

## Compact and accurate Sendix F36 encoders

**Intelligent Scan Technology™.** These optical absolute singleturn and multiturn encoders distinguish themselves particularly by their compact 36 mm size and the award-winning Intelligent Scan Technology™. This technology integrates all singleturn and multiturn functionalities on an OptoASIC and offers high resolution up to 41 bits, 100% magnetic field resistance and cost-efficiency. This construction allows a through hollow shaft up to 8 mm.



### Characteristics and advantages at a glance

- Robust: Safety-Lock™ bearing construction, high IP67 protection level
  - ▶ Installation errors do not lead to standstill, suitable for harsh environments
- Magnetic sensors used because of their low cost can now be replaced with cost-efficient and high-accuracy optical sensors
  - ▶ High performance, high efficiency
- Miniaturised: compact 36 mm construction, hollow shaft up to  $\varnothing$  8 mm, blind hollow shaft up to  $\varnothing$  10 mm
  - ▶ Ideal for restricted mounting spaces
- Speed: position update  $< 1 \mu\text{m}$ , clock frequencies up to 10 MHz
  - ▶ High-resolution real-time feedback, plant improvement and machine performance increase

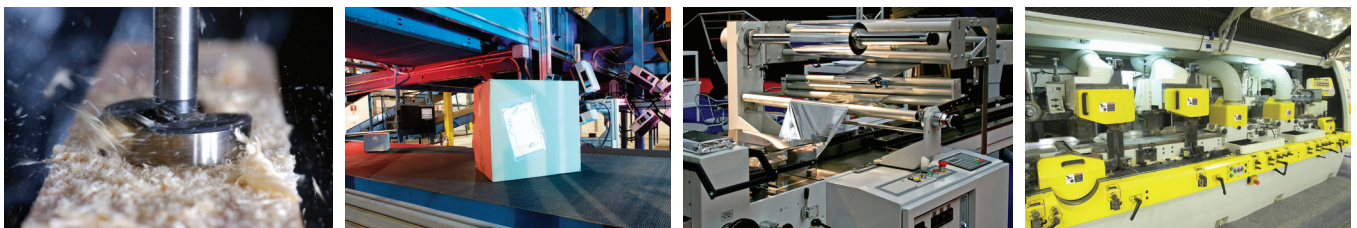


Scan the QR code for further information

### Applications

The Intelligent Scan Technology™ is the answer to fundamental trends in automation: cost-efficiency, miniaturisation and speed. The compact Sendix F36 encoders demonstrate their abilities in the following application examples:

general automation technology, packaging machines, drive technology - especially for small drives.



# Absolute Encoders - Singleturn

<b>Compact Optical</b>	<b>Sendix F3653 / F3673 (Shaft / Hollow shaft)</b>	<b>SSI / BiSS-C</b>
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The Sendix F36 singleturn with the patented Intelligent Scan Technology™ and SSI or BiSS-C interface boasts exceptional ruggedness and compact dimensions.

With a size of just 36 x 42 mm it offers a through hollow shaft of up to 8 mm or a blind hollow shaft of up to 10 mm. Its high-precision optical sensor technology can achieve a resolution of up to 17 bits.



Absolute Encoders Singleturn

Safety-Lock™	Temperature range -40°...+90°C	High protection level IP	High shaft load capacity	Shock / vibration resistant	Magnetic field proof	Short-circuit proof	Reverse polarity protection	SinCos	Optical sensor	Seawater-resistant version on request

### Reliable and magnetically insensitive

- Sturdy bearing construction in Safety-Lock™ Design for resistance against vibration and installation errors
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40°C up to +90°C
- Patented Intelligent Scan Technology™ with all singleturn and multiturn functions on one single OptoASIC - offering highest reliability, a high resolution up to 17 bits and 100% magnetic field insensitivity

### Optimised performance

- High-precision with a data refresh rate of the position value ≤ 1µs
- High-resolution feedback in real-time via incremental outputs SinCos and RS422
- Short control cycles, clock rate with SSI up to 2 MHz / with BiSS-C up to 10 MHz

