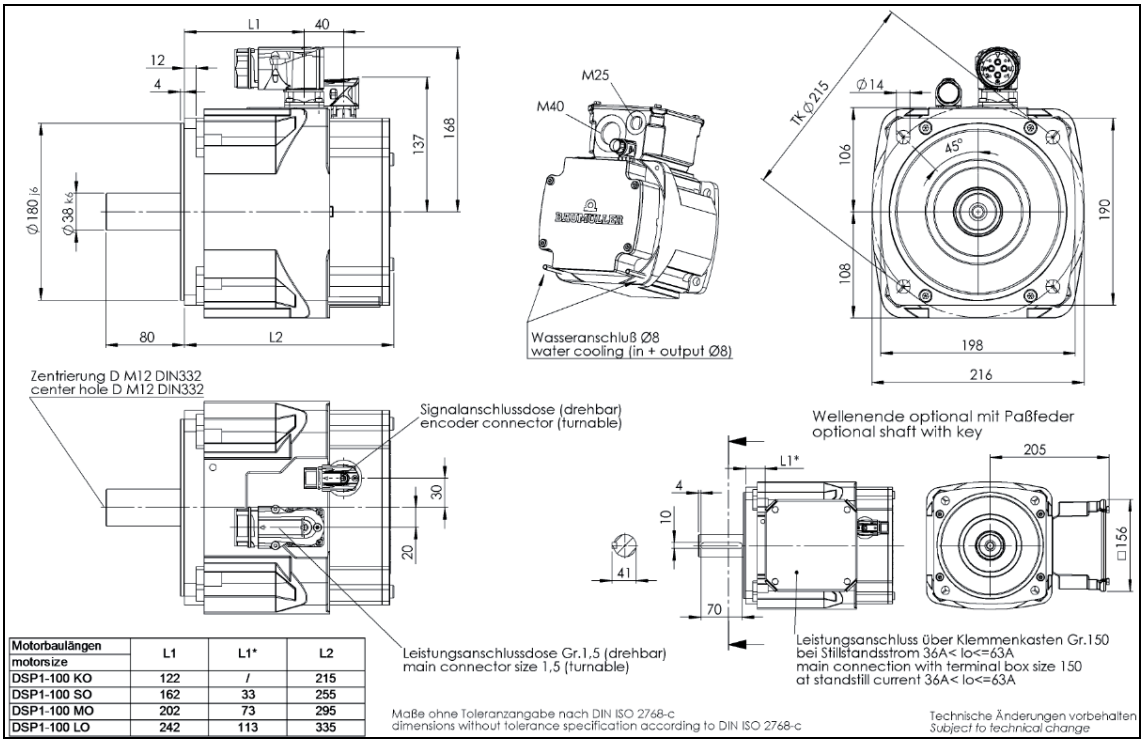


Motorbaulängen motorsize	L1	L2	L3	L1*
DSP1-100 SO	33	270	484	/
DSP1-100 MO	73	310	524	33
DSP1-100 LO	113	350	564	73

Maße ohne Toleranzangabe nach DIN ISO 2768-c
dimensions without tolerance specification according to DIN ISO 2768-c

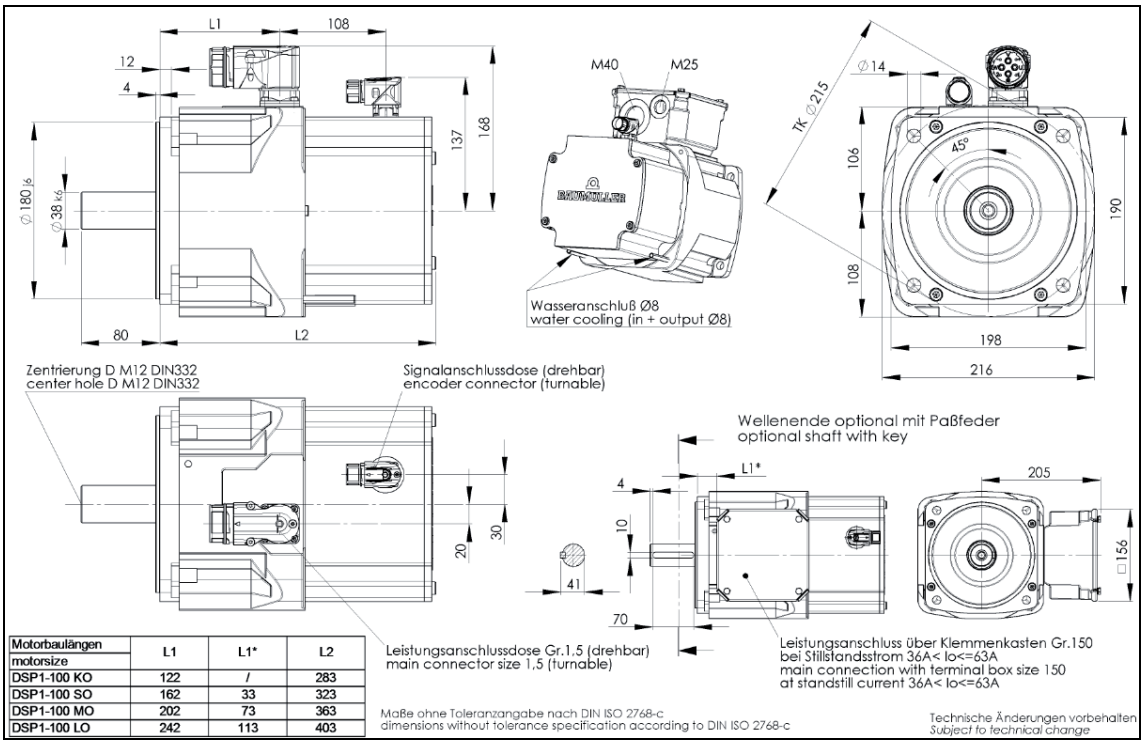
Technische Änderungen vorbehalten
Subject to technical change

Dimension drawing DSP1-100….W-..-..-.O.-__P-.-..-O-000
Version IM B5



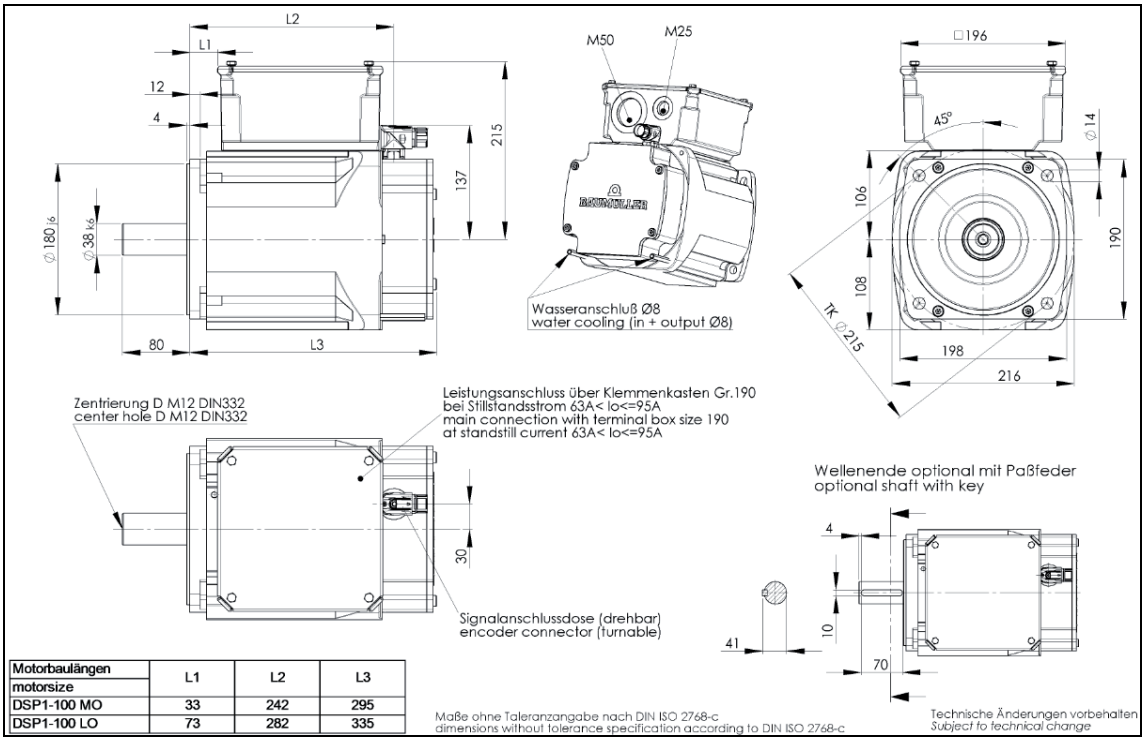
Motorbaulängen / motorsize	L1	L1*	L2
DSP1-100 KO	122	/	215
DSP1-100 SO	162	33	255
DSP1-100 MO	202	73	295
DSP1-100 LO	242	113	335

Dimension drawing DSP1-100….W-..-..-.B.-__P-.-..-O-000
Version IM B5



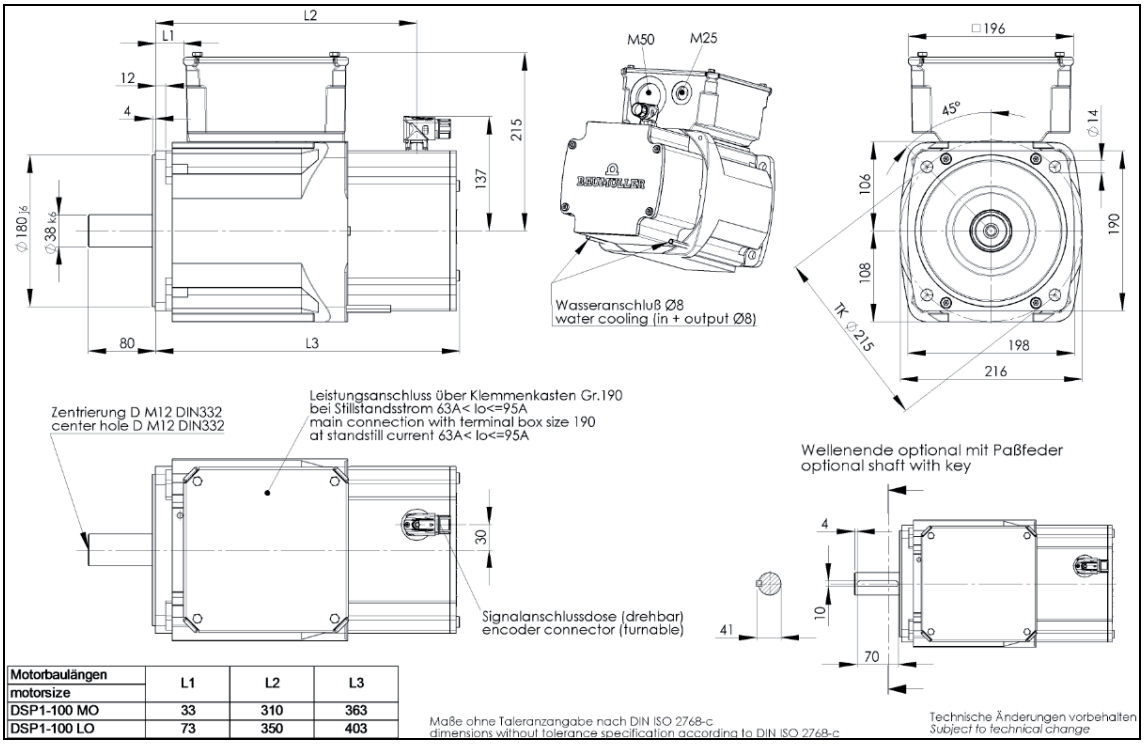
Motorbaulängen / motorsize	L1	L1*	L2
DSP1-100 KO	122	/	283
DSP1-100 SO	162	33	323
DSP1-100 MO	202	73	363
DSP1-100 LO	242	113	403

Dimension drawing DSP1-100….W-..-..-.O.-KNP-.-..-O-000
Version IM B5



Motorbaulängen / motorsize	L1	L2	L3
DSP1-100 MO	33	242	295
DSP1-100 LO	73	282	335

Dimension drawing DSP1-100….W-..-..-.B.-KNP-.-..-O-000
Version IM B5

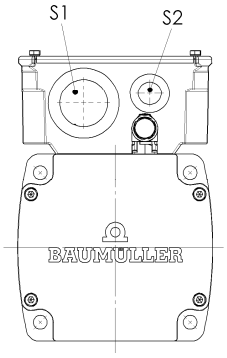


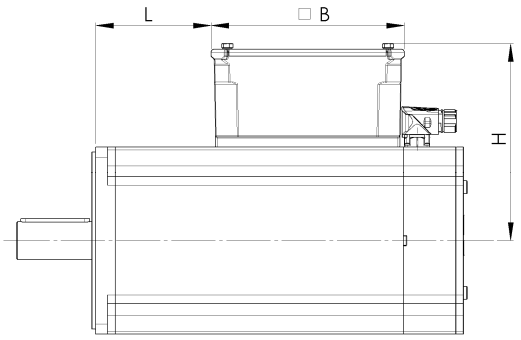
Motorbaulängen / motorsize	L1	L2	L3
DSP1-100 MO	33	310	363
DSP1-100 LO	73	350	403

4.5. Terminal box dimensions

In a I_0 > 36 A, a terminal box must be used.

If 63 A > I_0 > 36 A, the following terminal box must be used. The outflow direction of the main connection is toward the N side.

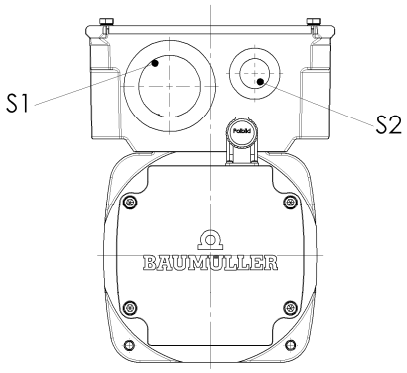


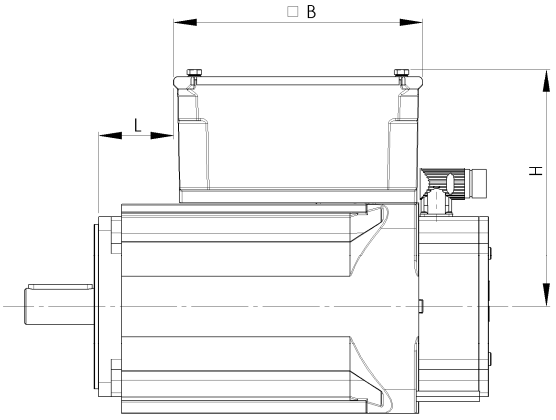


Motor length	L	B	H	S1	S2	I_0
DSP1-071SO	17	156	170	M40	M25	≤ 63 A
DSP1-071MO	57	156	170	M40	M25	≤ 63 A

DSP1-100KO	/	156	205	M50	M25	≤ 63 A
DSP1-100SO	33	156	205	M50	M25	≤ 63 A
DSP1-100MO	73	156	205	M50	M25	≤ 63 A
DSP1-100LO	113	156	205	M50	M25	≤ 63 A

In a motor with I_0 > 63 A, the following terminal box must be used. The outflow direction of the main connection is toward the N side.





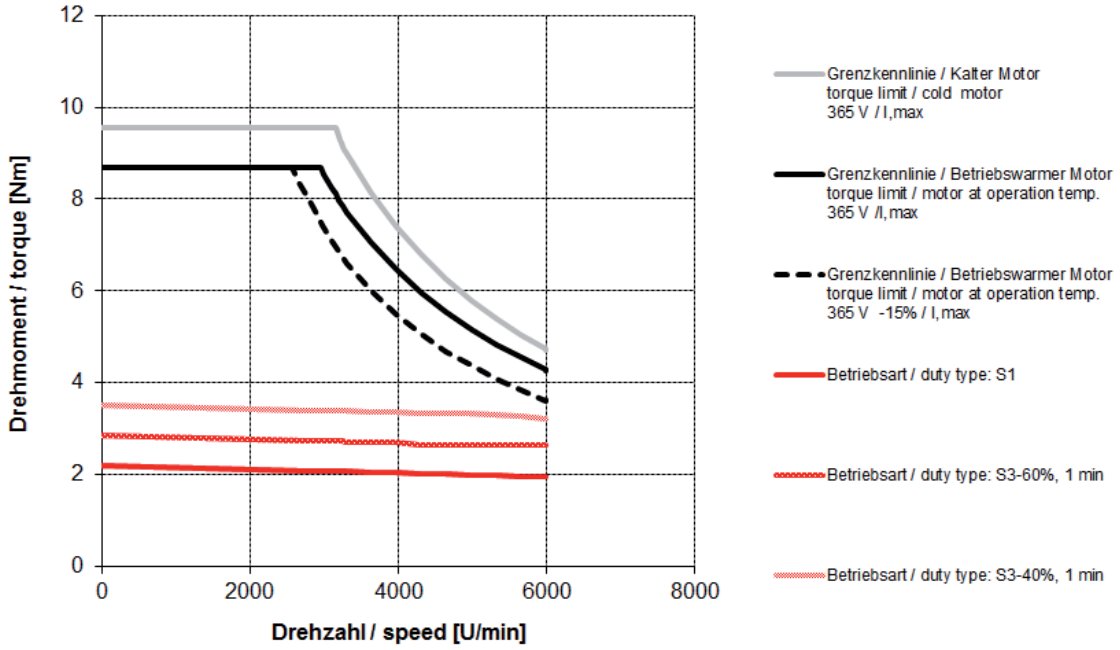
Motor length	L	B	H	S1	S2	I_0
DSP1-071MO	59	196	190	M50	M25	≤ 95 A

Motor length	L	B	H	S1	S2	I_0
DSP1-100SO	/	196	190	M50	M25	≤ 95 A
DSP1-100MO	33	196	190	M50	M25	≤ 95 A
DSP1-100LO	73	196	190	M50	M25	≤ 95 A