<b>Order code</b>	<b>8.F3653</b>	<b>.XXXX.XX12</b>	If for each parameter of an encoder the <b>underlined preferred option</b> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.
<b>Shaft version</b>	Type	<b>a b c d e f</b>	
<b>a Flange</b>			
1 = clamping flange, IP67, ø 36 mm [1.42"]			
3 = clamping flange, IP65, ø 36 mm [1.42"]			
2 = synchro flange, IP67, ø 36 mm [1.42"]			
<u>4 = synchro flange, IP65, ø 36 mm [1.42"]</u>			
<b>b Shaft (ø x L), with flat</b>			
1 = ø 6 x 12.5 mm [0.24 x 0.49"]			
<u>3 = ø 8 x 15 mm [0.32 x 0.59"]</u>			
5 = ø 10 x 20 mm [0.39 x 0.79"]			
2 = ø 1/4" x 12.5 mm [0.49"]			
4 = ø 3/8" x 5/8"			
<b>c Interface / Power supply</b>			
1 = SSI or BiSS-C / 5 V DC			
<u>2 = SSI or BiSS-C / 10 ... 30 V DC</u>			
3 = SSI or BiSS-C + 2048 ppr SinCos / 5 V DC			
4 = SSI or BiSS-C + 2048 ppr SinCos / 10 ... 30 V DC			
5 = SSI or BiSS-C, with sensor output for monitoring the voltage on the encoder / 5 V DC			
6 = SSI or BiSS-C + 2048 ppr SinCos, with sensor output for monitoring the voltage on the encoder / 5 V DC			
7 = SSI or BiSS-C + 2048 ppr incr. signals RS422 / 5 V DC			
8 = SSI or BiSS-C + 2048 ppr incr. signals RS422 / 10 ... 30 V DC			
<b>d Type of connection</b>			
<u>1 = cable, tangential, 1 m [3.28] PUR</u>			
3 = cable tangential, 5 m [16.40] PUR			
8 = M12 connector, 8-pin, axial <sup>1)</sup>			
<b>e Code</b>			
B = SSI, Binary			
C = BiSS-C, Binary			
<u>G = SSI, Gray</u>			
<b>f Resolution</b>			
A = 10 bit ST			
2 = 12 bit ST			
<u>3 = 13 bit ST</u>			
4 = 14 bit ST			
7 = 17 bit ST			
optional on request			
- seawater-resistant			
- special cable length			

1) Only with output circuits 1 and 2

# Absolute Encoders - Singleturn

**Compact  
Optical**

**Sendix F3653 / F3673 (Shaft / Hollow shaft)**

**SSI / BiSS-C**

**Order code  
Hollow shaft**

**8.F3673** . **XXXXX** . **XX12**  
Type **a b c d e f**

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces.  
Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.

**10 by 10**

<p><b>a Flange</b> 1 = with spring element short, IP65 3 = with spring element long, IP65 <u>2 = with stator coupling, IP65, ø 46 mm [1.81"]</u></p> <p><b>b Hollow shaft</b> 1 = ø 6 mm [0.24"] 3 = ø 8 mm [0.32"] <u>4 = ø 10 mm [0.39"], blind hollow shaft</u> 2 = ø 1/4"</p>	<p><b>c Interface / Power supply</b> 1 = SSI or BiSS-C / 5 V DC <u>2 = SSI or BiSS-C / 10 ... 30 V DC</u> 3 = SSI or BiSS-C + 2048 ppr SinCos / 5 V DC 4 = SSI or BiSS-C + 2048 ppr SinCos / 10 ... 30 V DC 5 = SSI or BiSS-C, with sensor output for monitoring the voltage on the encoder / 5 V DC 6 = SSI or BiSS-C + 2048 ppr SinCos, with sensor output for monitoring the voltage on the encoder / 5 V DC 7 = SSI or BiSS-C + 2048 ppr incr. signals RS422 / 5 V DC 8 = SSI or BiSS-C + 2048 ppr incr. signals RS422 / 10 ... 30 V DC</p> <p><b>d Type of connection</b> <u>1 = cable, tangential, 1 m [3.28'] PUR</u> 3 = cable tangential, 5 m [16.40'] PUR 8 = M12 connector, 8-pin, axial <sup>1)</sup></p>	<p><b>e Code</b> B = SSI, Binary C = BiSS-C, Binary <u>G = SSI, Gray</u></p> <p><b>f Resolution</b> A = 10 bit ST 2 = 12 bit ST <u>3 = 13 bit ST</u> 4 = 14 bit ST 7 = 17 bit ST</p> <p>optional on request - seawater-resistant - special cable length</p>
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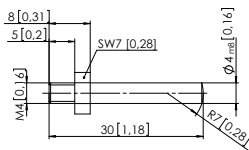
## Mounting accessory for shaft encoders