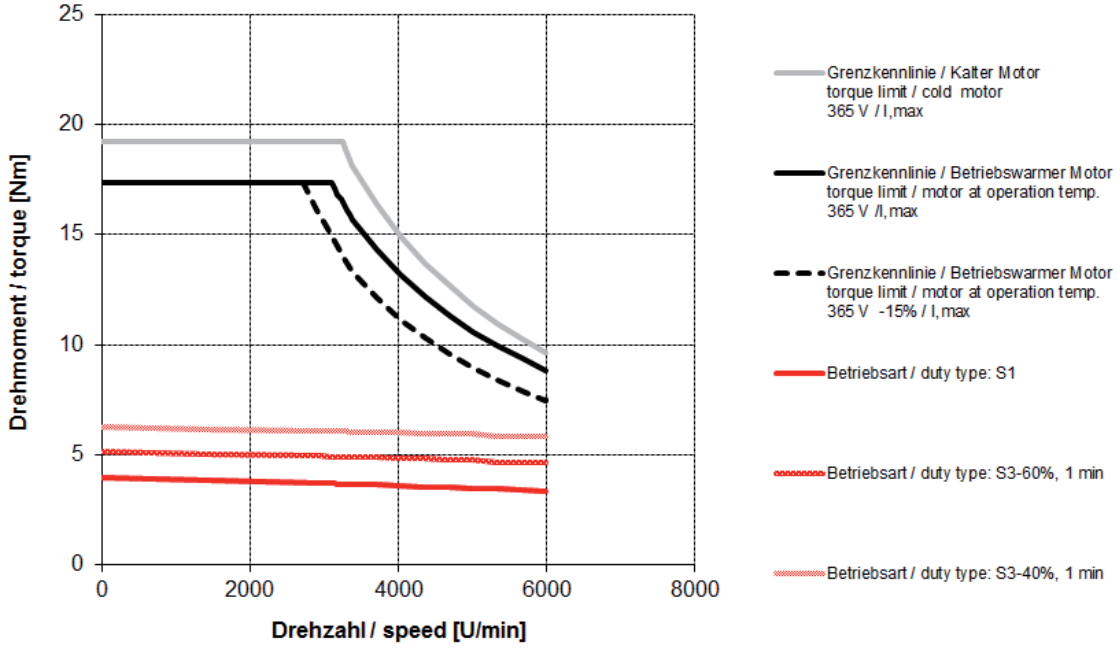
5. Motor characteristic curves

5.1. Characteristic curves DSP1-045

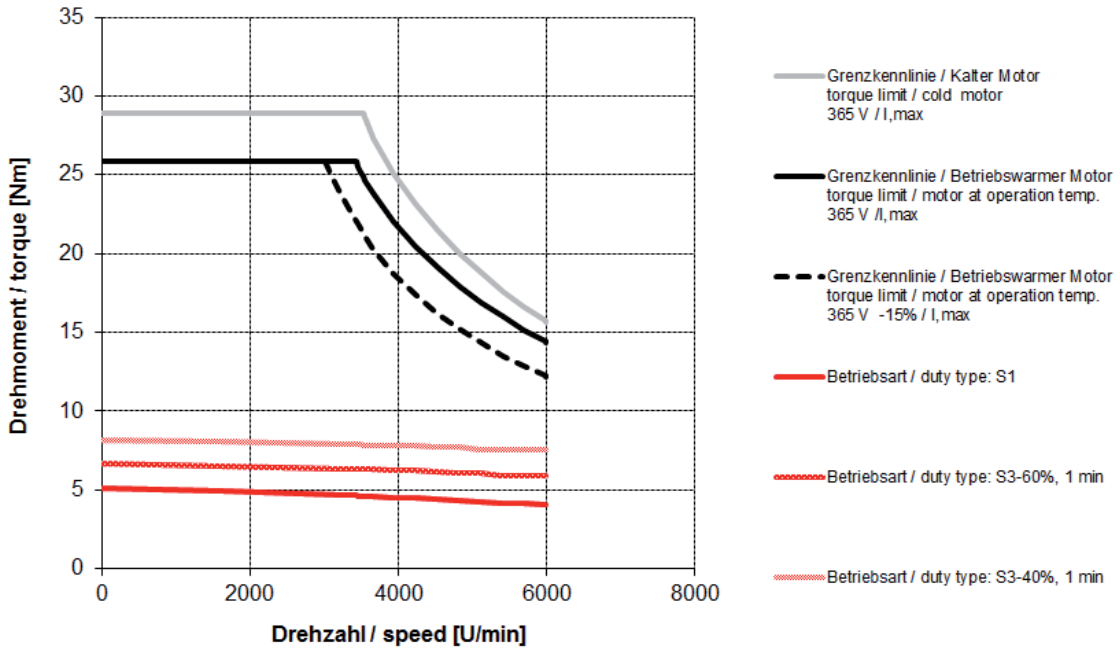
DSP1-045KO64U-60-54



DSP1-045SO64U-60-54



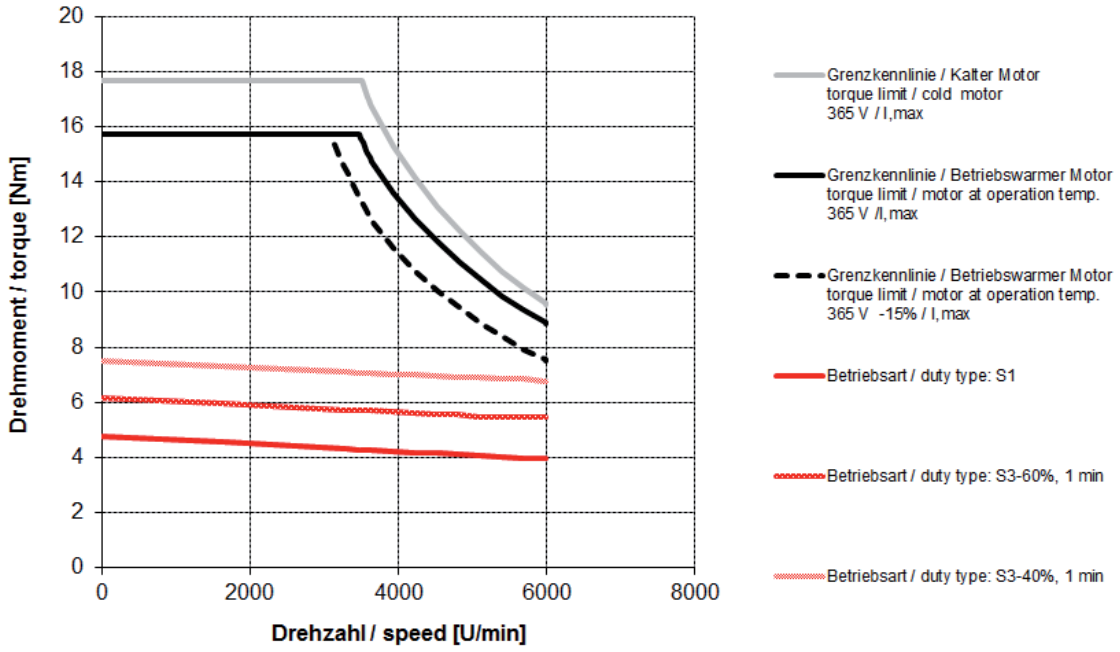
DSP1-045MO64U-60-54



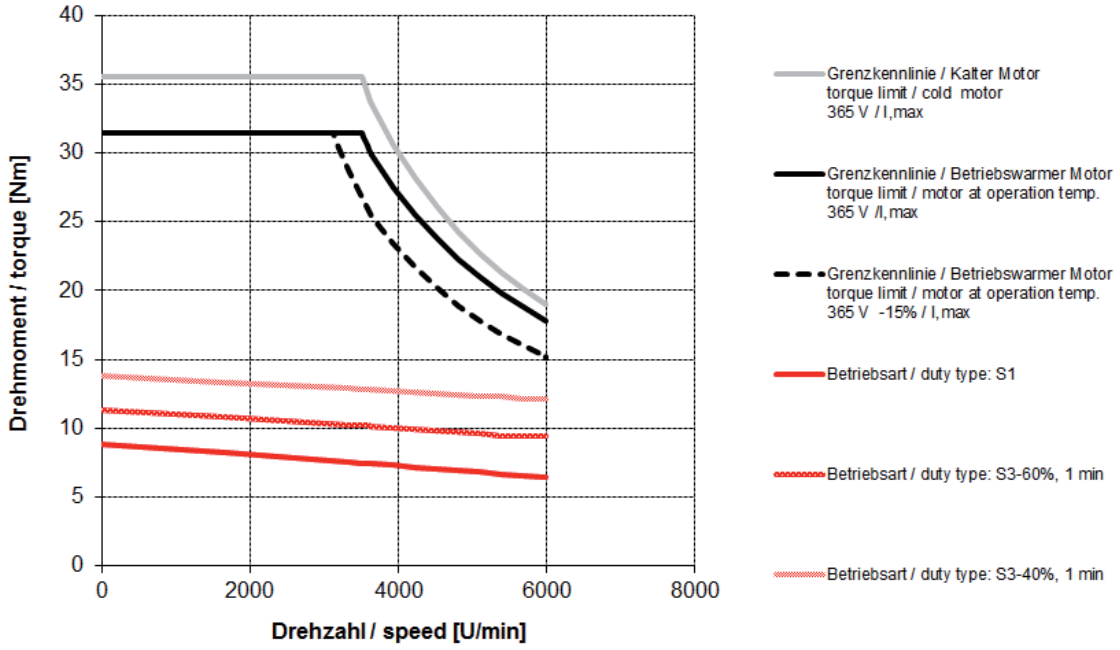
5.2. Characteristic curves DSP1-056

5.2.1. DSP1-056..64U-.. (without fan)

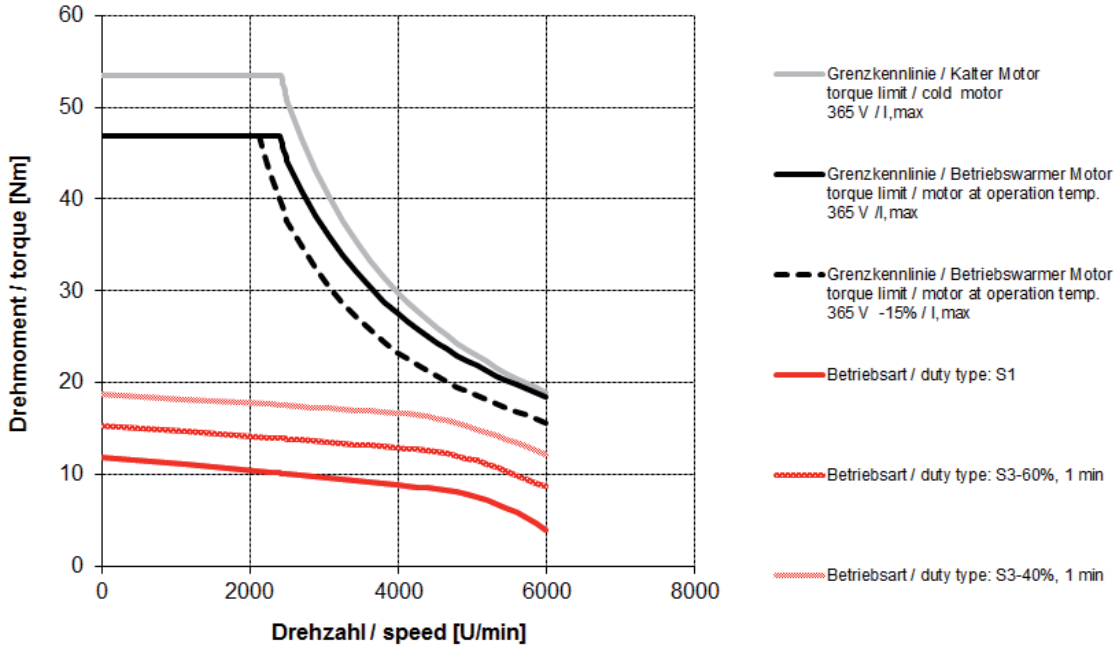
DSP1-056KO64U-60-54



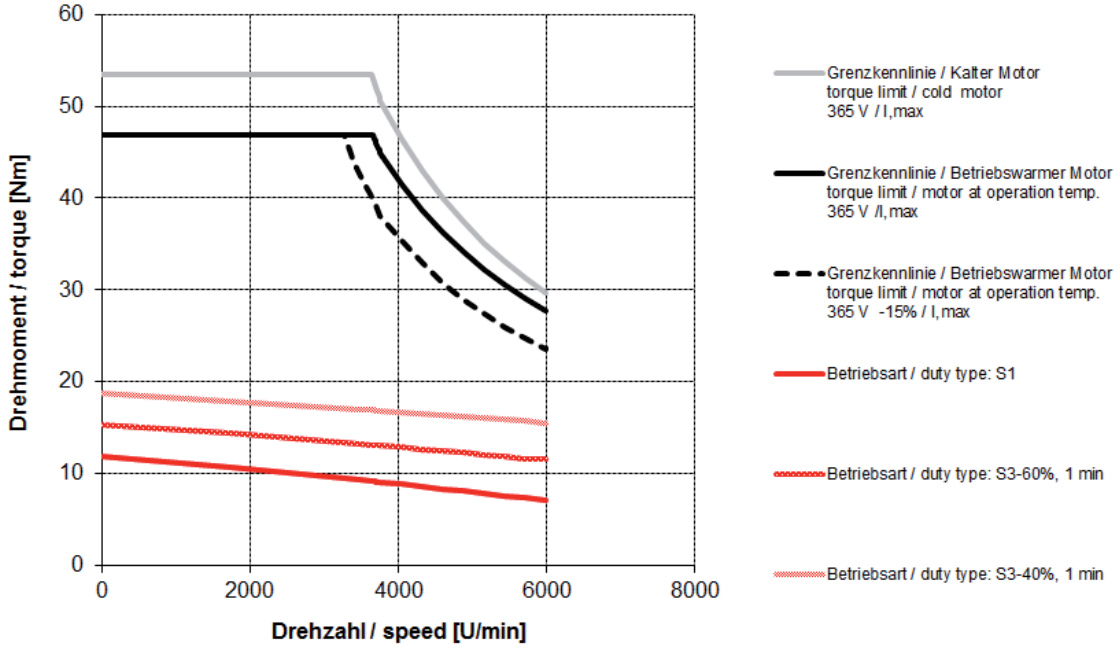
DSP1-056SO64U-60-54



DSP1-056MO64U-40-54

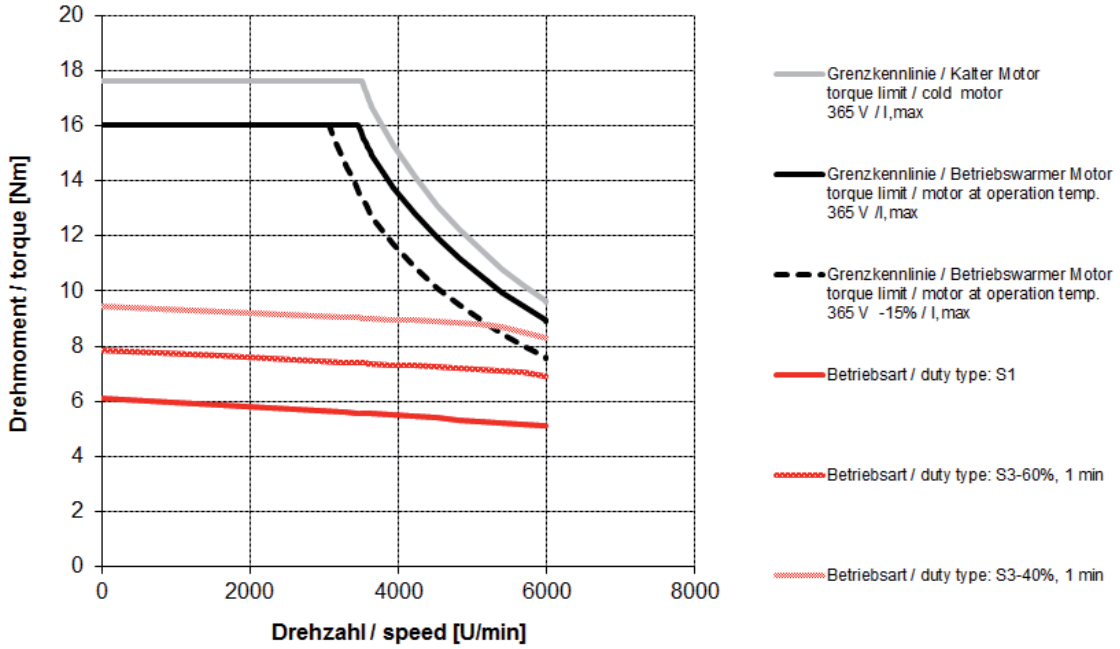


DSP1-056MO64U-60-54

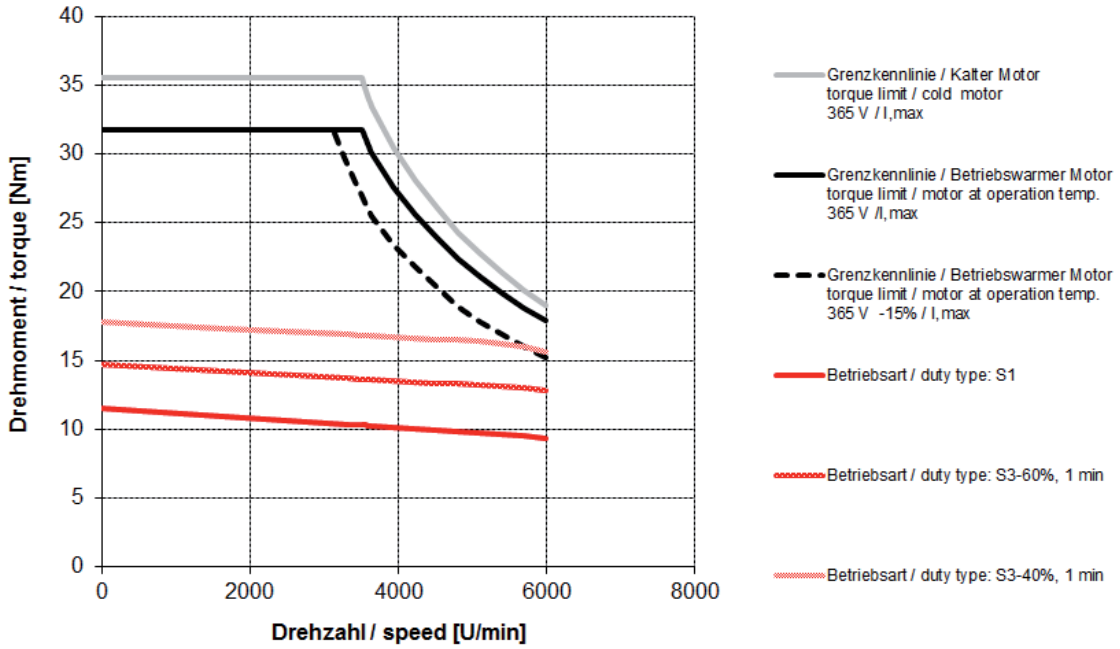


5.2.2. DSP1-056..64O-.. (with fan)

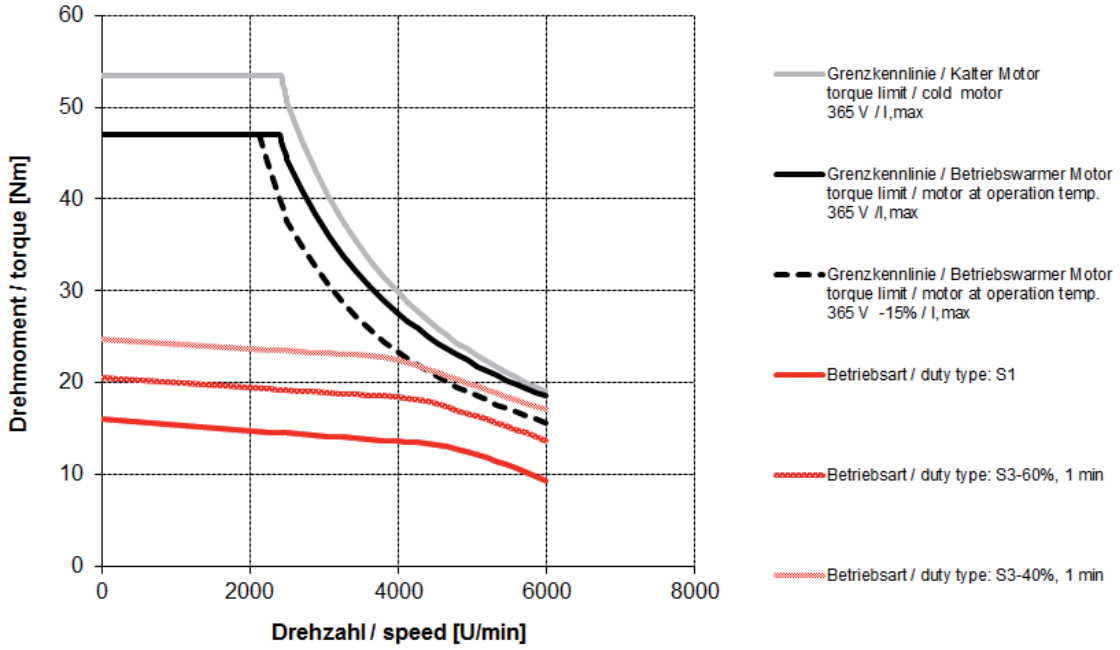
DSP1-056KO64O-60-54



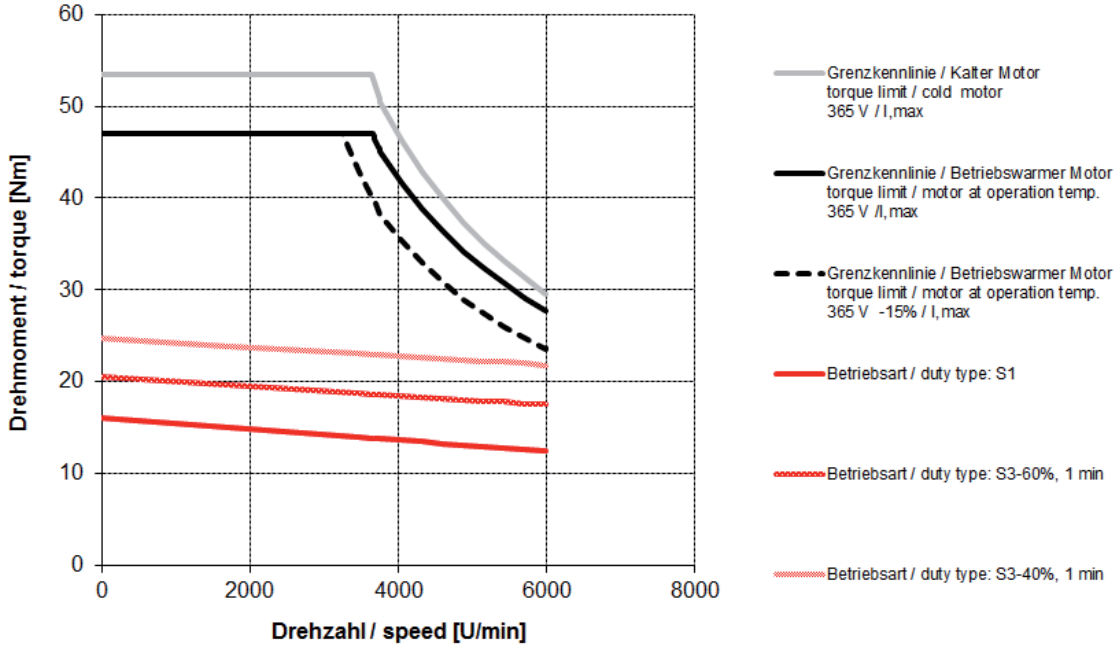
DSP1-056SO64O-60-54



DSP1-056MO64O-40-54



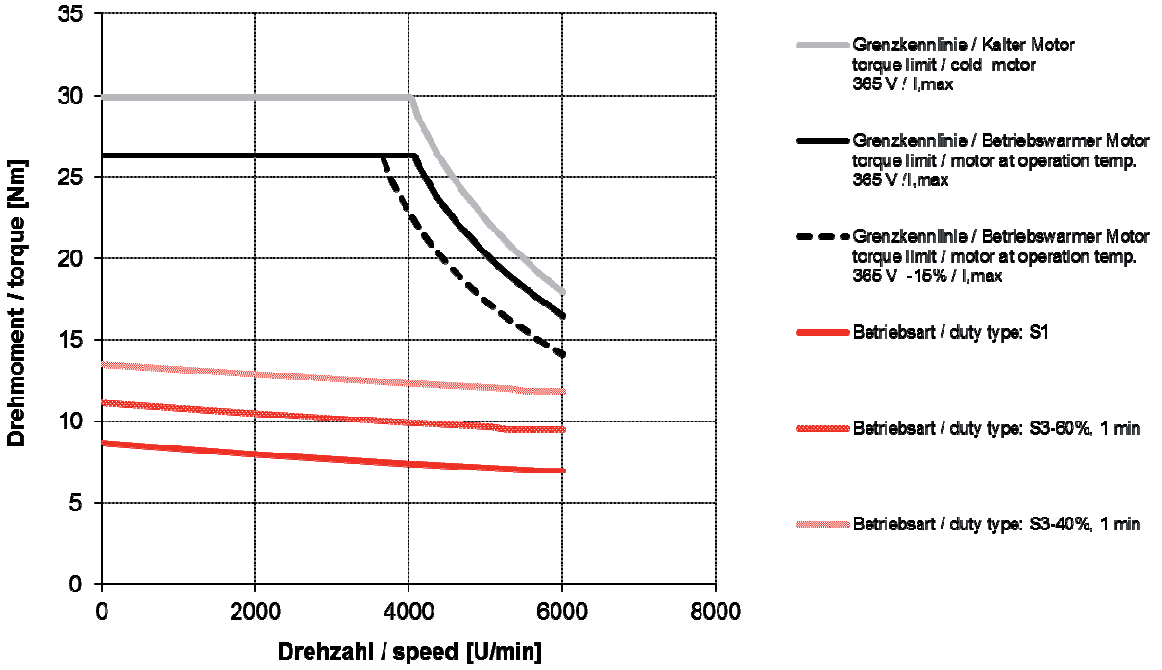
DSP1-056MO64O-60-54



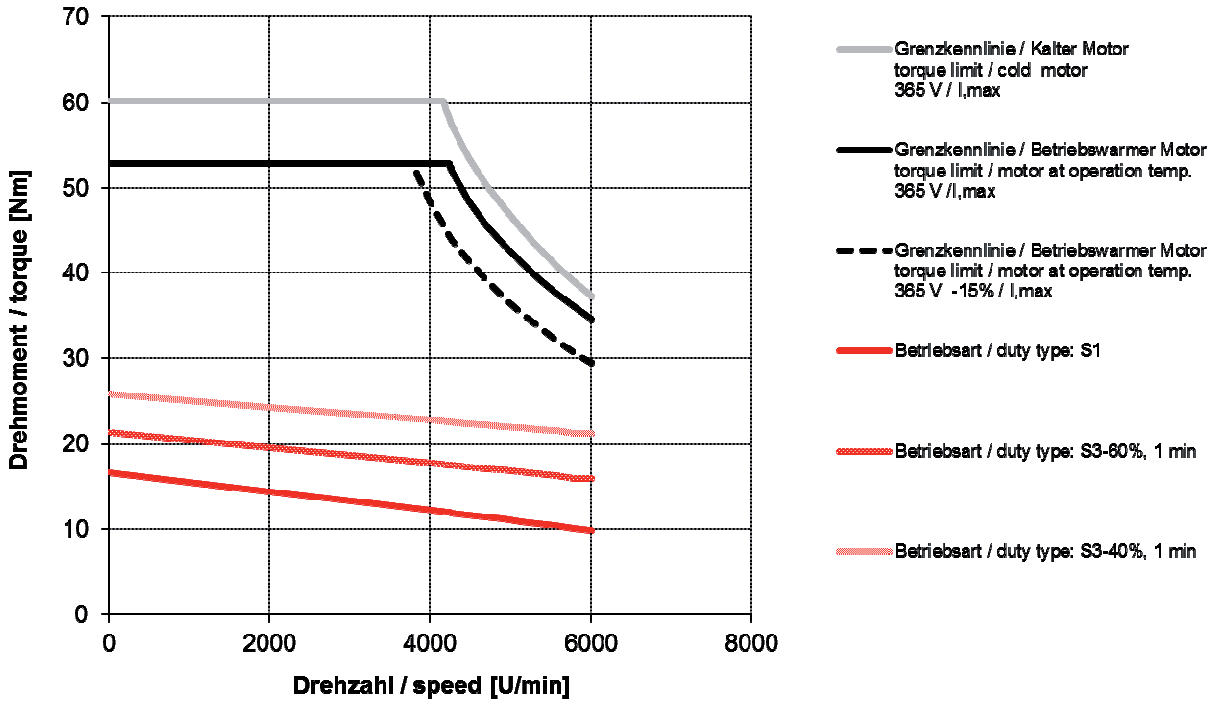
5.3. Characteristic curves DSP1-071

5.3.1. DSP1-071..64U-.. (without fan)

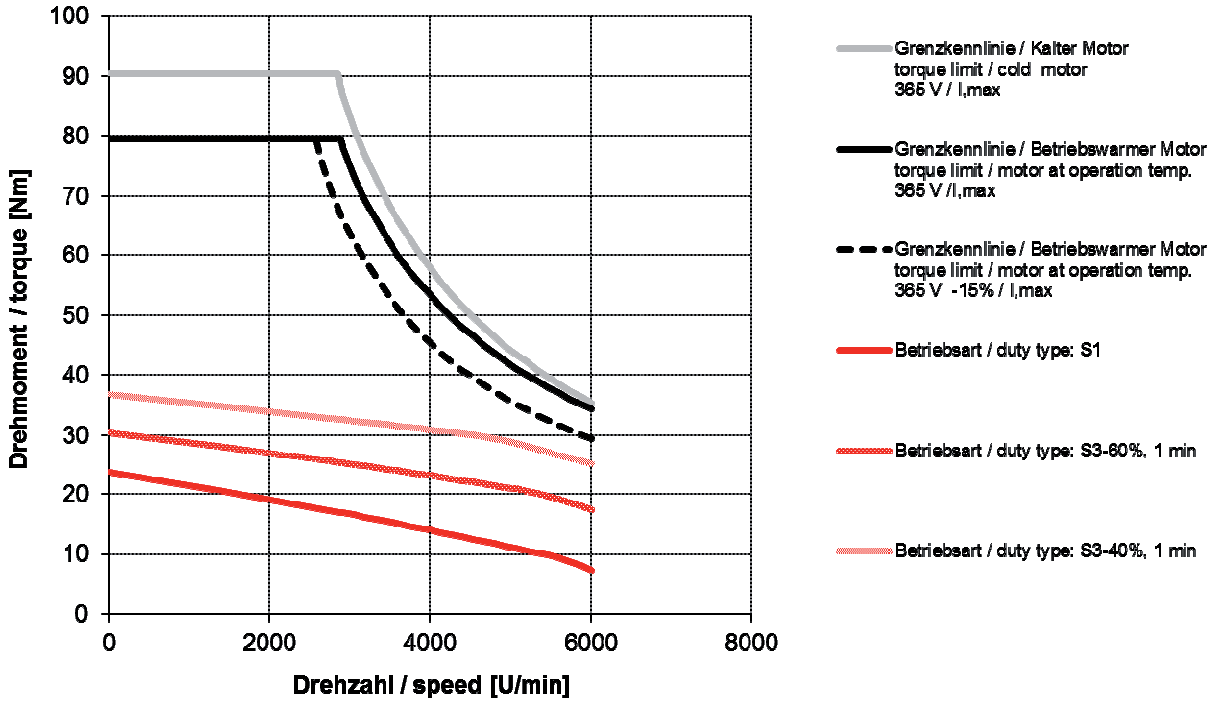
DSP1-071KO64U-60-5



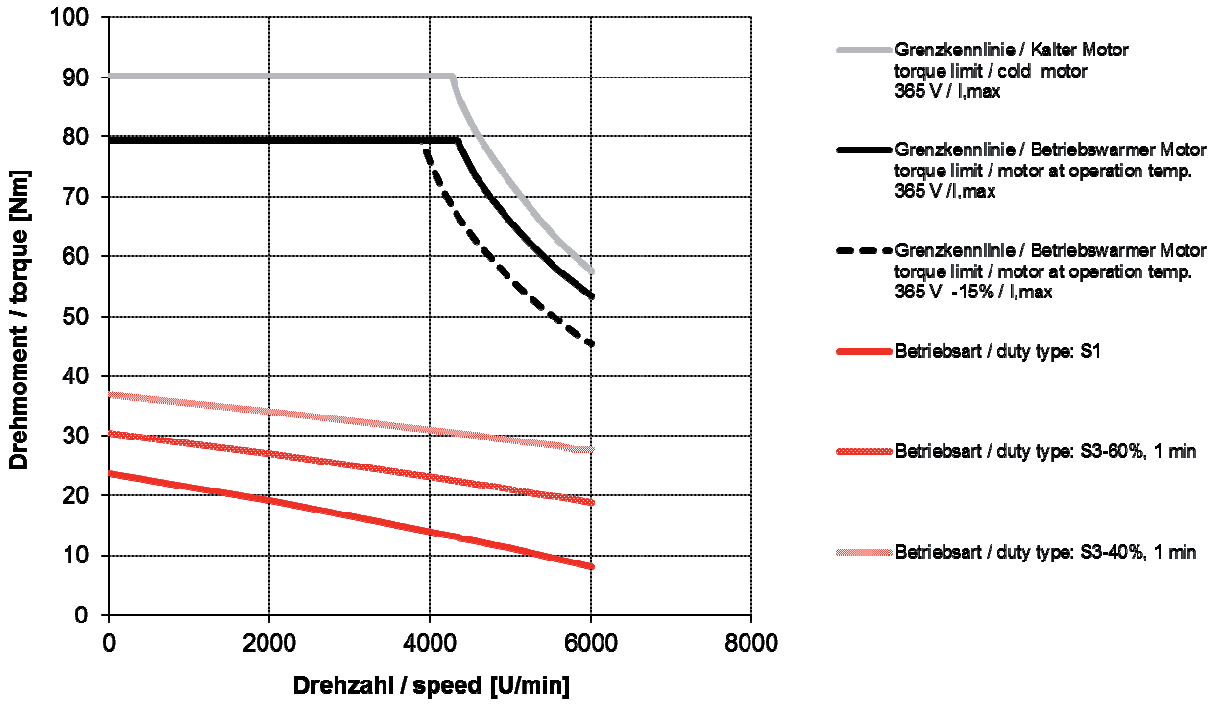
DSP1-071SO64U-60-5



DSP1-071MO64U-40-5

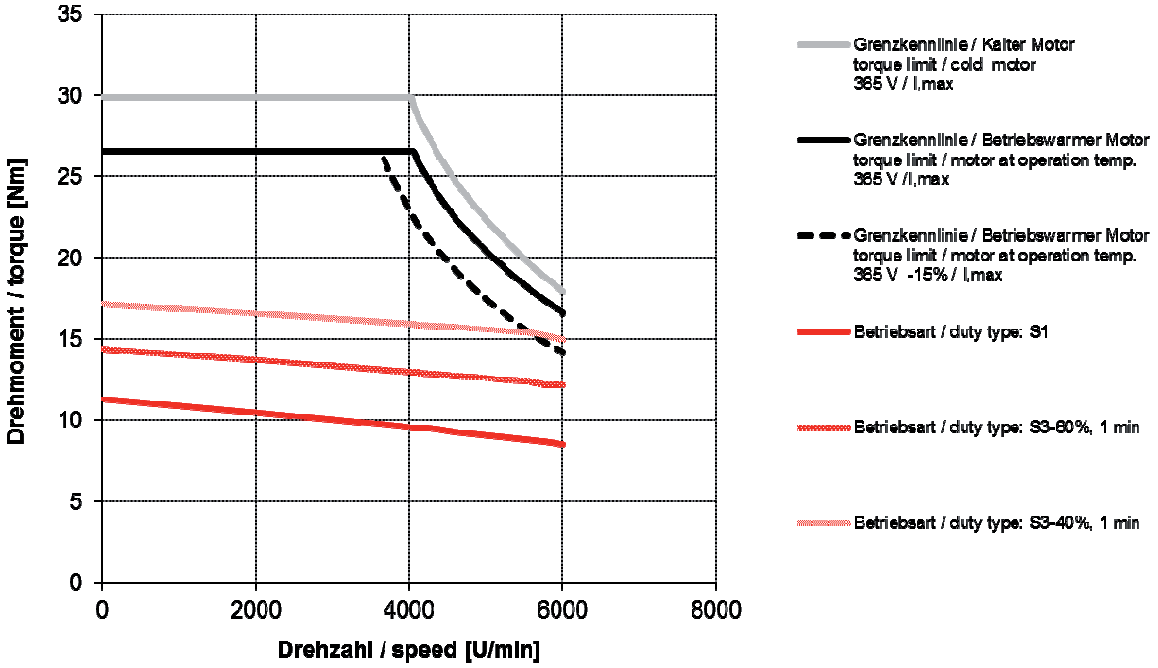


DSP1-071MO64U-60-5

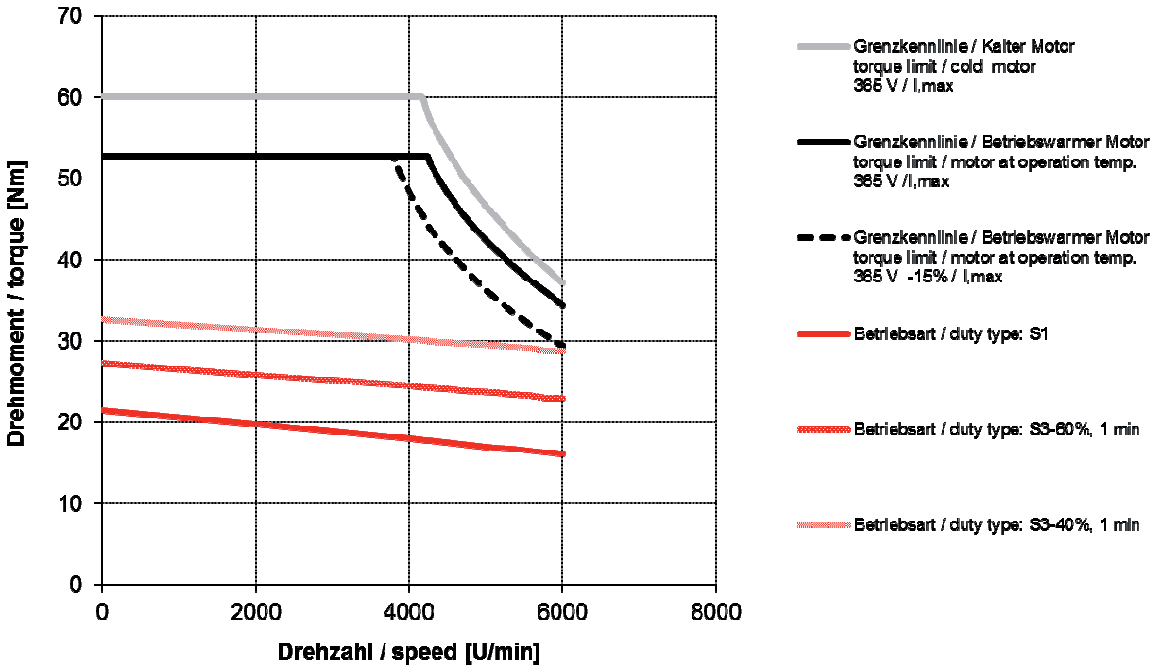


5.3.2. DSP1-071..64O-.. (with fan)

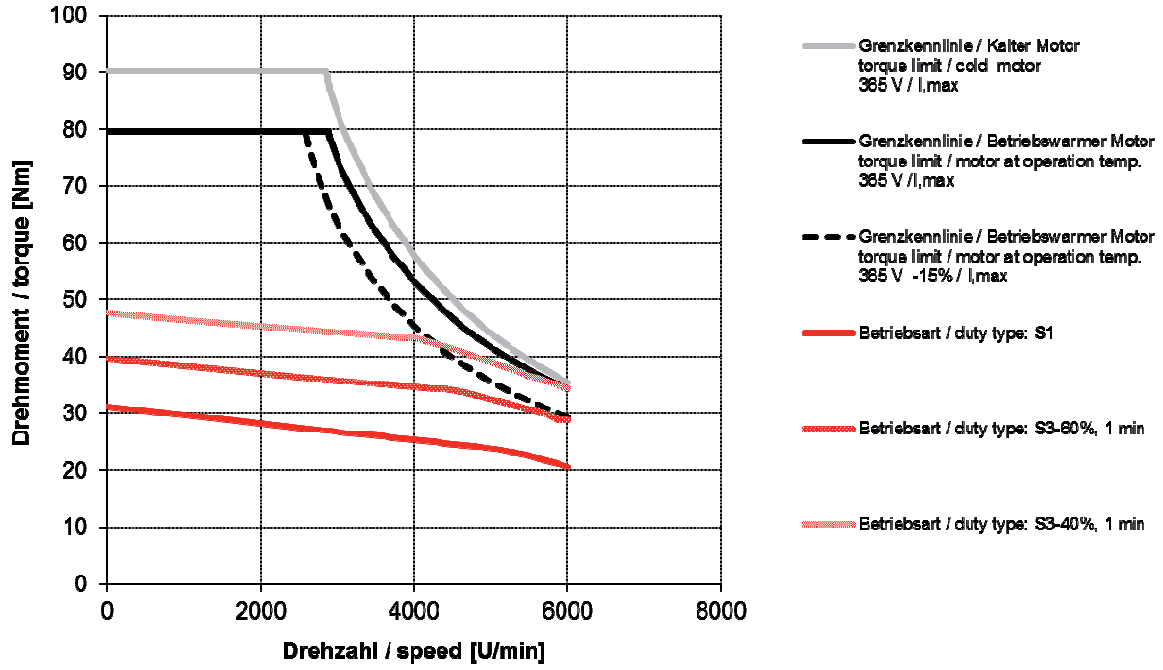
DSP1-071KO64O-60-5