Order No.

**Coupling** Bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"] **8.0000.1101.0606**

## Mounting accessory for hollow shaft encoders

**Cylindrical pin, long** With fixing thread **8.0010.4700.0000**  
for torque stops



## Connection technology

<b>Connector, self-assembly (straight)</b>	M12 female connector with coupling nut (suitable for connection type 8)	<b>05.CMB 8181-0</b>
<b>Cordset, pre-assembled</b>	M12 female connector with coupling nut, 2 m [6.56'] PVC cable (suitable for connection type 8)	<b>05.00.6041.8211.002M</b>

Further accessories can be found in the accessories section or in the accessories area of our website at: [www.kuebler.com/accessories](http://www.kuebler.com/accessories)

Additional connectors can be found in the connection technology section or in the connection technology area of our website at: [www.kuebler.com/connection\\_technology](http://www.kuebler.com/connection_technology)

## Technical data

### Mechanical characteristics

<b>Maximum speed</b>		
Shaft- or blind hollow shaft version		12 000 min <sup>-1</sup>
without shaft seal (IP65)		10 000 min <sup>-1</sup> (continuous)
Shaft version (IP67) or hollow shaft version		10 000 min <sup>-1</sup>
(IP65) with shaft seal		8 000 min <sup>-1</sup> (continuous)
<b>Starting torque</b>	without shaft seal	< 0.007 Nm
at 20°C [68°F]	with shaft seal (IP67)	< 0.01 Nm
<b>Load capacity of shaft</b>	radial	40 N
	axial	20 N
<b>Weight</b>		approx. 0.2 kg [7.06 oz]

<b>Protection</b> acc. to EN 60529	housing side	IP67
	shaft side	IP65
		(solid shaft version opt. IP67)
<b>Working temperature range</b>		-40°C ... +90°C [-40°F ... +194°F]
<b>Material</b>	shaft / hollow shaft	stainless steel
	flange	aluminium
	housing	zinc die-cast
	cable	PUR
<b>Shock resistance</b> acc. to EN 60068-2-27		2500 m/s <sup>2</sup> , 6 ms
<b>Vibration resistance</b> acc. to EN 60068-2-6		100 m/s <sup>2</sup> , 55 ... 2000 Hz

1) Only with interfaces 1 and 2 in combination with blind hollow shaft 10 mm [0.39"]

# Absolute Encoders - Singleturn

<b>Compact Optical</b>	<b>Sendix F3653 / F3673 (Shaft / Hollow shaft)</b>	<b>SSI / BiSS-C</b>
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Electrical characteristics	
<b>Power supply</b>	5 V DC $\pm$ 5% or 10 ... 30 V DC
<b>Current consumption (no load)</b>	5 V DC max. 60 mA 10 ... 30 V DC max. 30 mA
<b>Reverse polarity protection of the power supply</b>	yes (only with 10 ... 30 V DC)
<b>Short-circuit proof outputs</b>	yes <sup>1)</sup>
<b>UL approval</b>	File 224618
<b>CE compliant acc. to</b>	EMC guideline 2004/108/EC
<b>RoHS compliant acc. to</b>	guideline 2011/65/EU