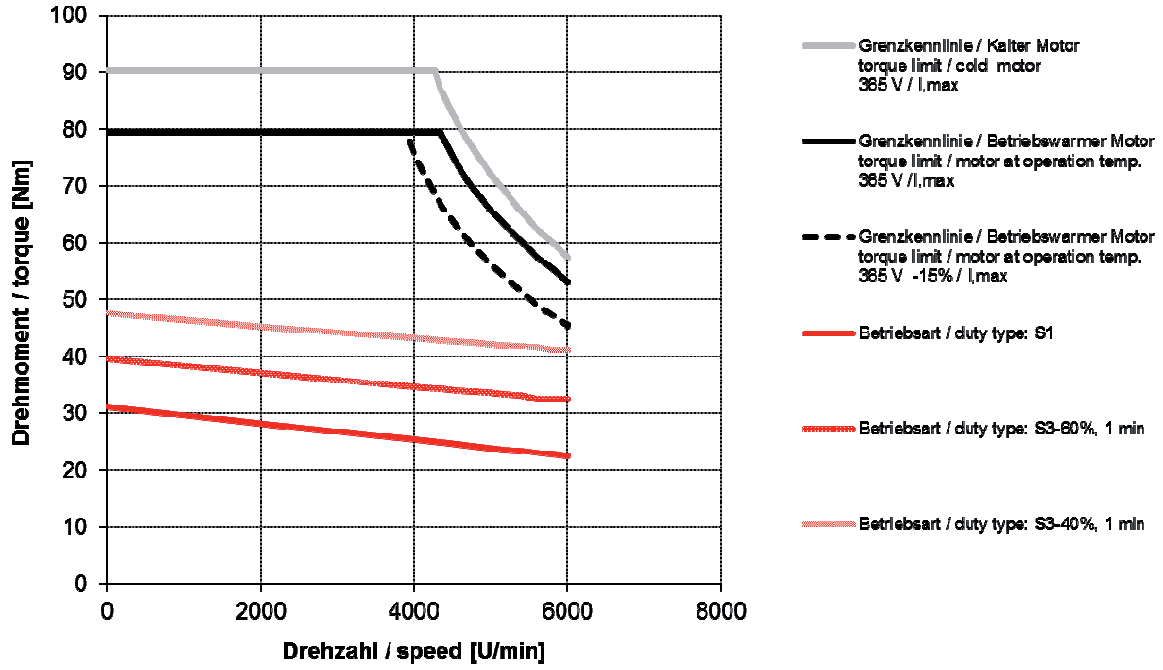
DSP1-071SO64O-60-5



DSP1-071MO64O-40-5

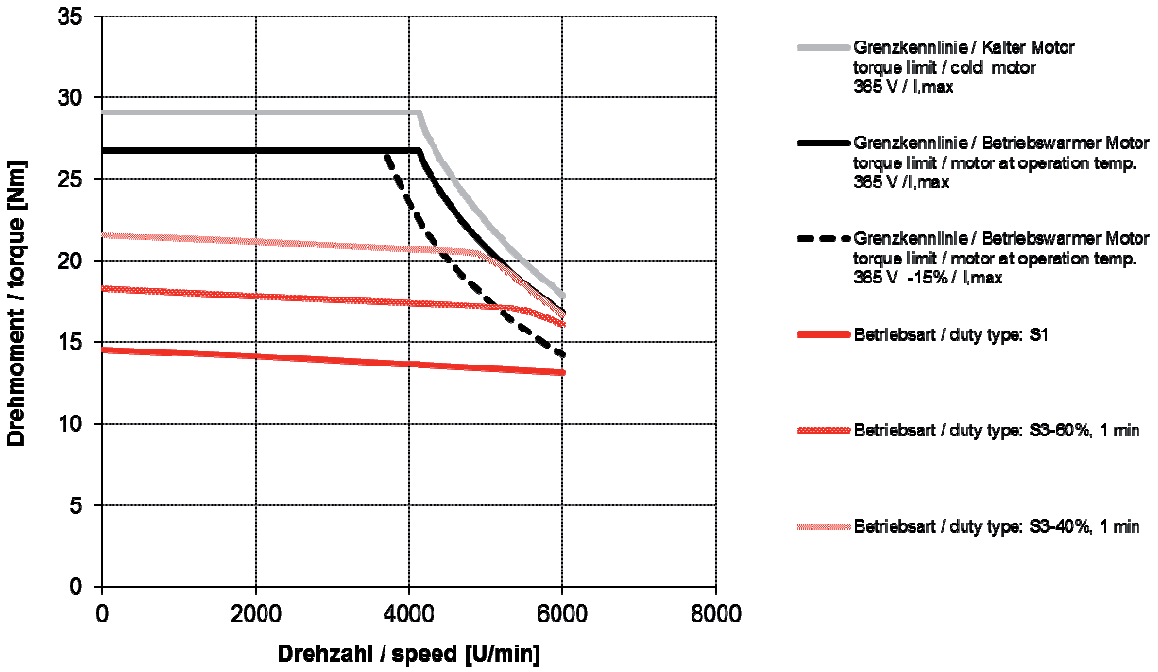


DSP1-071MO64O-60-5

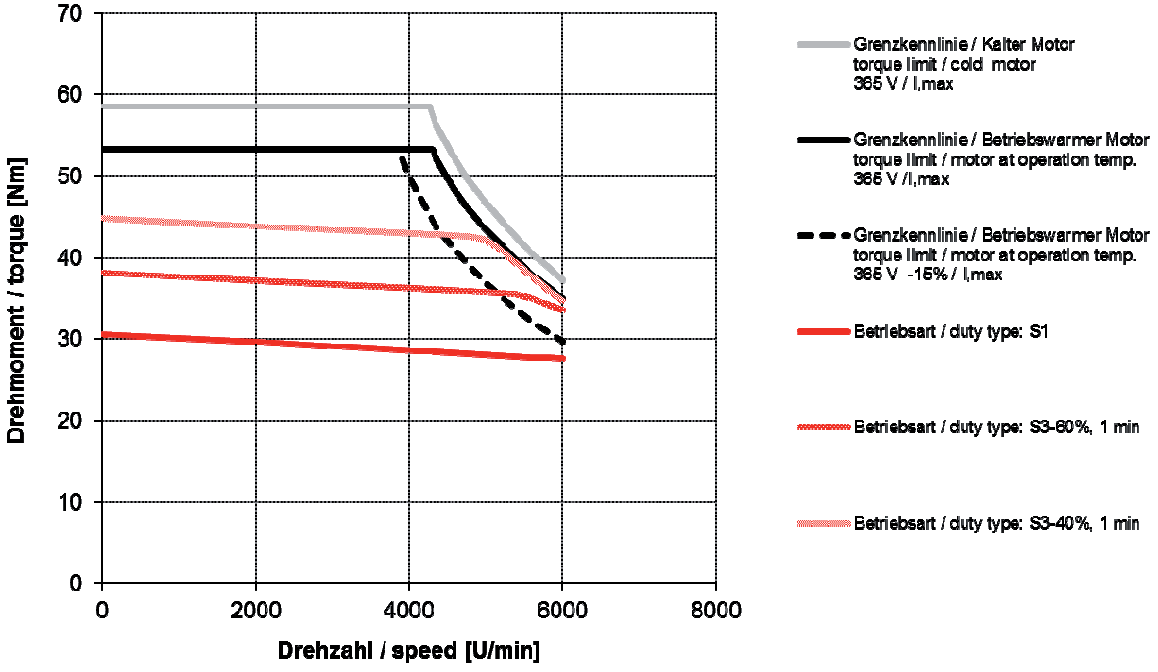


5.3.3. DSP1-071..64W-.. (water cooled)

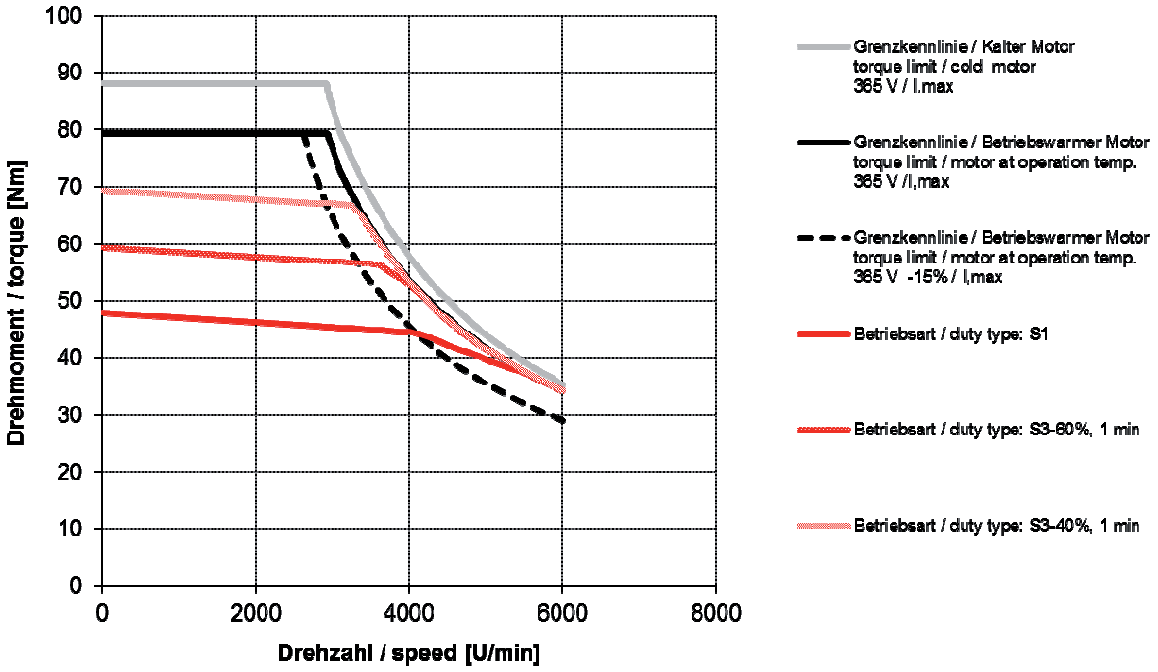
DSP1-071KO64W-60-5



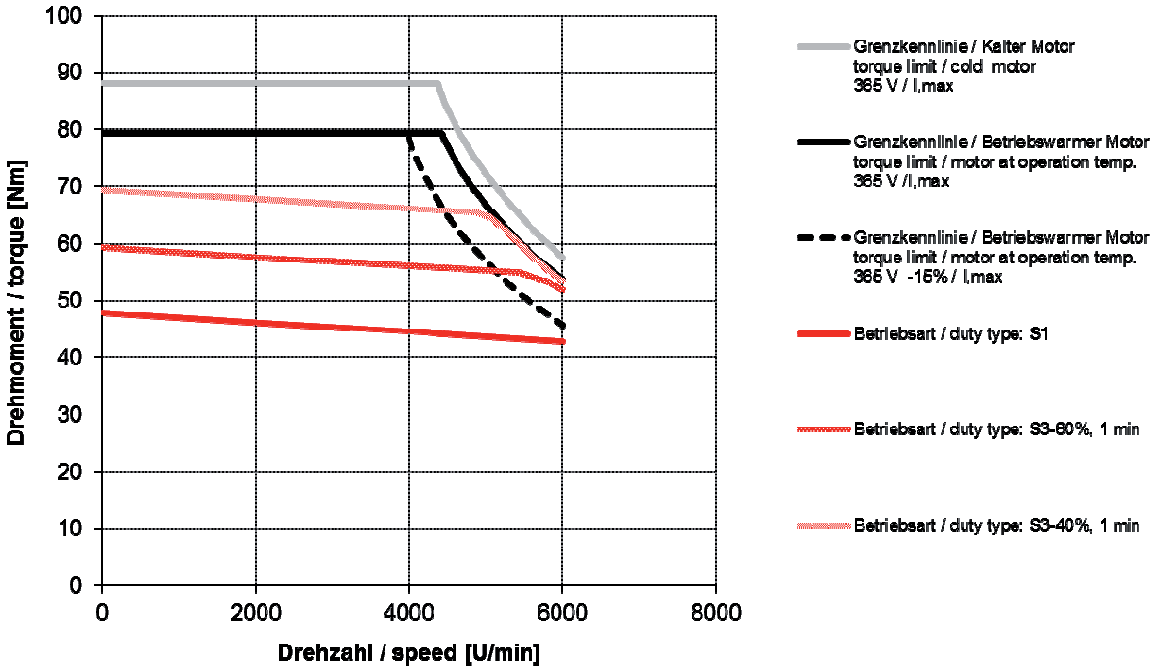
DSP1-071SO64W-60-5



DSP1-071MO64W-40-5



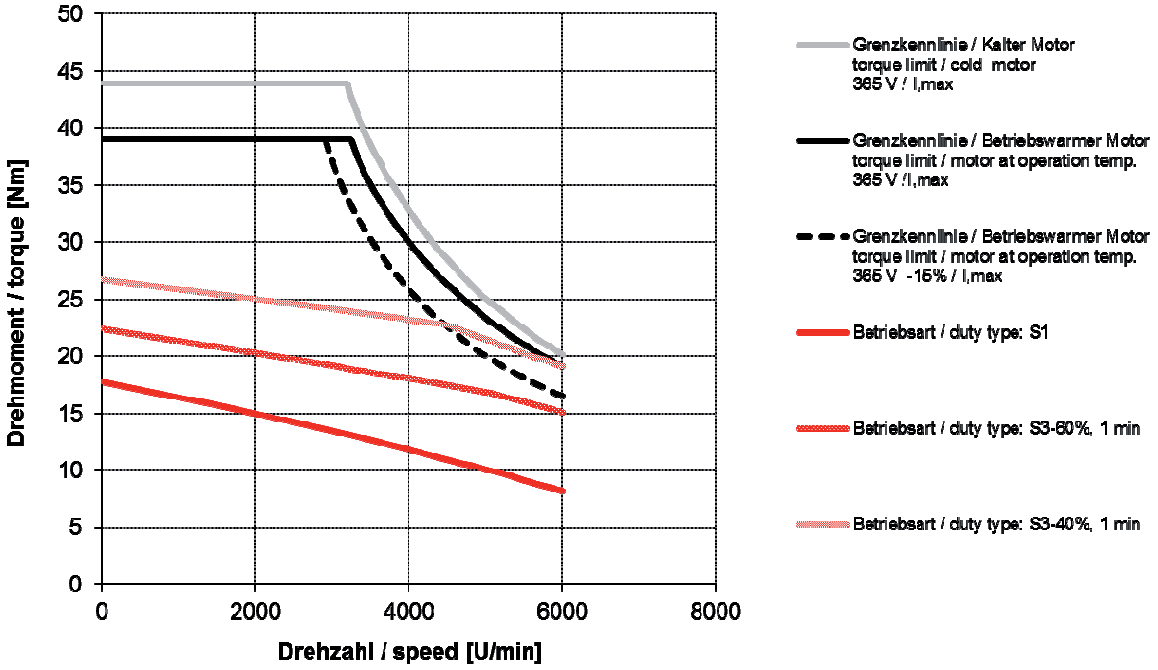
DSP1-071MO64W-60-5



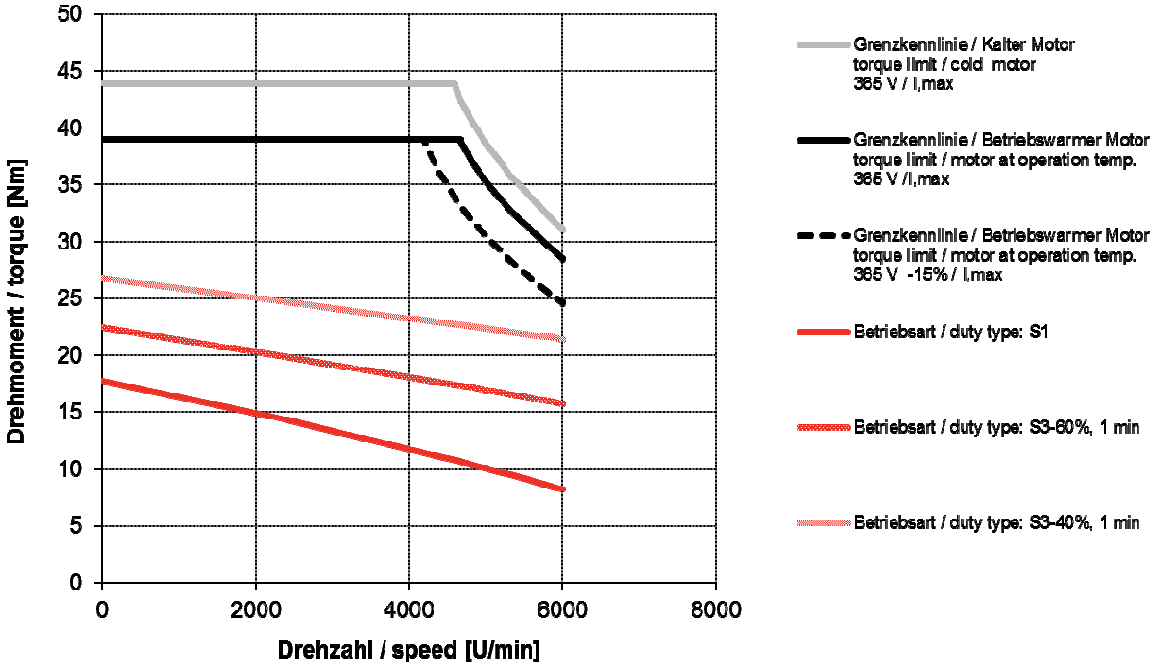
5.4. Characteristic curves DSP1-100

5.4.1. DSP1-100..64U-.. (without fan)

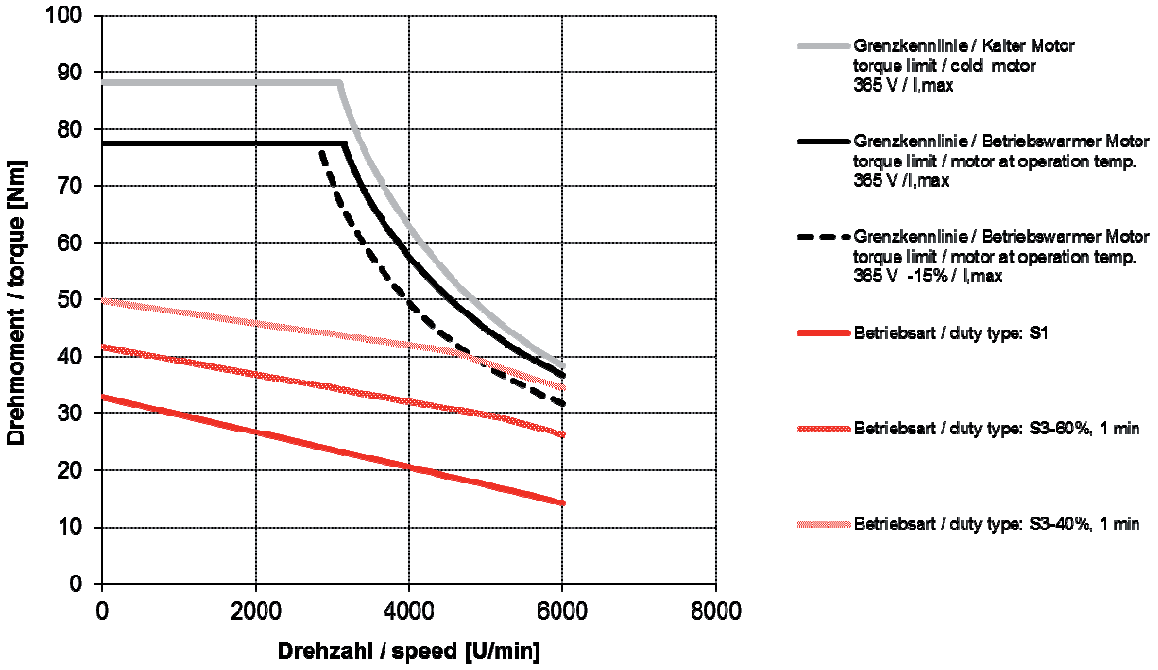
DSP1-100KO64U-40-5



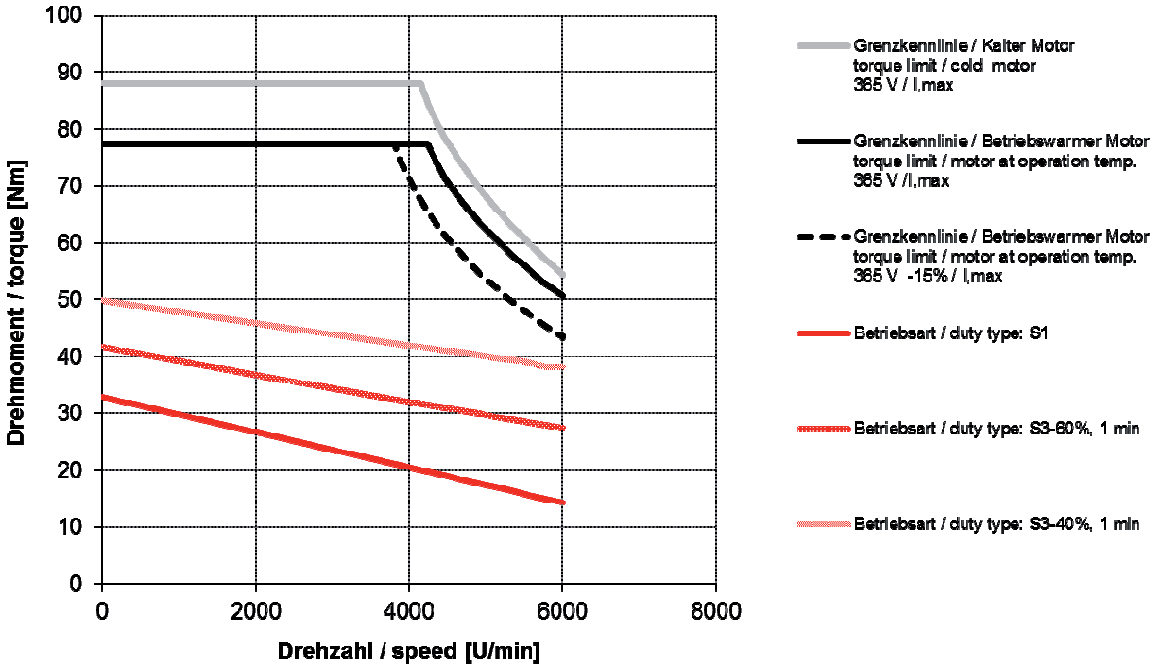
DSP1-100KO64U-60-5



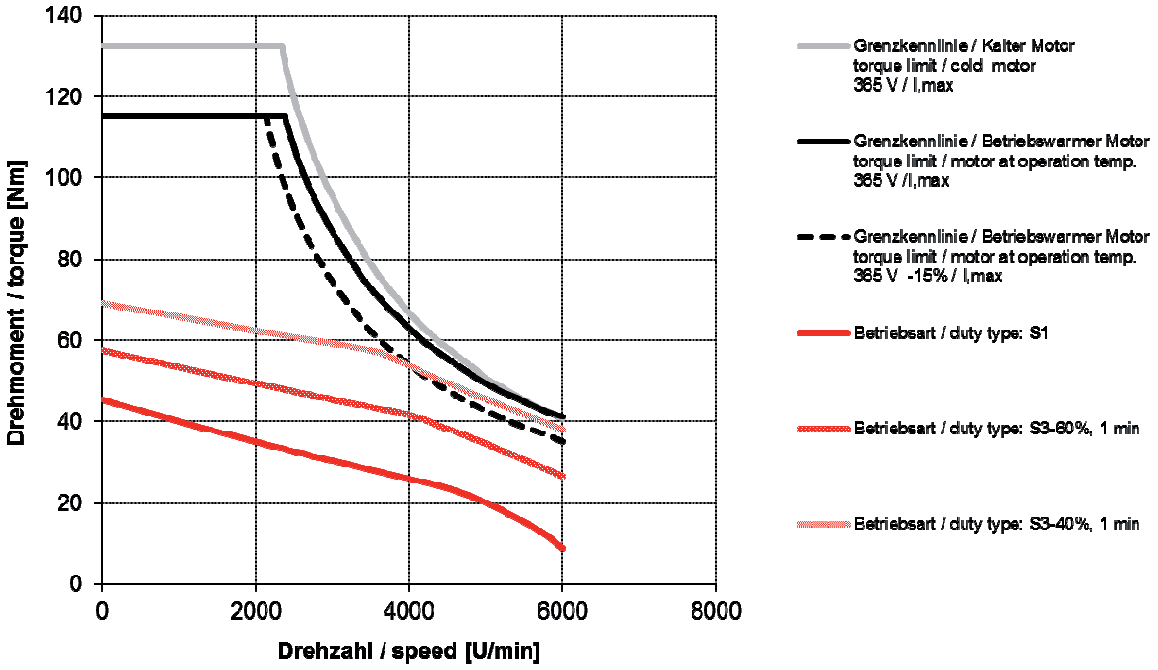
DSP1-100SO64U-40-5



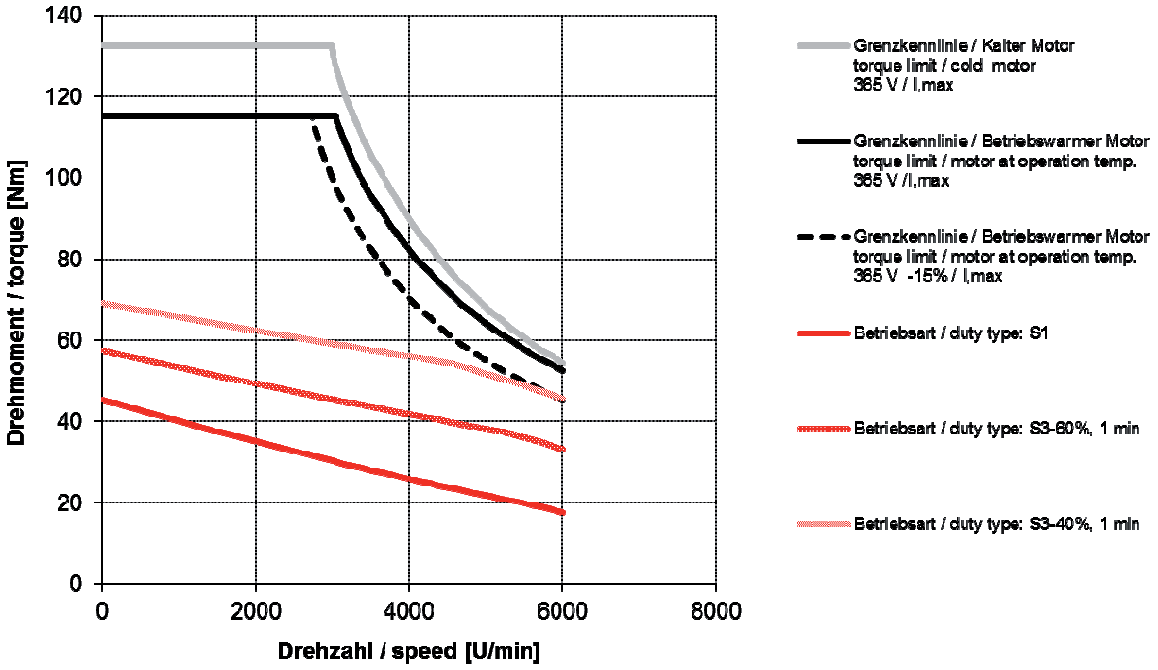
DSP1-100SO64U-60-5



DSP1-100MO64U-30-5



DSP1-100MO64U-40-5



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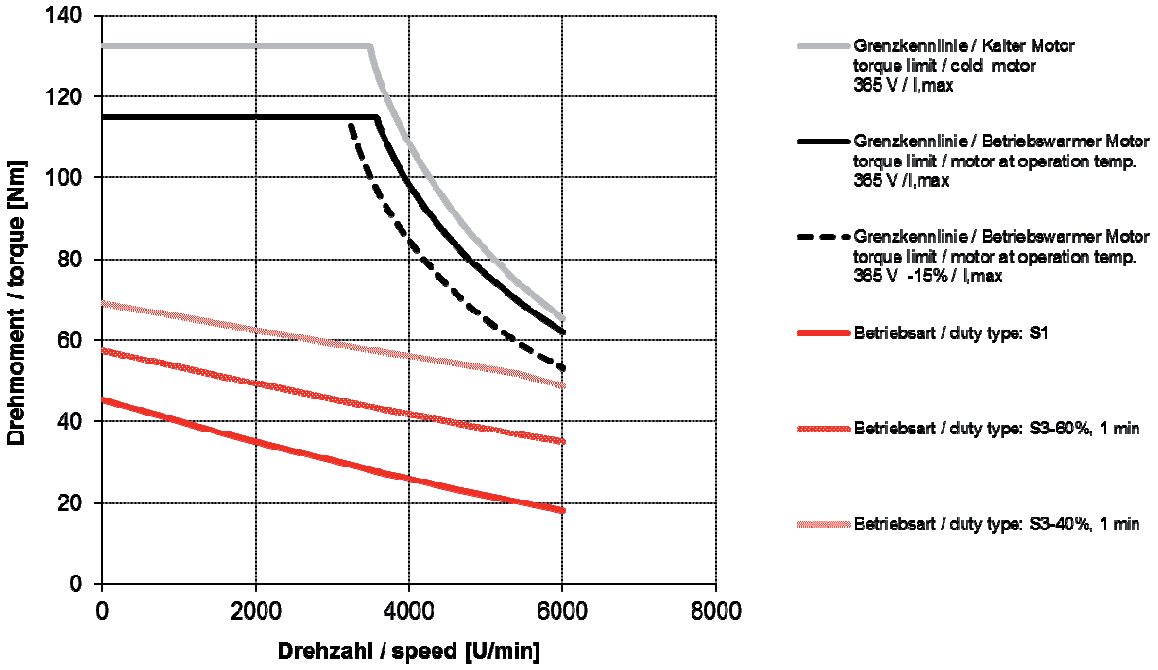

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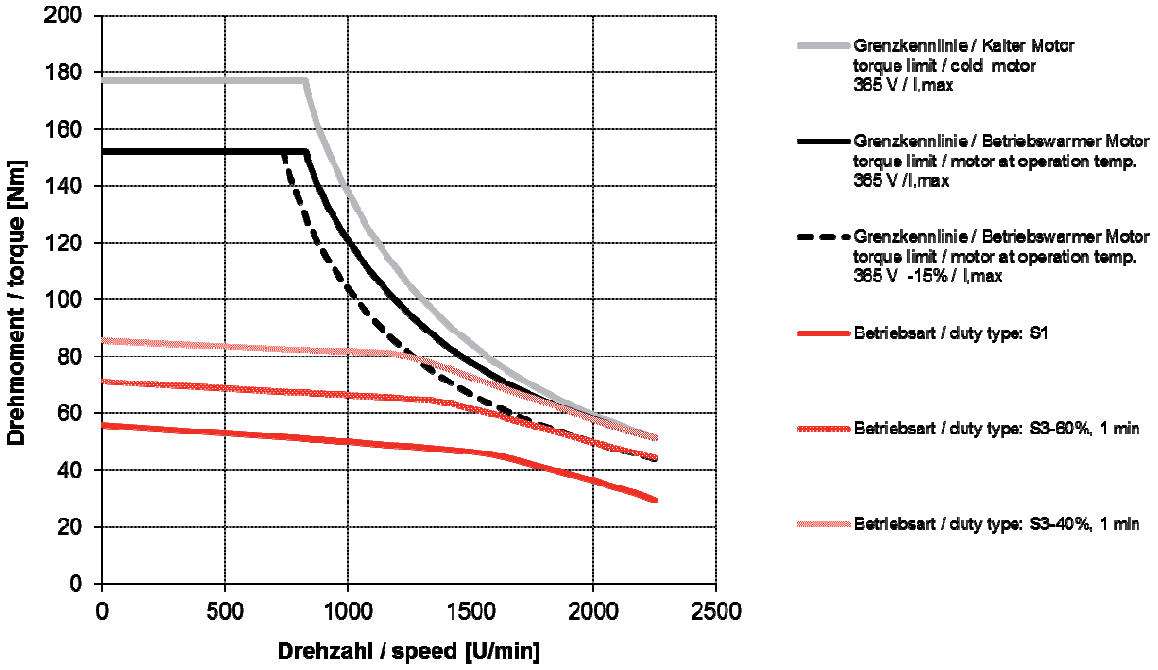

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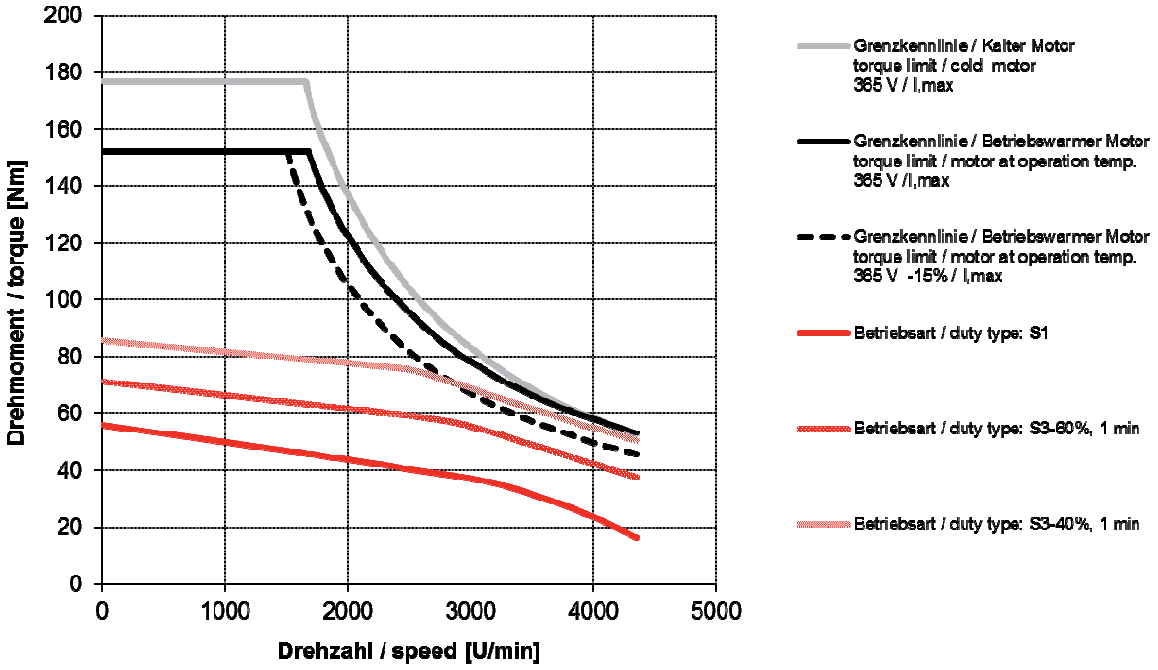

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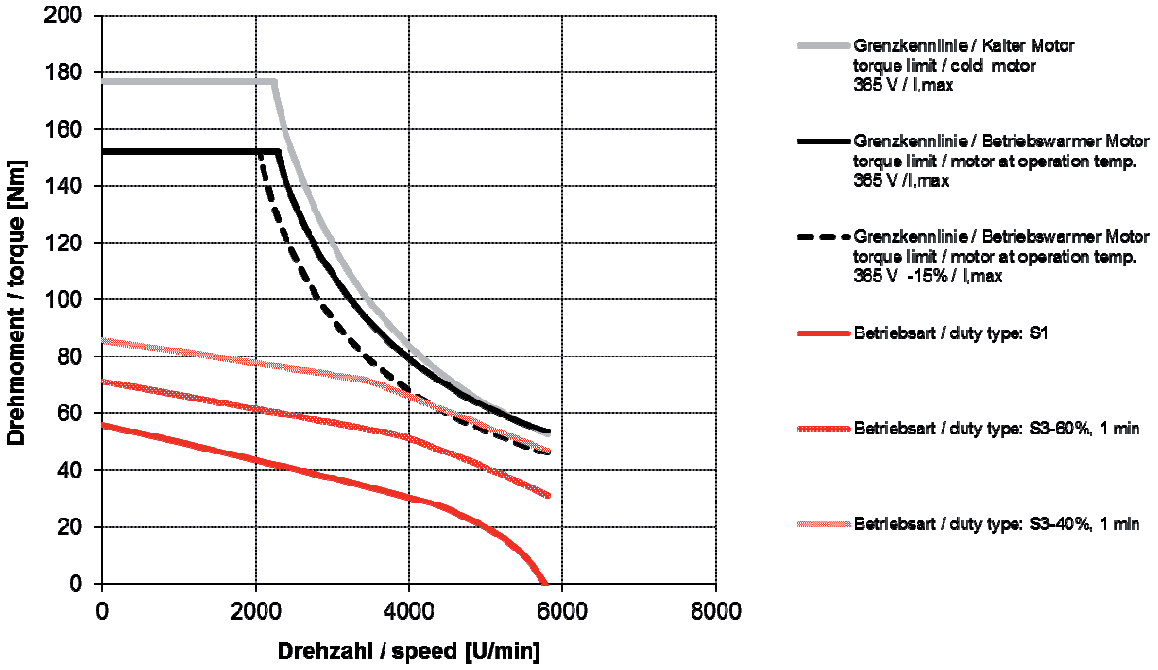

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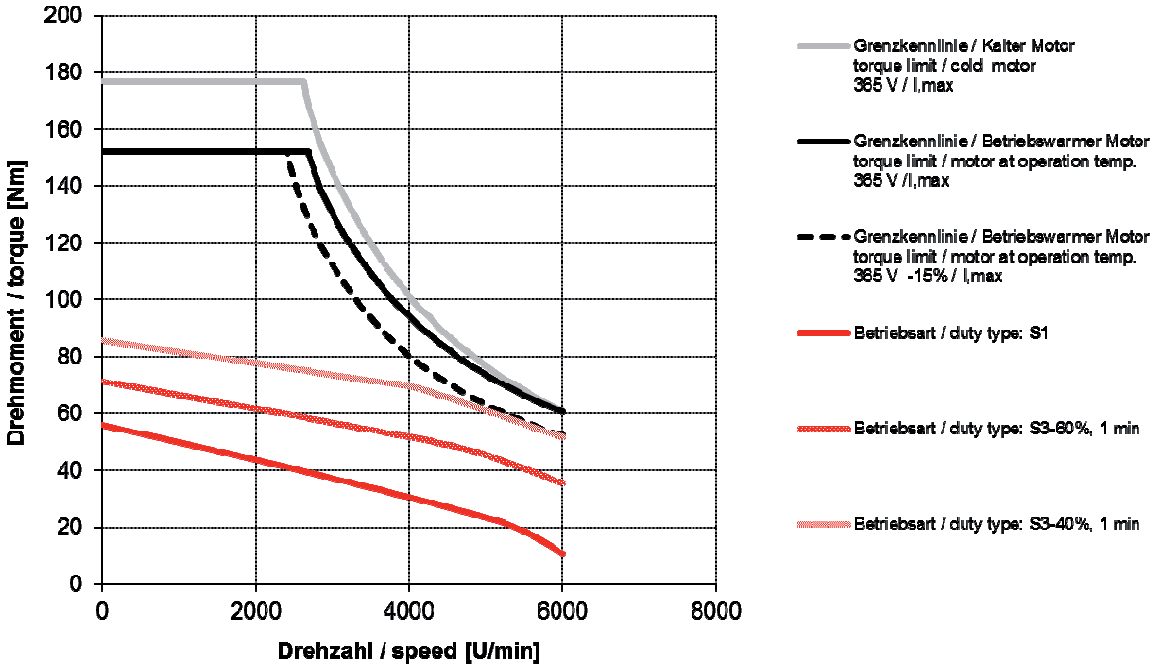
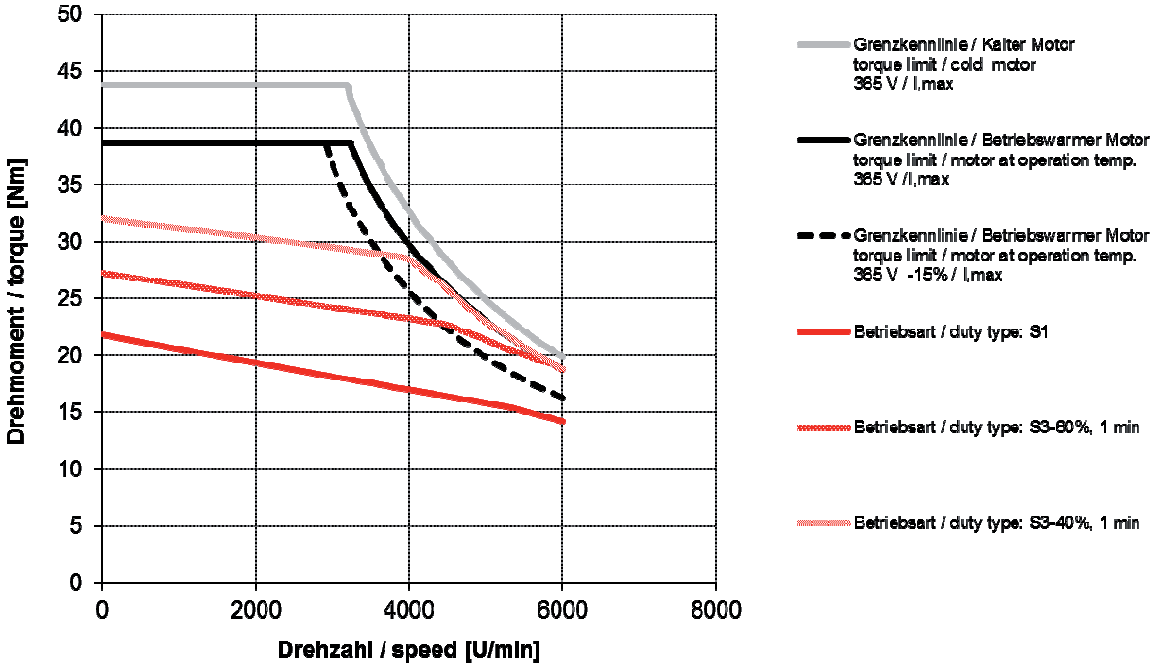