SSI interface	
<b>Output driver</b>	RS485 transceiver type
<b>Permissible load/channel</b>	max. $\pm$ 30 mA
<b>Signal level</b>	HIGH typ 3.8 V LOW with $I_{Load} = 20$ mA typ 1.3 V
<b>Resolution, singleturn</b>	10 ... 17 bit
<b>Code</b>	Binary or Gray
<b>SSI clock rate</b>	50 kHz ... 2 MHz
<b>Monoflop time</b>	$\leq$ 15 $\mu$ s
<b>Note:</b> If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.	
<b>Data refresh rate</b>	resolution $\leq$ 14 bit $\leq$ 1 $\mu$ s resolution $\geq$ 15 bit 4 $\mu$ s
<b>Status and parity bit</b>	on request

BiSS-C interface	
<b>Resolution, singleturn</b>	10 ... 17 bit
<b>Code</b>	Binary
<b>BiSS-C clock rate</b>	50 kHz ... 10 MHz
<b>Max. update rate</b>	$<$ 10 $\mu$ s, depends on the clock rate and the data length
<b>Data refresh rate</b>	$\leq$ 1 $\mu$ s
<b>Note:</b>	<ul style="list-style-type: none"> <li>– Bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings</li> <li>– CRC data verification</li> </ul>

Incremental outputs (A/B), 2048 ppr		
	SinCos	RS422 TTL-compatible
<b>Max. frequency -3dB</b>	400 kHz	400 kHz
<b>Signal level</b>	1 Vpp ( $\pm$ 20%)	HIGH: min. 2.5 V LOW: max. 0.5 V
<b>Short circuit proof</b>	yes <sup>1)</sup>	yes <sup>1)</sup>

SET input	
<b>Input</b>	active HIGH
<b>Input type</b>	comparator
<b>Signal level (+V = power supply)</b>	HIGH min. 60 % of +V, max: +V LOW max. 30 % of +V
<b>Input current</b>	$<$ 0.5 mA
<b>Min. pulse duration (SET)</b>	10 ms
<b>Input delay</b>	1 ms
<b>New position data readable after</b>	1 ms
<b>Internal processing time</b>	200 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS-C. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the power supply must not be switched off. The SET function should be carried out whilst the encoder is at rest.

DIR input	
A HIGH signal switches the direction of rotation from the default CW to CCW. This inverted function can also be factory-programmed. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The status output will switch to LOW.	
<b>Response time (DIR input)</b>	1 ms

Status output	
<b>Output driver</b>	Open Collector, internal pull up resistor 22 kOhm
<b>Permissible load</b>	max. 20 mA
<b>Signal level</b>	HIGH +V LOW $<$ 1 V
<b>Active</b>	LOW
The status output serves to display various alarm or error messages. In normal operation the status output is HIGH (Open Collector with int. pull-up 22 kOhm).	
An active status output (LOW) displays: LED fault (failure or ageing) – over-temperature – undervoltage In the SSI mode, the fault indication can only be reset by switching off the power supply to the device.	

Power ON	
After Power-ON the device requires a time of approx. 150 ms before valid data can be read.	
Hot plugging of the encoder should be avoided.	

1) Short circuit proof to 0 V or to output when power supply correctly applied

# Absolute Encoders - Singleturn

**Compact  
Optical**

**Sendix F3653 / F3673 (Shaft / Hollow shaft)**

**SSI / BiSS-C**

## Terminal assignment

Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
1, 2	1, 3	SET, DIR, Status	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	Stat	$\perp$			
			Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	VT	Shield			
Interface	Type of connection	Features	M12 connector													
1, 2	8	SET, DIR	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	$\perp$				
			Pin:	1	2	3	4	5	6	7	8	PH				
Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
3, 4	1, 3	SET, DIR, 2048 SinCos	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	A	$\bar{A}$	B	$\bar{B}$	$\perp$
			Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	Shield
Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
5	1, 3	SET, DIR, Sensor output	Signal:	0 V	+V	C+	C-	D+	D-	SET	DIR	0 Vsens	+Vsens	$\perp$		
			Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	VT	RD-BU	Shield		
Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
6	1, 3	2048 SinCos, Sensor output	Signal:	0 V	+V	C+	C-	D+	D-	0 Vsens	+Vsens	A	$\bar{A}$	B	$\bar{B}$	$\perp$
			Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY-PK	RD-BU	Shield
Interface	Type of connection	Features	Cable (Isolate unused wires individually before initial start-up)													
7, 8	1, 3	2048 incr. RS422	Signal:	0 V	+V	C+	C-	D+	D-	A	$\bar{A}$	B	$\bar{B}$	$\perp$		
			Cable colour:	WH	BN	GN	YE	GY	PK	BK	VT	GY-PK	RD-BU	Shield		