5.4.2. DSP1-100..64O-.. (with fan)

DSP1-100KO64O-40-5



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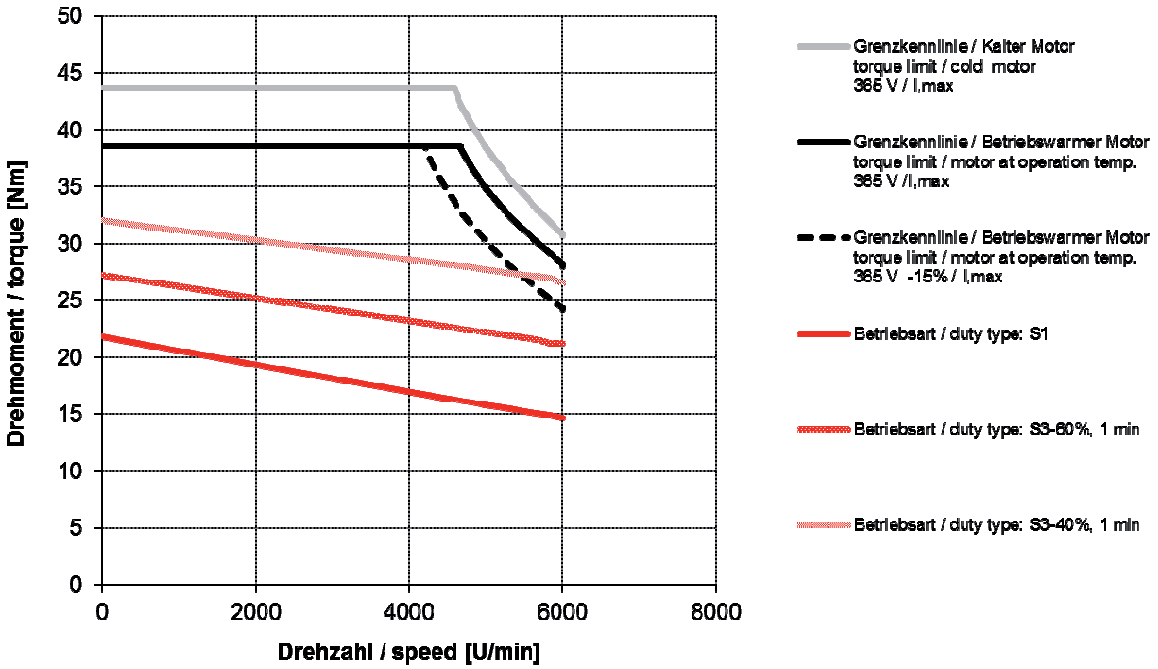
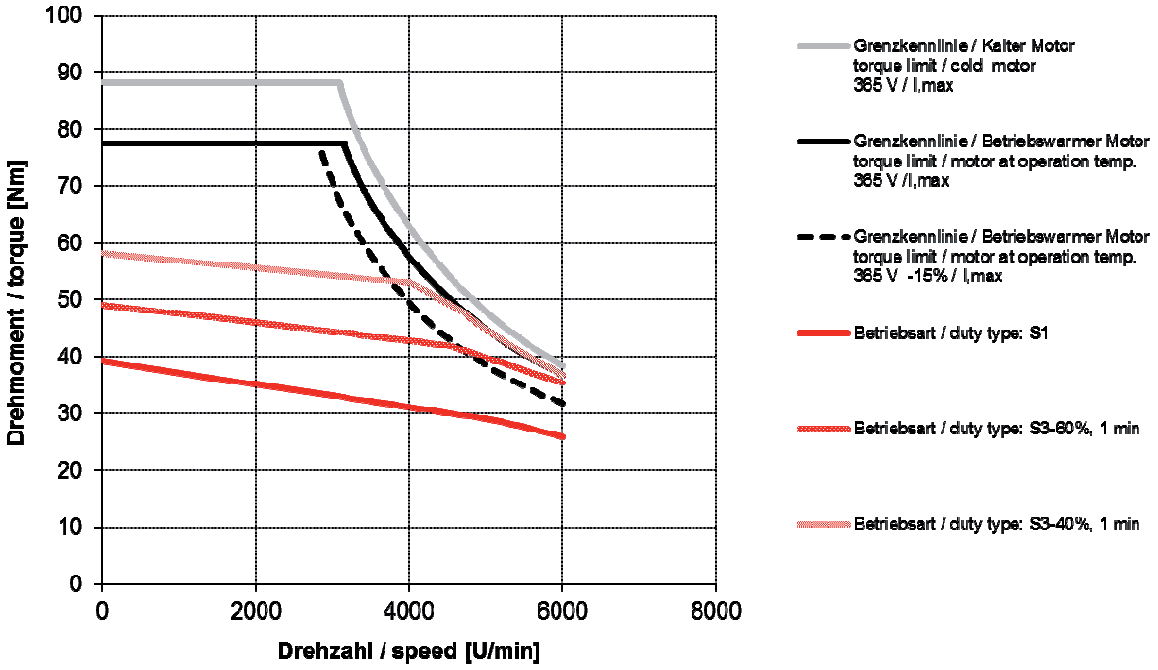


DSP1-100SO64O-40-5



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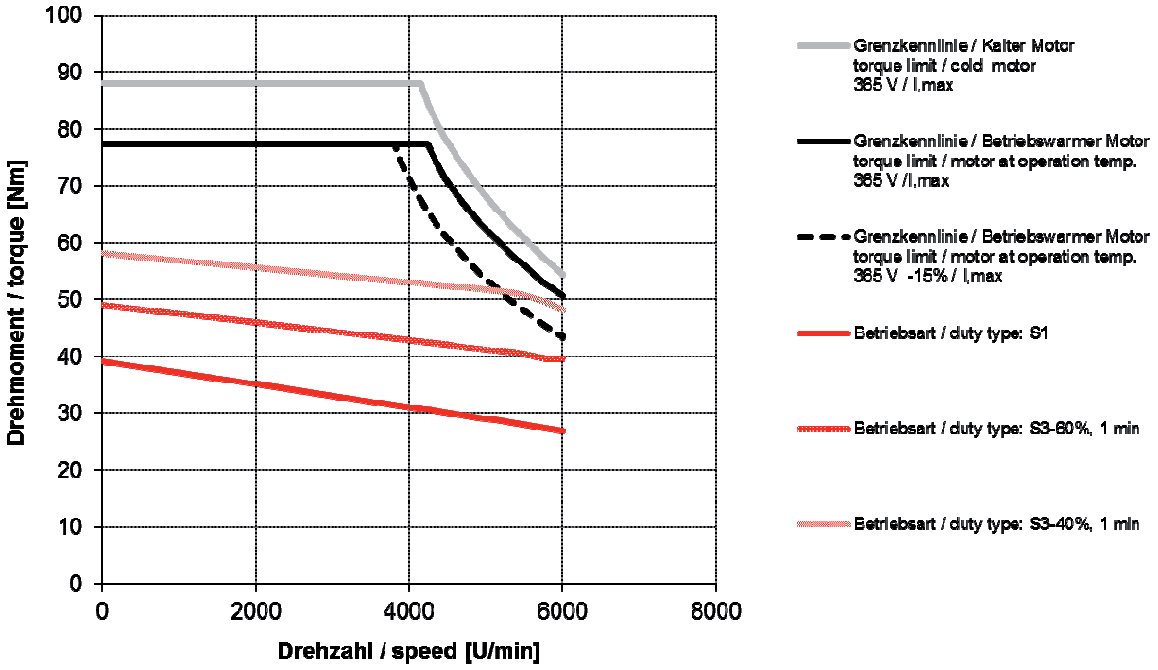

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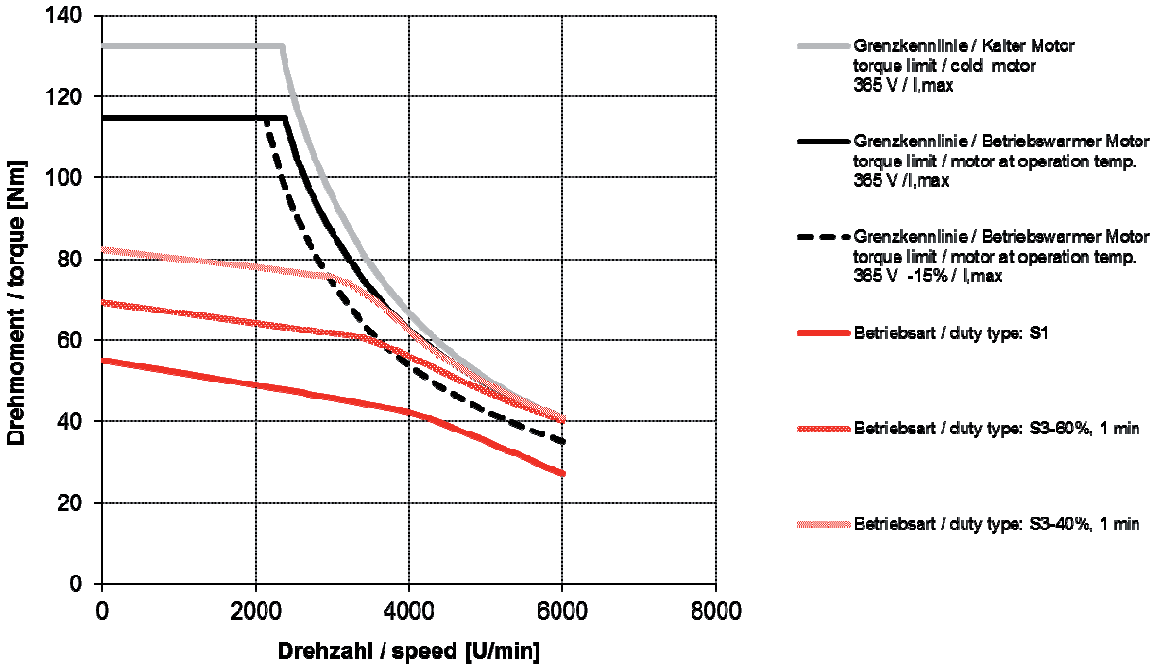

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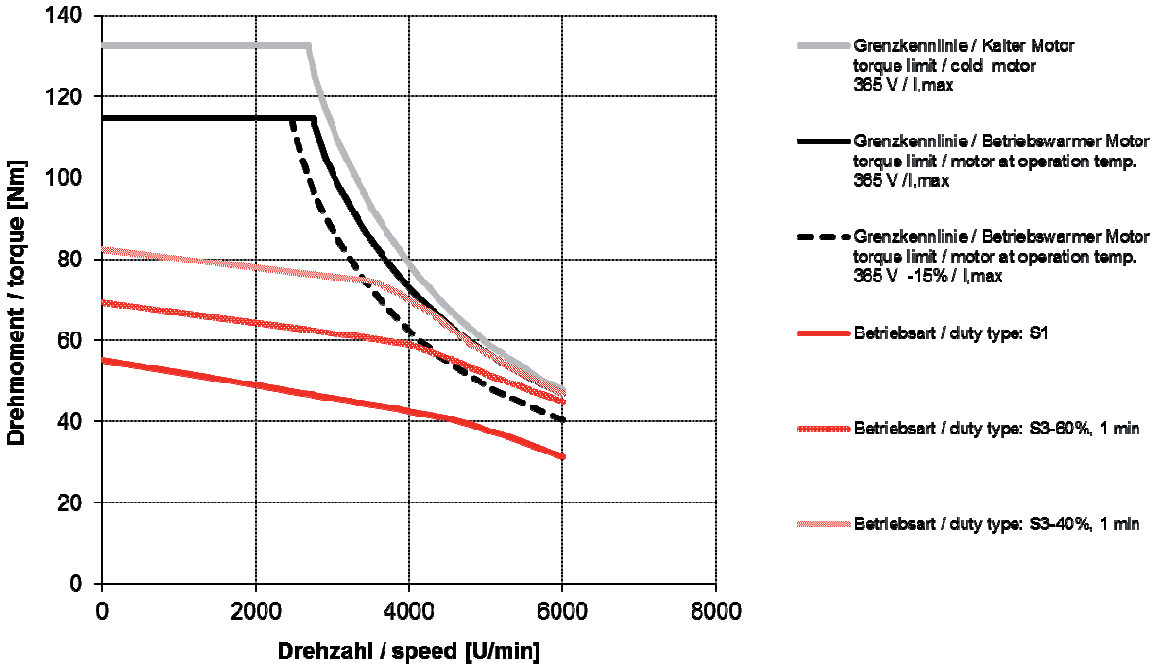

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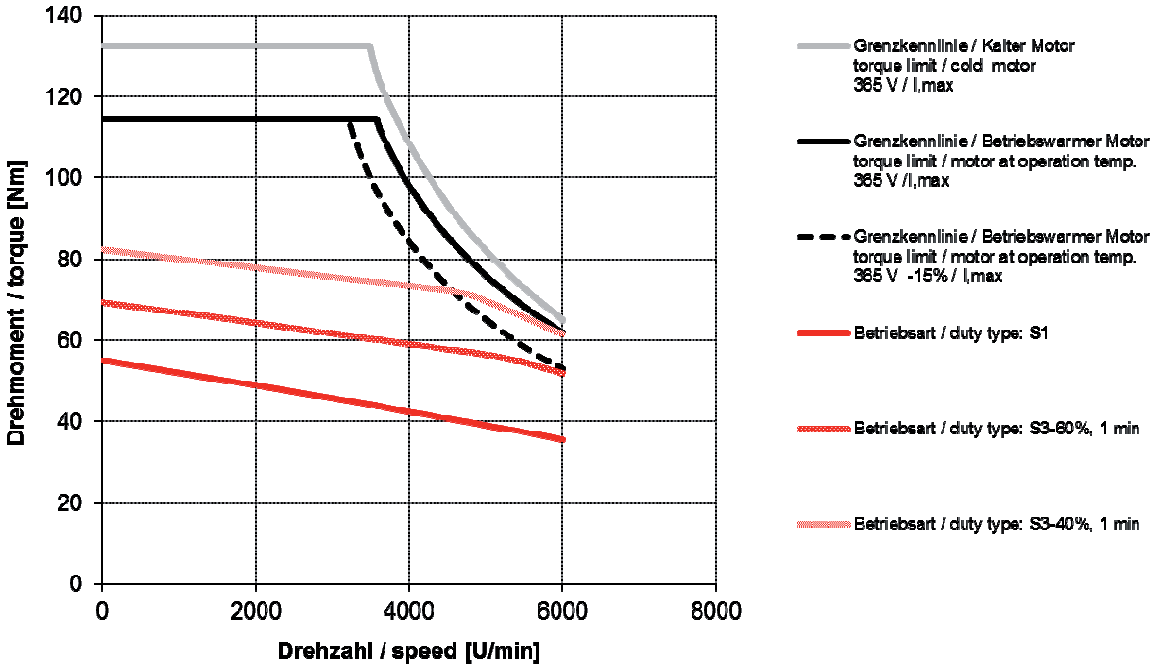

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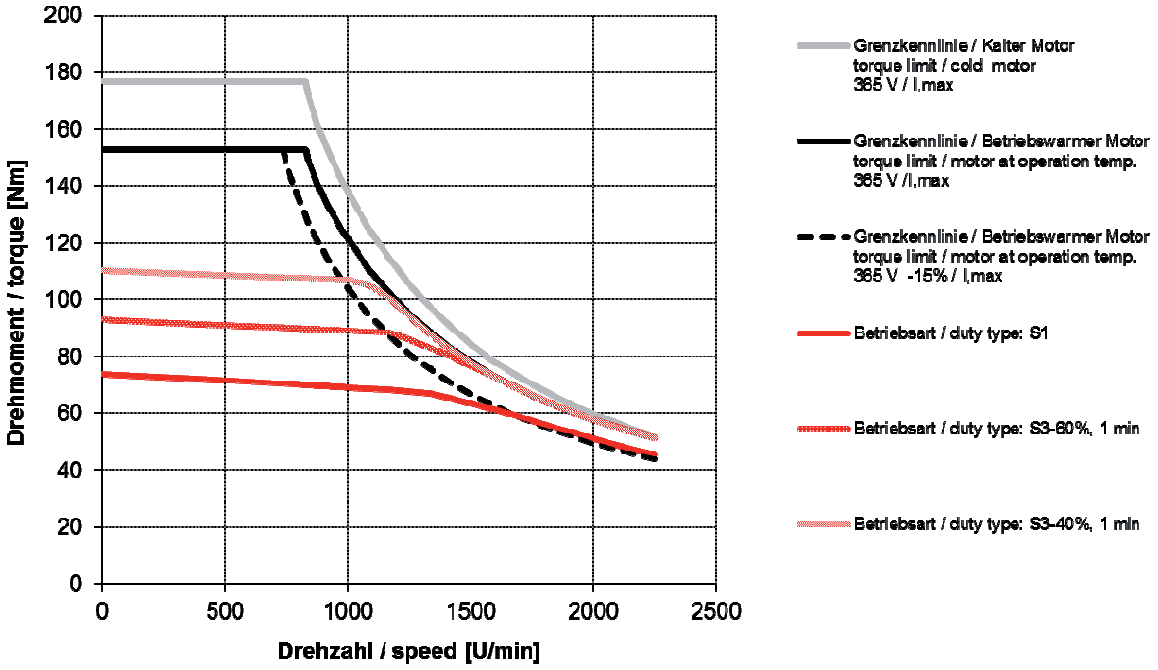

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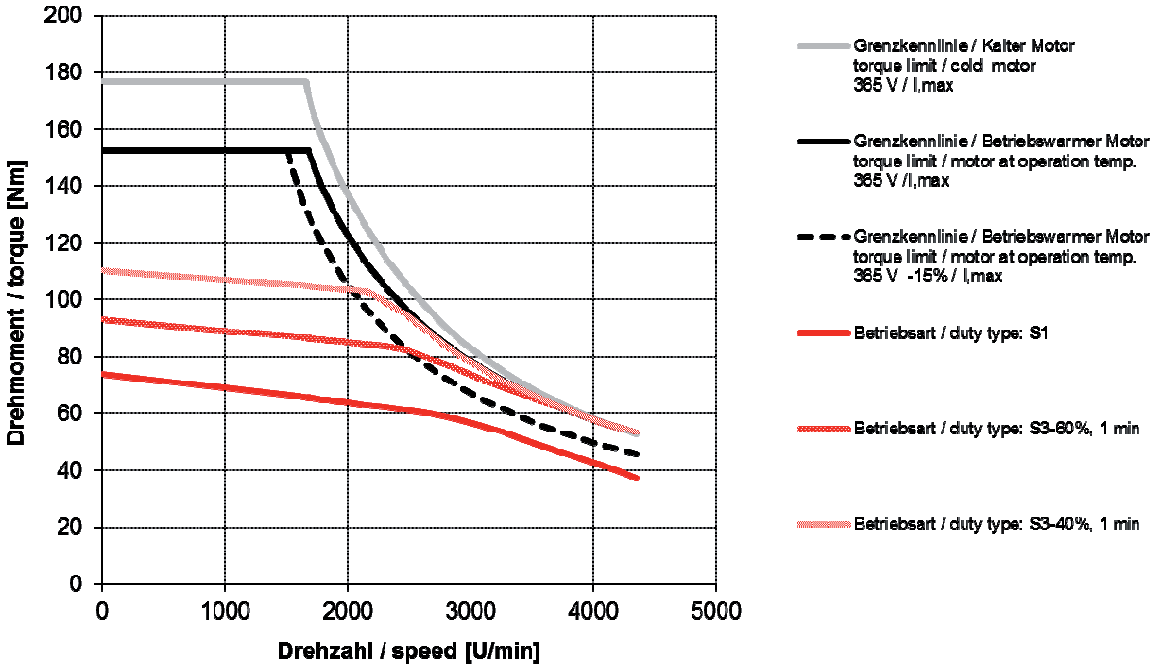

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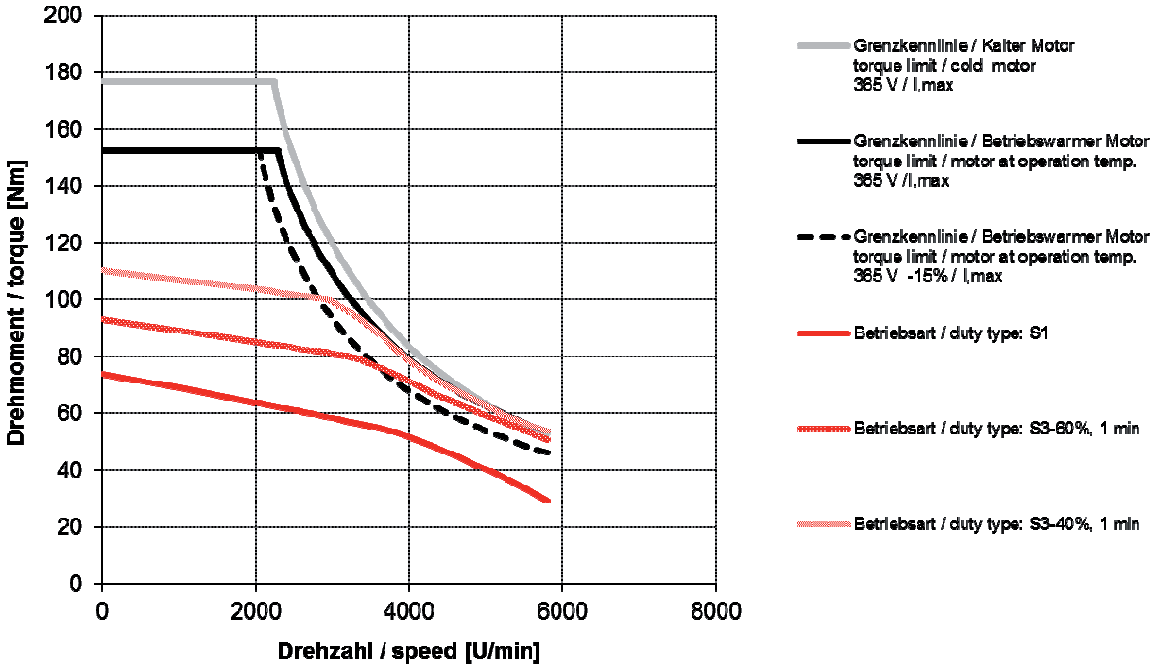

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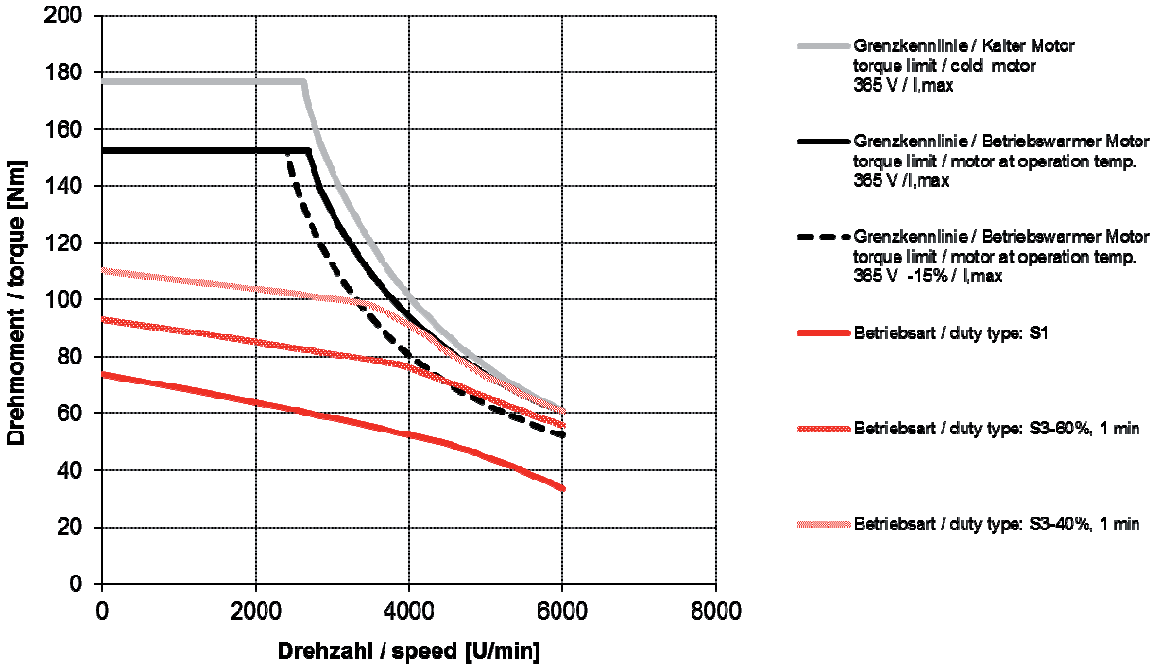
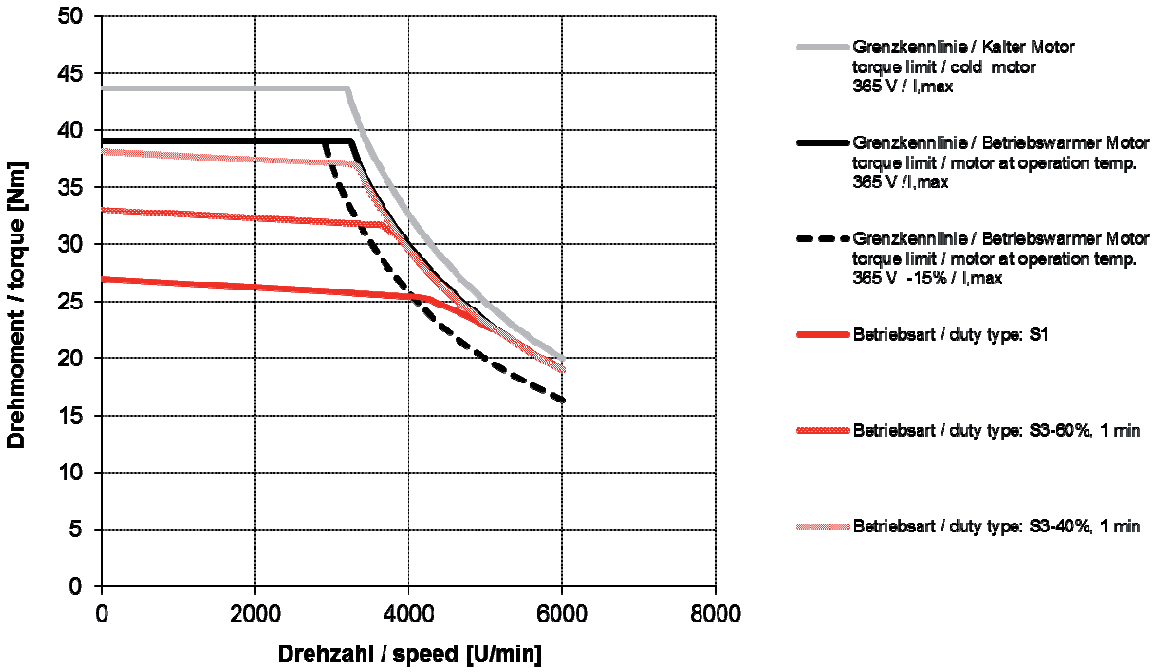


5.4.3. DSP1-100..64W-.. (water cooled)

DSP1-100KO64W-40-5



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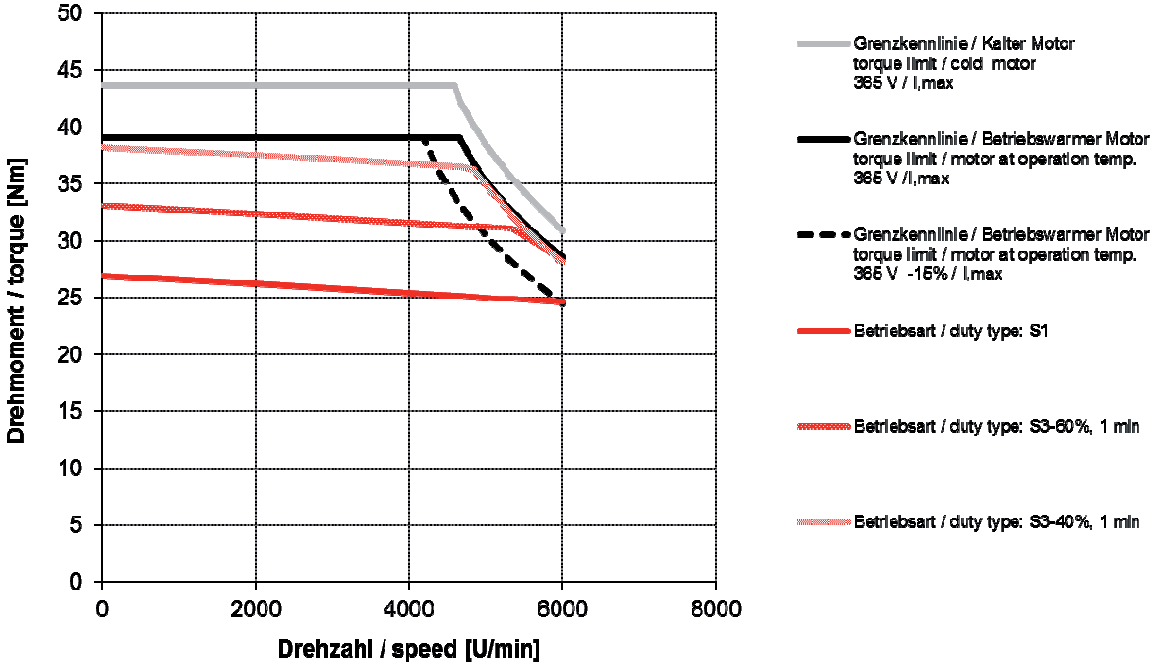

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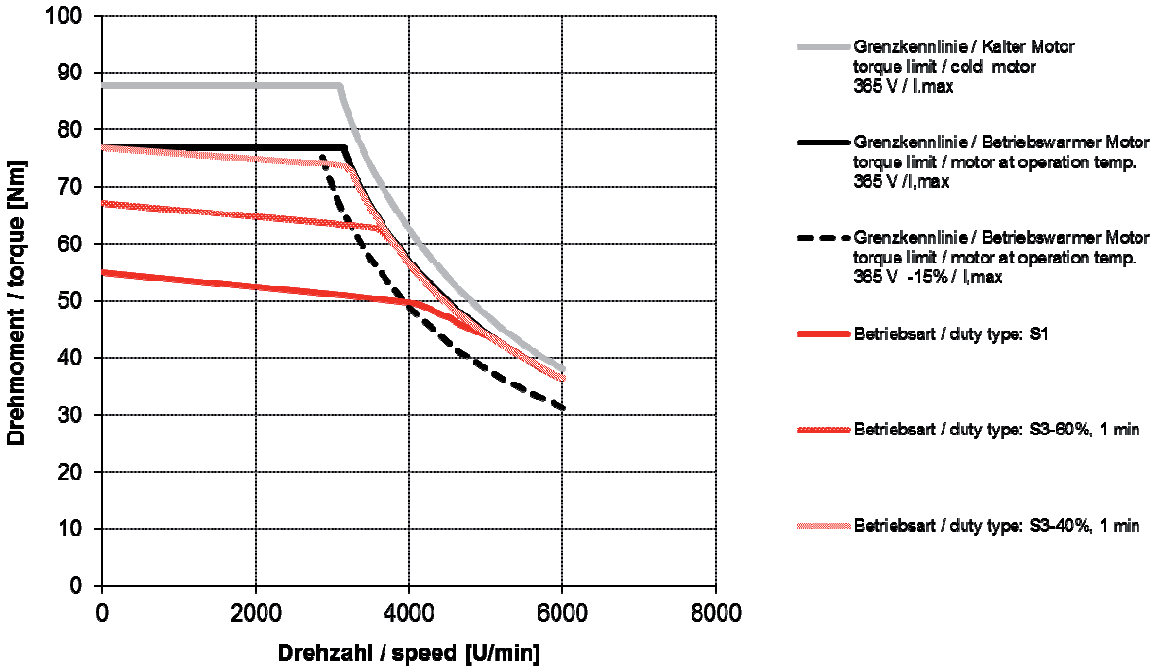

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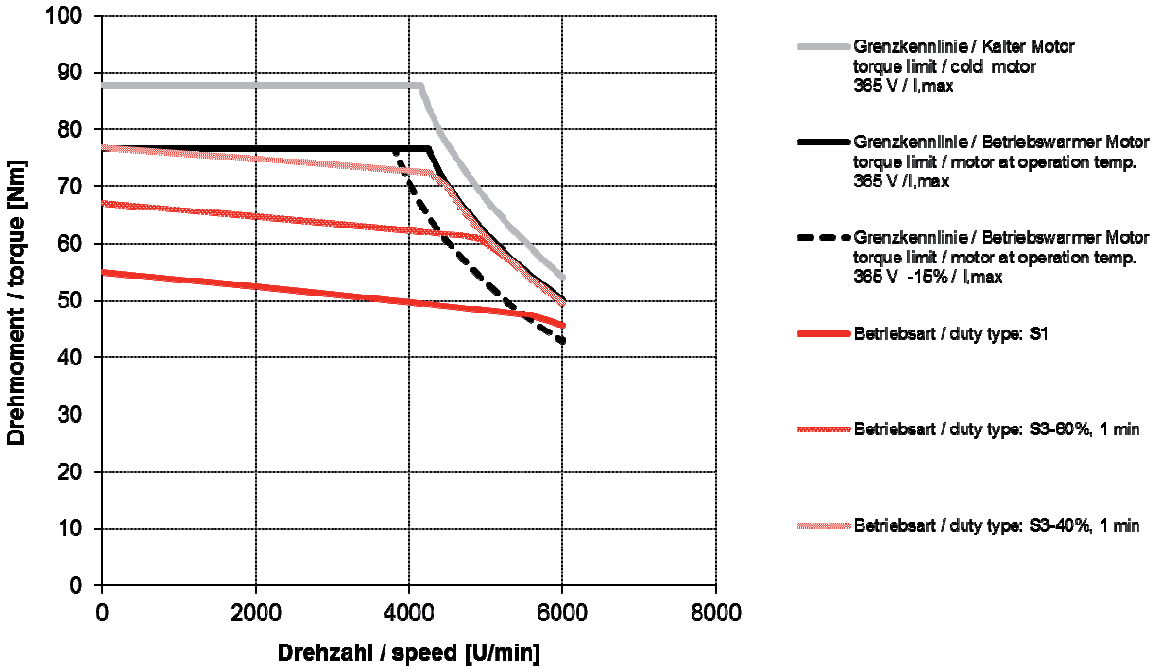

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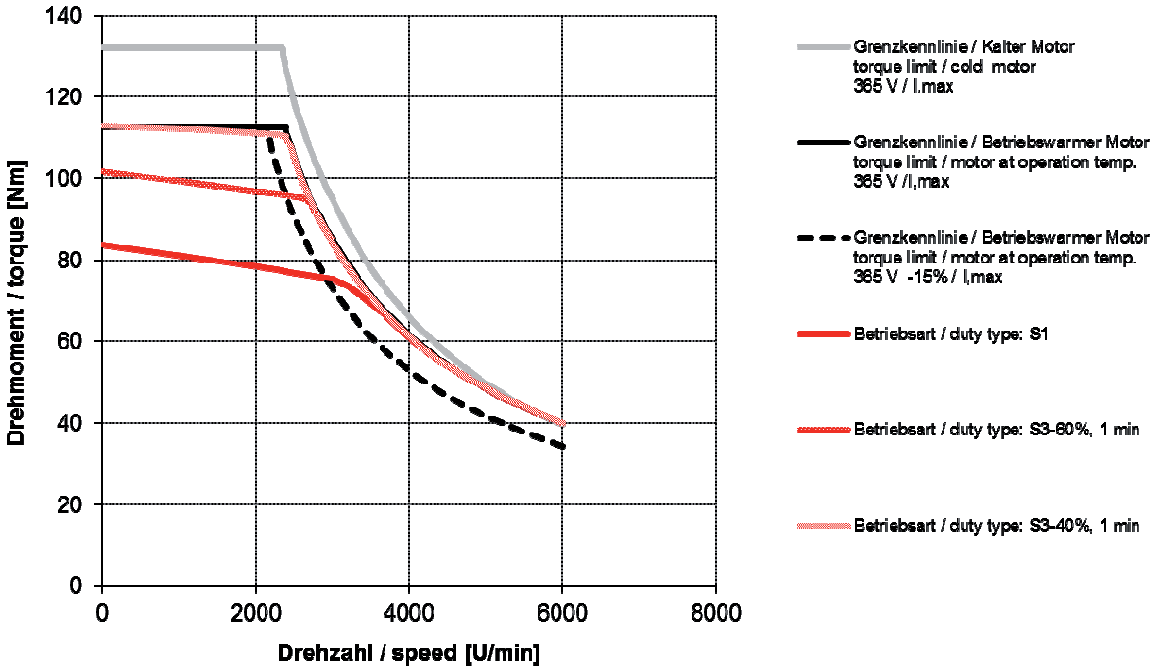

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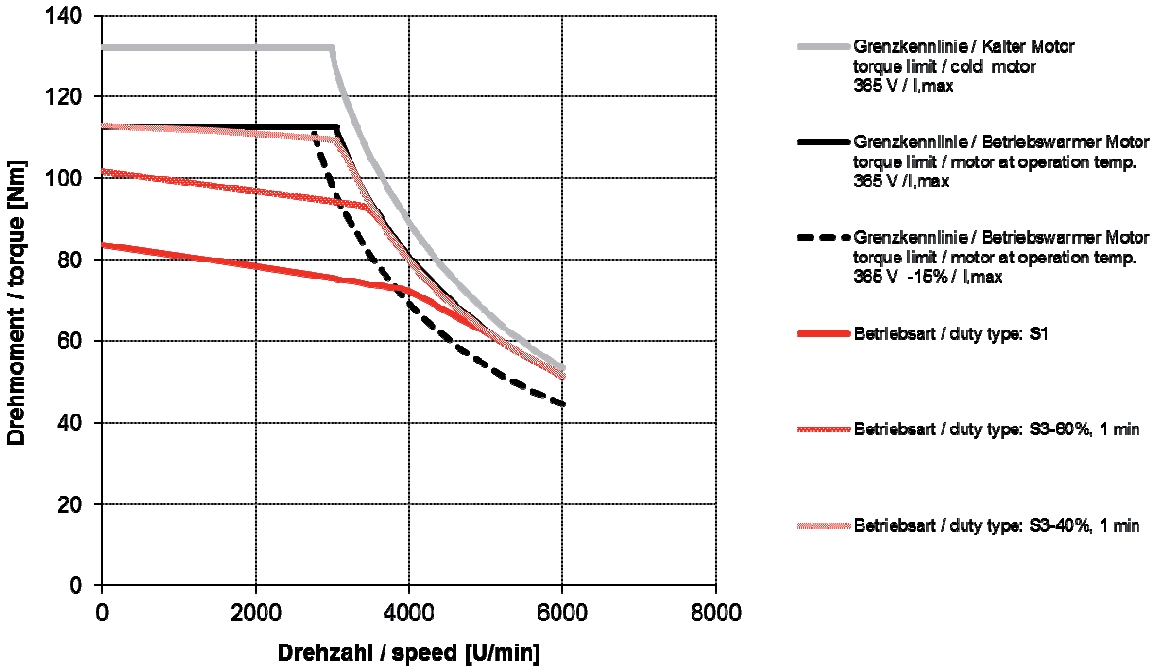

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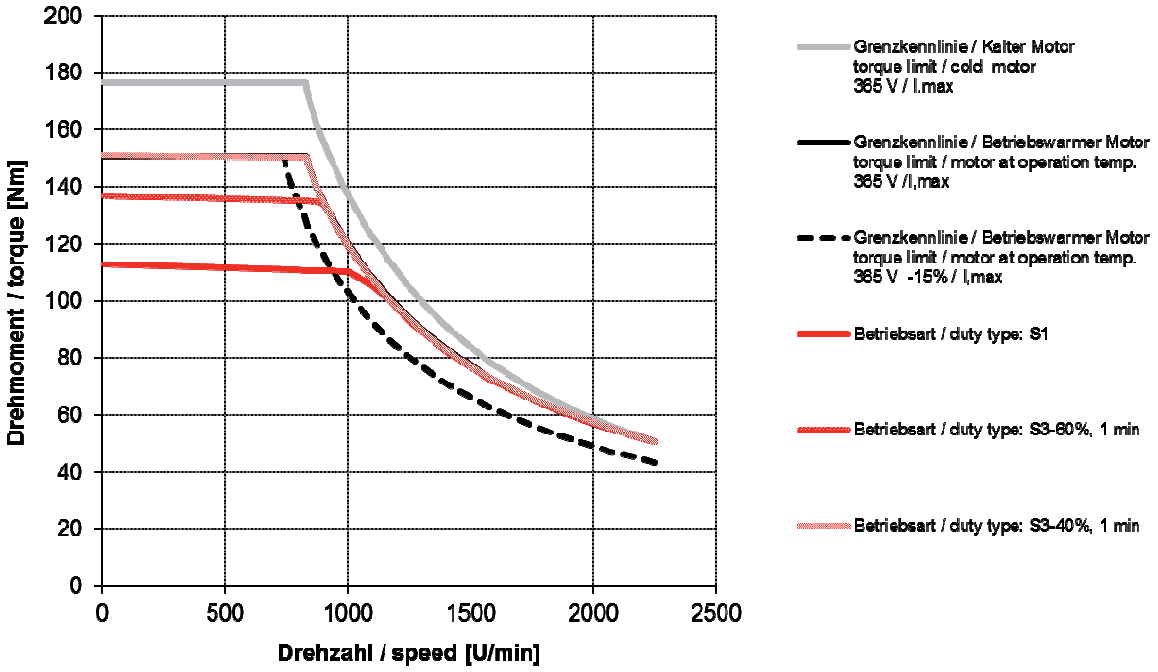