- +V: Encoder power supply +V DC
- 0 V: Encoder power supply ground GND (0 V)
- 0 Vsens / +Vsens: Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.
- A,  $\bar{A}$ : Incremental output channel A (cosine)
- B,  $\bar{B}$ : Incremental output channel B (sine)
- C+, C-: Clock signal
- D+, D-: Data signal
- SET: Set input. The current position becomes defined as position zero.
- DIR: Direction input. If this input is active, output values are counted backwards (decrease) when the shaft is turning clockwise.
- Stat: Status output
- PH  $\perp$ : Plug connector housing (Shield)

### Top view of mating side, male contact base



M12 connector, 8-pin

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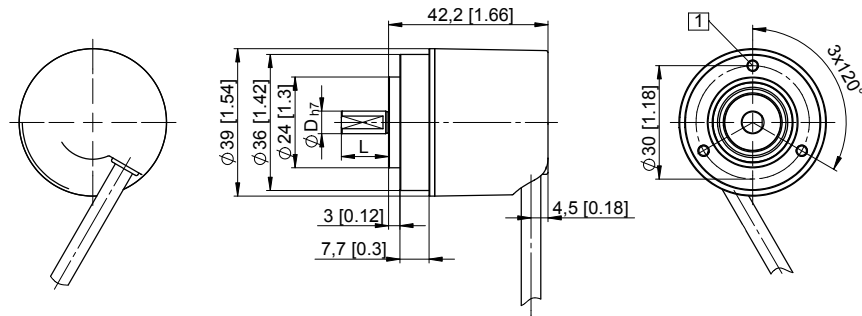
### Dimensions shaft version

Dimensions in mm [inch]

**Clamping flange,  $\varnothing$  36 [1.42]**  
**Flange type 1 and 3**

1 3 x M3, 6 [0.24] deep

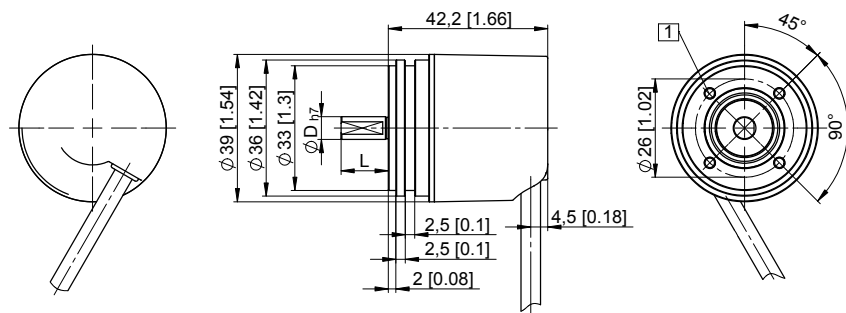
D	L	Fit
6 [0.24]	12.5 [0.49]	h7
8 [0.32]	15 [0.59]	h7
10 [0.39]	20 [0.79]	h7
1/4"	12.5 [0.49]	h7
3/8"	5/8"	h7



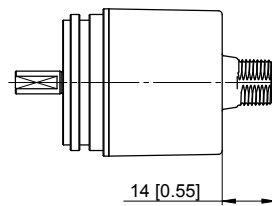
### Synchro flange, $\varnothing$ 36 [1.42]

**Flange type 2 and 4**  
 (Drawing with cable)

1 3 x M3, 6 [0.24] deep



Drawing with M12 connector  
 Type of connection 8



D	L	Fit
6 [0.24]	12.5 [0.49]	h7
8 [0.32]	15 [0.59]	h7
10 [0.39]	20 [0.79]	h7
1/4"	12.5 [0.49]	h7
3/8"	5/8"	h7