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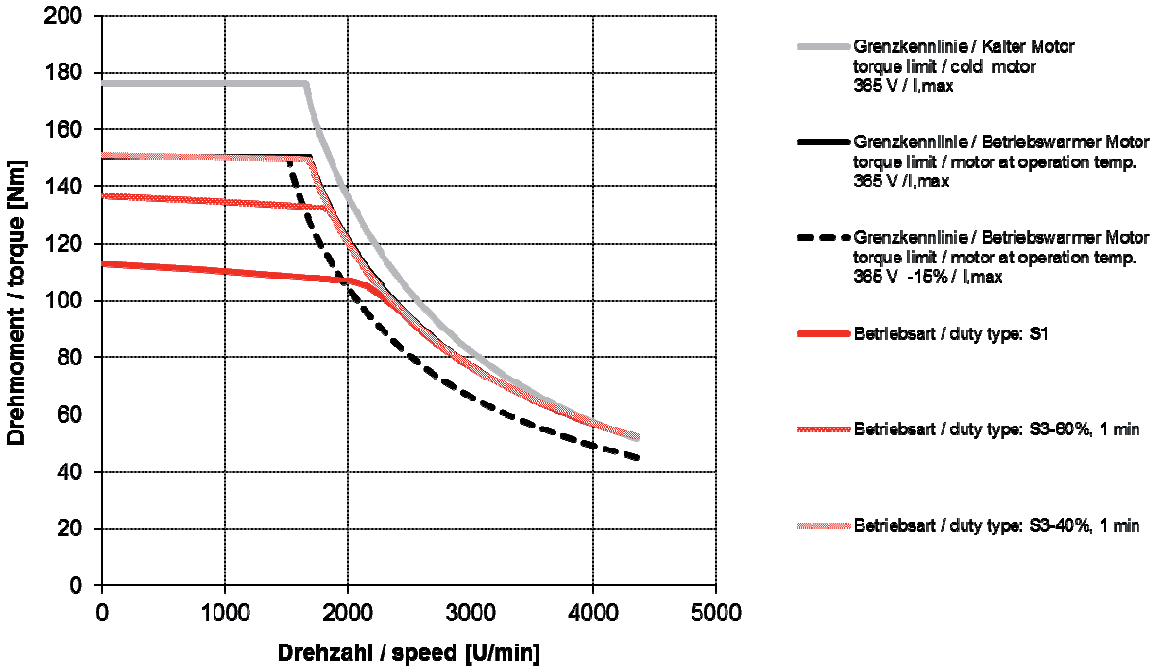
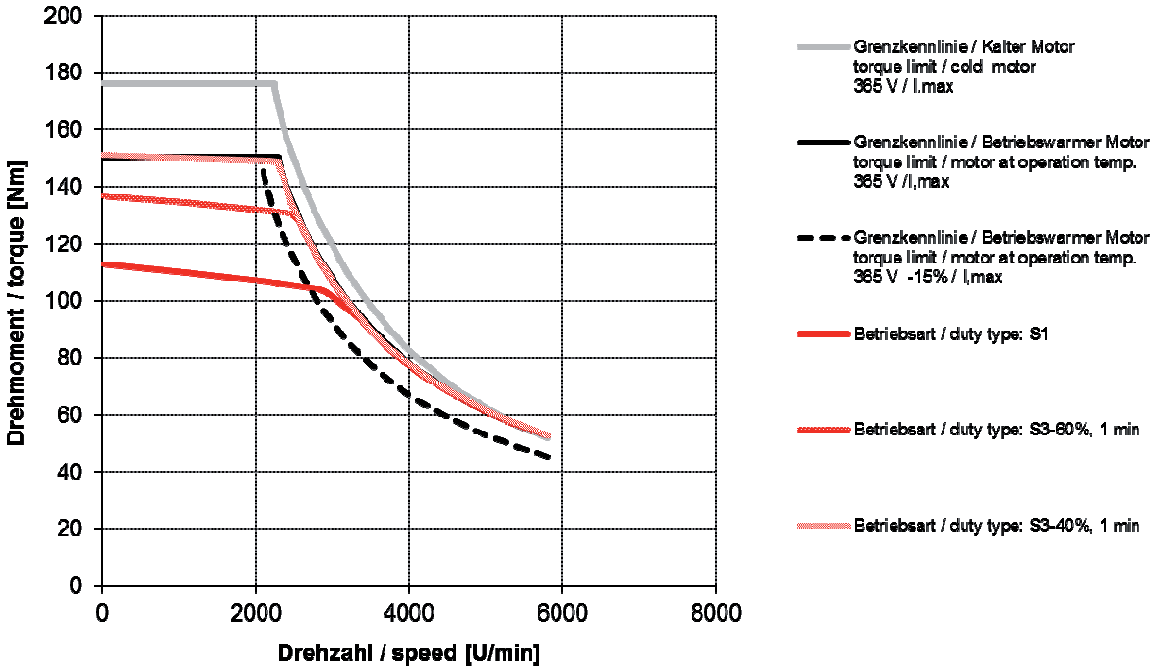


DSP1-100LO64W-30-5



6. Commissioning and maintenance instructions

For information on commissioning the motors, please request a copy of our commissioning and maintenance instructions, quotion number 00682,

7. Declaration of Conformity

This chapter contains general information on EC Directives, the CE marking and the Declaration of Conformity,

7.1. What is an EC Directive?

EC Directives stipulate specific requirements, The Directives are compiled by the corresponding organisations within the EU and transposed by all EU member states into national law to guarantee free trade within the European Union,

An EC Directive only outlines basic minimum requirements, More detailed requirements are included in standards to which the Directive makes direct reference,

7.2. What does the CE marking signify?

a) The CE marking symbolises conformity to all the obligations incumbent on manufacturers for the product by virtue of the Community Directives providing for its affixing,

b) The CE marking affixed to industrial products symbolises the fact that the natural or legal person having affixed or been responsible for affixing the said marking has verified that the product conforms to all Community provisions for total harmonisation which apply to it and has been the subject of the appropriate conformity evaluation procedures,

Council Decision 93/465/EEC, appendix I B, a) + c)

We affix the CE marking to the device and include it in the documentation as soon as we have established that the product fulfils the requirements outlined in the relevant Directives,

If this Baumüller product is used in your machine as specified, you can assume that the product satisfies the requirements stipulated in 2006/95/EC,

Correct installation is a decisive factor in ensuring that this product complies with 89/336/EEC (EMC Directive), Since you are installing the product yourself, you are also responsible for ensuring compliance with 89/336/EEC,

We will provide you with assistance in the form of EMC information, which can be found in the corresponding technical instructions, Once you have satisfied all the requirements outlined in this documentation and the technical instructions, you can assume (or "suppose") that the product meets all the requirements stipulated in the EMC Directive,

Please remember to observe all binding national, local and system-specific regulations as well,

In order for you to operate your machine within the EU, the following must be available:

- Mark of conformity (CE symbol)
- Declaration(s) of Conformity relating to the relevant Directive(s) for the machine

7.3. Definition of terms in the Declaration of Conformity

A Declaration of Conformity based on this documentation is a declaration that the electrical equipment brought into circulation meets all the basic health and safety regulations that currently apply,

By including the Declaration of Conformity in this chapter, Baumüller Nürnberg GmbH declares that the product complies with all the relevant basic health and safety regulations from the Directives and standards listed in the Declaration of Conformity,

7.4. EU – Declaration of Conformity

CE

BAUMÜLLER

EU-Konformitätserklärung
gemäß

- **Richtlinie 2014/35/EU**
  (Niederspannungsrichtlinie)

  Richtlinie 2014/30/EU
  (EMV-Richtlinie)
  ausschließlich mit Geber, wenn im Motor integriert

Hersteller

Baumüller Nürnberg GmbH
Ostendstr. 80 - 90
90482 Nürnberg
Deutschland
Tel. +49 9 11 54 32 - 0
Fax: +49 9 11 54 32 - 1 30
E-Mail: mail@baumueller.de
Internet: www.baumueller.de

Hiermit erklären wir, dass die nachfolgend genannten Produkte aufgrund ihrer Konzeption, Konstruktion und Bauart in der von uns in Verkehr gebrachten Ausführung den Anforderungen der oben genannten Richtlinien einschließlich der zum Zeitpunkt der Erklärung geltenden Änderungen entsprechen.

Hinweise:

1. Bei Umbau oder Änderungen am Produkt verliert diese Erklärung mit sofortiger Wirkung ihre Gültigkeit.

2. Diese Erklärung bescheinigt die Übereinstimmung mit der genannten Richtlinie, stellt aber keine Zusicherung von darüber hinaus gehenden Produkteigenschaften dar.

3. Die alleinige Verantwortung für die Erstellung der Konformitätserklärung trägt der Hersteller.

Angewandte harmonisierte Normen:

- DIN EN 60034-1:2010
  Drehende elektrische Maschinen – Teil 1:
  Bemessung und Betriebsverhalten
- DIN EN 60034-5:2007-09
  Drehende elektrische Maschinen – Teil 5:
  Schutzarten aufgrund der Gesamtkonstruktion von drehenden elektrischen Maschinen (IP-Code) – Einteilung
- DIN EN 60034-6:1996-08
  Drehende elektrische Maschinen – Teil 6:
  Einteilung der Kühlverfahren (IC-Code)

(Wird fortgesetzt auf der nächsten Seite ...)

EU-Declaration of Conformity
according

- **Directive 2014/35/EU**
  (Low-voltage-directive)

  Directive 2014/30/EU
  (EMC-directive)
  only if there is a electronic feedback-device integrated in the motor

Manufacturer

Baumüller Nürnberg GmbH
Ostendstr. 80 - 90
90482 Nürnberg
Germany
Tel. +49 9 11 54 32 - 0
Fax: +49 9 11 54 32 - 1 30
E-Mail: mail@baumueller.de
Internet: www.baumueller.de

We declare, that the products referred to in the following conform in their concept, construction and design as lauched by us to the above mentioned directives and their respective changes which were valid at the point of declaration.

Notes:

1. By modifying or alternating the device(s) this declaration immediately becomes invalid.

2. This declaration confirms the compliance with the directive listed, but it is no covenant of any further product properties.

3. Only the manufacturer is responsible for the declaration of conformity.

Applied harmonised standards:

- DIN EN 60034-1:2010
  Rotating electrical machines – Part 1:
  Rating and performance
- DIN EN 60034-5:2007-09
  Rotating electrical machines – Part 5:
  Degree of protection provided by the integral design of rotating electrical machines (IP-Code) – Classification
- DIN EN 60034-6:1996-08
  Rotating electrical machines – Part 6:
  Methods of cooling (IC-Code)

(To be continued on the next page ...)

(... Fortsetzung von der vorherigen Seite)

- DIN EN 60034-9:2008-01
  Drehende elektrische Maschinen – Teil 9:
  Geräuschgrenzwerte
- DIN EN 60034-14:2008-03
  Drehende elektrische Maschinen – Teil 14:
  Mechanische Schwingungen von bestimmten Maschinen mit einer Achshöhe von 56 mm und höher – Messung, Bewertung und Grenzwerte der Schwingstärke
- DIN EN 61800-5-1:2015
  Elektrische Leistungsantriebssysteme mit einstellbarer Drehzahl – Teil 5-1:
  Anforderungen an die Sicherheit – Elektrische, thermische und energetische Anforderungen
- EN 60204-1:2006+A1:2009
  Sicherheit von Maschinen - Elektrische Ausrüstung von Maschinen - Teil 1:
  Allgemeine Anforderungen

(... continued from the previous page)

- DIN EN 60034-9:2008-01
  Rotating electrical machines – Part 9:
  Noise limits
- DIN EN 60034-14:2008-03
  Rotating electrical machines – Part 14:
  Mechanical vibration of certain machines with shaft heights 56 mm and higher – Measurement, evaluation and limits of vibration severity
- DIN EN 61800-5-1:2015-
  Adjustable speed electrical power drive systems – Part 5-1:
  Safety requirements – Electrical, thermal and energy
- EN 60204-1:2006+A1:2009
  Safety of machinery - Electrical equipment of machines - Part 1:
  General requirements

Produkt / Product	**Jahr der erstmaligen CE-Kennzeichnung / Year of first CE marking**
DSP1-045XXXXX-XX-XX-XXX-XXX-X-XX-X-XXX **DSP1-056XXXXX-XX-XX-XXX-XXX-X-XX-X-XXX** **DSP1-071XXXXX-XX-XX-XXX-XXX-X-XX-X-XXX** **DSP1-100XXXXX-XX-XX-XXX-XXX-X-XX-X-XXX**	**2013**

Nürnberg, 31.05.2016

i.V.

Leiter Entwicklung Motoren
Head of Motor Development

ppa.

Bereichsleiter Motoren
Business Unit Manager Motors

Headquarters

Baumüller Nürnberg GmbH
Ostendstraße 80–90, 90482 Nürnberg
T: +49 (0) 911 5432 – 0, F: +49 (0) 911 5432 – 130
www.baumueller.com

Baumüller Anlagen-Systemtechnik GmbH & Co. KG
Ostendstraße 84, 90482 Nürnberg
T: +49 (0) 911 54408 – 0, F: +49 (0) 911 54408 – 769
www.baumueller.com

Baumüller Reparaturwerk GmbH & Co. KG
Andernacher Straße 19, 90411 Nürnberg
T: +49 (0) 911 9552 – 0, F: +49 (0) 911 9552 – 999
www.baumueller-services.com

Baumüller DirectMotion GmbH
Flugplatzweg 2, 37581 Bad Gandersheim
T: +49 (0) 5382 9805 – 0, F: +49 (0) 5382 9805 – 55
www.baumueller.com

Nürmont Installations GmbH & Co. KG
Am Keuper 14, 90475 Nürnberg
T: +49 (0) 9128 9255 – 0, F: +49 (0) 9128 9255 – 333
www.nuermont.com

Subsidiaries

Argentina
Mektron ID S.R.L.
José Bonifacio 234, C1424CHF, C.A.B.A,
Buenos Aires
T: +54 011 4922 4086; T/F: +54 011 2075 7048

Australia
Baumüller Australia Pty. Ltd.
19 Baker Street, Botany NSW 2019, Sydney
T: +61 2 83350 – 100, F: +61 2 83350 – 169

Austria
Baumüller Austria GmbH
Schärdinger Straße 13, 4061 Pasching
T: +43 (0) 7229 22822–0, F: +43 (0) 7229 22822–32

Brazil
Baumüller Automação (Sales)
R. Padre Guilherme Pompeu, 1, Centro
06501–055 Santana de Parnaíba S.P.
T: +55–11–4115–8277, M: +55–11–98277–4445

Brazil
NC Motores (Service)
R. Iguassú, 42, Vila São Silvestre
CEP 06417–140 – Baruerí S.P.
T: +55–11–4168–4130, F: +55–11–4168–4144

Canada
Baumueller Canada
6581 Kitimat Road, Unit 8
Mississauga, ON L5N 4J4, Canada
T: +1 905–228–1096, F: +1 905–247–0609

China
Baumüller Automation Equipment Trading (Shanghai) Co., Ltd.
Room 1003 Floor 10th Building C2 Xinjinqiao Rd.1599
Pudong New Zone, Shanghai China
Tel: +86 21 5031 0336; Fax: + 86 21 5031 6106

China
Baumueller Automation (Suzhou) Co., Ltd.
08/D01, No. 1801 Pangjin Road, Wujiang
Economic and Technological Development Zone,
215200 Jiangsu
T: +86 512 6319 3298, F: +86 512 6319 3318

China
Beijing Go-Well Electrical Technology Co. Ltd.
Room 1001, No.7, Huaqing Business Building,
Huaqing Garden, Wudaokou, Haidian District,
100083 Beijing
T: +86(0) 10 8286 7930–856, F: +86(0) 10 8286 7987

France
Baumüller SARL
Parc Saint Exupéry 6 bis, rue Maryse Bastié,
69500 Bron
T: +33 (0) 4 3724 0900, F: +33 (0) 4 7826 3420

Germany
Sales office Dresden
Baumüller Nürnberg GmbH
Fritz-Reuter-Str. 34a, 01097 Dresden
T: +49 (0) 911 5432–517, F: +49 (0) 911 5432–99518

Germany
Sales office Griesheim
Baumüller Nürnberg GmbH
Waldstraße 1, 64347 Griesheim
T: +49 (0) 6155 8430 – 0, F: +49 (0) 6155 8430 – 20

Germany
Sales office Langenhagen
Baumüller Nürnberg GmbH
Bohlenweg 10, 30853 Langenhagen
T: +49 (0) 511 771 968 – 0, F: +49 (0) 511 771 968 – 77

Germany
Sales office Nürnberg
Baumüller Nürnberg GmbH
Ostendstraße 80–90, 90482 Nürnberg
T: +49(0)911 5432–501, F: +49(0)911 5432–510

Germany
Sales office Velbert
Baumüller Nürnberg GmbH
Sontumer Str. 18, 42551 Velbert
T: +49 (0) 2051 80858 – 0 F: +49(0)2051 80858 – 15

Germany – Appen
Nürmont Installations GmbH & Co. KG
Hasenkamp 34, 25482 Appen
T: +49 (0) 4101 37707–0, F: +49 (0) 4101 37707–29

Germany – Freiberg
Nürmont Installations GmbH & Co. KG
Am Junger Löwe Schacht 11, 09599 Freiberg
T: +49 (0) 3731 3084 – 0, F: +49 (0) 3731 3084 – 33

Germany – Kamenz
Baumüller Reparaturwerk GmbH & Co. KG
Nordstraße 57, 01917 Kamenz
T: +49 (0) 3578 3406 – 15, F: +49 (0) 3578 3406 – 50

Germany – München
Baumüller Reparaturwerk GmbH & Co. KG
Meglingerstraße 58, 81477 München
T: +49 (0) 89 748 898 – 0, F: +49 (0) 89 748 898 – 55

Great Britain
Baumüller (UK) Ltd.
Unit 9 Rugby Park, Bletchley Road
Heaton Mersey Industrial Estate
Heaton Mersey, Stockport SK4 3EJ
T: +44 (0) 1614 3278 – 24, F: +44 (0) 1614 3284 – 93

Indien
Baumüller India Pvt. Ltd.
„Kavi" – Survey–94/7, Plot–38, Paud Road,
Bhusari Colony, Kothrud, 411038 Pune
T: +91 20 401603 33, F: +91 20 254241 79

Indien
NÜRMONT Installations India
Baumüller India Pvt. Ltd.
271/8, Ingawale Patil Estate
Pune–Pirangut Road, Bhugaon, 412115 Pune
T: +91 20 40160333/300

Iran
Baumüller Representation Iran
Western Unit, 2nd Floor, Building No. 1, Barmak
Aley, Alvand Street, Argentine Sq.
1516639415 Tehran
T: +98 21 8867 0813, F: +98 21 8878 5342

Israel
SERVI–TECH LTD.
48d HaHaroshet St. Building 34/10
P.O.B 6371, Ind. Zone Carmiel 20651
T: +972–4–9589550, F: +972–4–9589551

Italy
Baumüller Italia S.r.l.
Viale Italia 12, 20094 Corsico (Mi)
T: +39 02 45100 – 181, F: +39 02 45100 – 426

Mexico
Baumueller Nuermont S.A. de C.V.
Carretera Estatal 431 km 2+200, Lote 95 Módulo 11
Parque Industrial Tecnológico Innovación
CP 76246 El Marqués, Querétaro Mexico
T: +52 (442) 221 6670

Netherlands
Baumüller Benelux B.V.
Regenbeemd 6, 4825 AT Breda
T: +31 (0) 76 5717111, F: +31 (0) 76 5871211

Poland
Jarosław Hyla
Area Sales Manager – Poland
T: +48 728 416 444, E: jaroslaw.hyla@baumueller.com

Poland
Mekelburger Polska
Ul. Kóscielna 39 F/3, 60537 Poznán
T: +48 601 87 87 03, F: +48 (0) 61 8481 520

Poland
KF Domena Sp. z o.o.
Ul. Hutnicza 3, 40–241 Katowice
T/F: +48 32 299 04 83

Russia
ProSensor
Zavodskaya Street 1B building 2
124365 Moscow, Zelenograd
T: +7 495 6428 476, F: +7 495 6428 477

Slovenia, Croatia
Baumüller Dravinja d.o.o.
Delavska cesta 10, 3210 Slovenske–Konjice
T: +386 3 75723 – 00, F: +386 3 75723 – 32/33

South Africa
Motion Tronic cc
Unit 15, Nutwood Industrial Park
144 Brackenhill Road, 3652 Waterfall
T: +27 31 7011620, F: +27 86 6150597

South Korea
Bomac Systems
417 Yucheon Factophia, 196 Anyang–7 dong,
Mananku, Anyangsi, Kyungkido 430–017
T: +82 31 467 – 2030, F: +82 31 467 – 2033

South Korea
BMK Co., Ltd
Ssangyoung 3th, 397 Seokcheon–Ro, Ojeong–Gu,
Bucheon–Si, Gyeonggi–Do, Korea
T: +82 32 624–3073, F: +82 32 624–3074

Spain
Baumüller Ibérica, S.L.
C/ Italia, 6, 28916 Leganés (Madrid)
Tel: +34 91 685 66 55,Fax: +34 91 600 08 64

Switzerland
Baumüller Swiss AG
Oberwiesenstrasse 75, 8500 Frauenfeld
T: +41 (0) 52 723 28 – 00, F: +41 (0) 52 723 28 – 01

Thailand
Mr. Tom Sale and Service Co., Ltd.
39/9 Moo 1, Tepkanjana Rd., Tambol Nadee
Amphur Muang, 74000 Samutsakorn
T: +66 34 854932–4, F: +66 34 854935

Turkey
Baumüller Motor Kontrol Sistem San. ve Tic. Ltd. Sti.
Girne Mah., Kücükyali Is Merkezi, B Blok No. 12
Maltepe, 34852 Maltepe – Istanbul
T: +90 216 519 – 9071, F: +90 216 519 – 9072

USA
Baumueller–Nuermont Corp.
1858 S. Elmhurst Road, Mount Prospect, IL 60056
T: +1 847 956–7392, F: +1 847 956–7925

USA
Baumueller–Nuermont Corp.
1555 Oakbrook Drive Suite 120, Norcross, GA 30093
T: +1 678 291–0535, F: +1 678 291–0537

Venezuela, Colombia, Ecuador
Nimbus International – 6941 SW 196th Ave,
Ste. 22, Pembroke Pines, FL 33332, USA
T: +1 954 252 9242; F: +1 954 252 5372

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Responsible for content:
Baumüller Nürnberg GmbH Ostendstraße 80–90 90482 Nürnberg T: +49 (0) 911 5432 – 0 F: +49 (0) 911 5432 – 130 **www.baumueller.com**
Baumüller Anlagen-Systemtechnik GmbH & Co. KG Ostendstraße 84 90482 Nürnberg T: +49 (0) 911 54408 – 0 F: +49 (0) 911 54408 – 769
Baumüller Reparaturwerk GmbH & Co. KG Andernacher Straße 19 90411 Nürnberg T: +49 (0) 911 9552 – 0 F: +49 (0) 911 9552 – 999
Baumüller DirectMotion GmbH Flugplatzweg 2 37581 Bad Gandersheim T: +49 (0) 5382 9805 – 0 F: +49 (0) 5382 9805 – 55

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