# Absolute Encoders - Singleturn

**Compact  
Optical**

**Sendix F3653 / F3673 (Shaft / Hollow shaft)**

**SSI / BiSS-C**

## Dimensions hollow shaft version

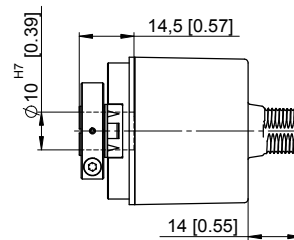
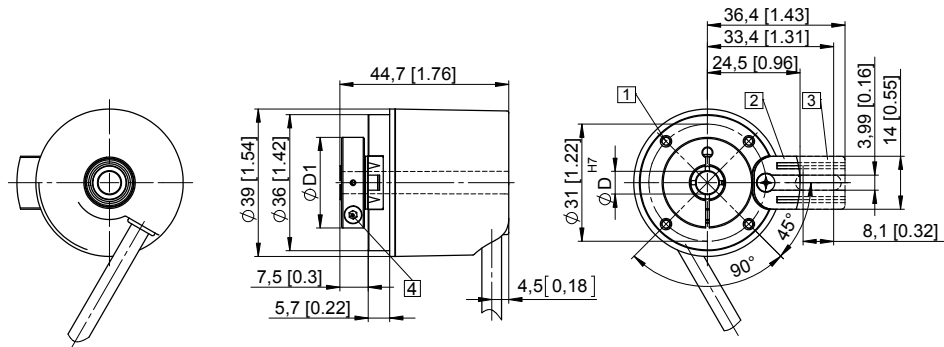
Dimensions in mm [inch]

### Flange with spring element

#### Flange type 1 and 3

(Drawing with spring element short, spring element long is shown dashed)

- 1 M2.5, 5 [0.2] deep
- 2 Spring element short  
Recommendation:  
Cylindrical pin DIN 7,  $\varnothing$  4 [0.16]
- 3 Spring element long  
Recommendation:  
Cylindrical pin DIN 7,  $\varnothing$  4 [0.16]
- 4 Recommended torque for the clamping ring 0.7 Nm



Drawing with M12 connector  
Type of connection 8

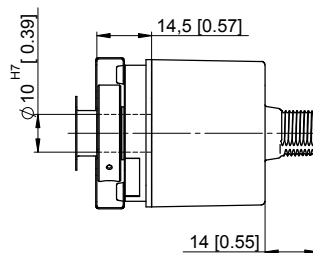
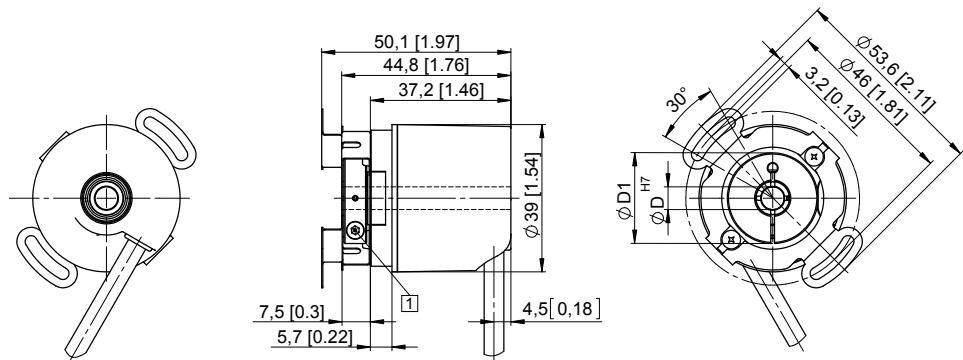
D	D1
6 [0.24]	24 [0.94]
8 [0.32]	25.5 [1.00]
10 [0.39]	25.5 [1.00]
1/4"	24 [0.94]

Insertion depth for blind hollow shaft 14.5 [0.57]

### Flange with stator coupling, $\varnothing$ 46 [1.81]

#### Flange type 2

- 1 Recommended torque for the clamping ring 0.7 Nm



Drawing with M12 connector  
Type of connection 8

D	D1
6 [0.24]	24 [0.94]
8 [0.32]	25.5 [1.00]
10 [0.39]	25.5 [1.00]
1/4"	24 [0.94]

Insertion depth for blind hollow shaft 14.5 [0.57]