Uhing Lineartriebe[®] Uhing Linear Drives[®]

Rollringgetriebe Rolling Ring Drives

Führungssystem Guide System

Wälzmutter Linear Drive Nut

Zahnriemenantriebe Timing Belt Drive

Klemm- und Spannelemente Clamping Systems

> Verlegesysteme Winding Systems

Uhing Motion Drive

















Joachim Uhing GmbH & Co. KG - the originator of the Rolling Ring Principle - successful since 1950. Our worldwide network of agencies guarantees a reliable service on the spot.

More about us at: www.uhing.com

Summary of contents

The Uhing Rolling Ring Principle	2
Applicational areas	3 - 6
Find your suitable rolling ring dri	ve 7
Dimensions and technical details	5
Types RG Shaft diameter Ø 15, 20 and 22 mm	8 - 9
Types RG Shaft diameter Ø 30 and 40 mm	10 - 11
Types RG Shaft diameter Ø 50, 60 and 80 mm	12 - 13
Types RGK Shaft diameter Ø 15, 20 and 22 mm	14 - 15
Types KI, AKI	16
Product survey and ordering information	17
Features	18 - 19
Uhing agents	ww.uhing.com

The Uhing Rolling Ring Principle

Rolling Ring Drives are non positive drives which convert the constant rotation of a plain round shaft into reciprocating motion.

They operate like nuts on a threaded bar, however the pitch both left-hand and right-hand is capable of fine adjustment or can be set at zero.

This effect is achieved by using ball bearing based Rolling Rings which are designed to pivot about the shaft, their specially crowned running surfaces being pressed against the shaft as it rotates.



Range of application for Rolling Ring Drives

- Winding
- Drives
- Surface treatment
- Measuring and testing Materials handling
- -
- Packaging _
- Converting Tyre manufacture _
- Feeds _
- -
- -
- -
- Positioning drives Power amplifiers (servo functions) Traverse drives for speeds up to 4,2 m/sec. Drives for synchronous cutting machines -
- Sequential feed drives -
- Special machines _

Operational areas

	Func	tion													
Industrial Area	Coating	Feeding	Manipulating	Measuring/testing	Opening/closing	Positioning	Cleaning	Cutting/parting	Spraying	Sequencing	Linking	Packing	Spreading	Winding	Mixing
Automation															
Automobile															
Baking machinery															
Wire + Cable industry															
Flat glass/mirrors															
Braiding machinery															
Foil															
Hollow glass ware															
Varnishing															
Food industry															
Paper/cardboard															
Tyres															
Steel															
Textile															
Packaging															
Pharmacy															•



Eddy-current test slide





double winder





Non-contact flange detecting system with laser sensor FA





Buncher



Application at -30° C in the Antarctic



Find your suitable rolling ring drive

Shaft diameter d(mm)	Max. side thrust F _{RG} (N)	Speed max. v* (m/sec)	Types	Page
15	30	0,30	KI3-15-6 MCR	16
15	90	0,30	RGK3-15-0	14
15	110	0,30	RG3-15-2MCRF	8
15	220	0,30	RG4-15-2MCRF	8
20	130	0,30	RGK3-20-1	14
20	160	0,30	RG3-20-2MCRF	8
20	320	0,30	RG4-20-2MCRF	8
22	130	0,30	RGK3-22-1	14
22	160	0,30	RG3-22-2MCRF	8
22	320	0,30	RG4-22-2MCRF	8
30	260	0,40	RG3-30-2MCRF	10
30	520	0,40	RG4-30-2MCRF	10
40	420	0,40	RG3-40-2MCRF	10
40	840	0,40	RG4-40-2MCRF	10
50	700	0,25	RG3-50-OMCR	12
50	1400	0,25	RG4-50-OMCR	12
60	1000	0,25	RG3-60-OMCR	12
60	2000	0,25	RG4-60-OMCR	12
80	1800	0,25	RG3-80-OMCR	12
80	3600	0,25	RG4-80-OMCR	12

*= With standard instantaneous reserval

Example ARG 3-30-2 MCRF





Dimensions for RG-Types (mm)												
Types	Weight (kg)	а	b	Ødh6	e	f	g	n2	ο	Р	x	
RG3-15-2MCRF	0,71	102	63	15	36	32	M5	24	53	16	15,5	
RG4-15-2MCRF	0,86	121	"	"	"	"	"	"	"	"	"	
RG3-20-2MCRF	1,33	124	84	20	70	40	M6	37,5	68	17,5	21	
RG4-20-2MCRF	1,53	133	"	"	"	"	"	"	"	"	"	
RG3-22-2MCRF	1,33	124	84	22	70	40	M6	37,5	68	17,5	21	
RG4-22-2MCRF	1,53	133	"	"	"	"	"	"	"	"	"	

RG-Types





Addition	al dimen	sions for AR		Technical details Thrust Idling max. pit torque drive shaft rota					
h1	h2	l1 *	s	x	**Angle L≥	Frg (N)	Mo(Ncm)	h(mm)	
75	112	150	53	53	750	110	2,5	11,1	
"	"	180	"	53	"	220	4,8	"	
104	145	200	80	63	850	160	2,5	15,5	
"	"	210	"	63	"	320	5,1	"	
104	145	200	80	63	850	160	2,5	16,5	
"	"	210	"	63	"	320	5,1	"	

ARG-Types





Dimensions for RG-Types (mm)														
Types	Weight (kg)	а	a1	Ь	Ødh6	e	f	g	Øm1	n2	0	р	x	
RG3-30-2MCRF	2,7	150	-	105	30	80	50	M6	-	42,5	86	18,5	23	
RG4-30-2MCRF	3,2	180	-	"	"	"	"	"	-	-	"	"	"	
RG3-40-2MCRF	4,4	182	4,5	128	40	100	68	M10	80	68	110	20	25,5	
RG4-40-2MCRF	5,3	210	"	"	"	"	"	"	"	"	"	"	"	









and technical details Uhing Rolling

Addition h1	hal dimensi h2	ons for Al	RG-Typen (mi	m) x	**Angle L≥	Thrust F _{RG} (N)	Technical details Idling torque drive M ₀ (Ncm)	max. pitch/ shaft rotation h(mm)
120	175	240	107,5	75	940	260/400	8/10,2	24
"	"	280	"	"	"	520	12	24
150	220	320	126,5	104	1100	420	28	32
"	"	350	"	"	"	840	50	32





l₁^{*} = for specific features different dimensions are possible



ARG-Types

Dimensions and technical details

Uhing Rolling Ring Drive Types RG and ARG



*F = Special Feature

Dimensions for I	RG-Types (mr	n)										
Types	Weight (kg)	а	Ь	Ødh6	e	f	g	n	0	р	x	
RG3-50-OMCR	9,8	240	154	50	160	90	M12	23	132	35	25,5	
RG4-50-OMCR	11,1	240	"	**	"	"	"	"	"	"	"	
RG3-60-OMCR	17,0	297	190	60	120	80	M12	26	160	32	40	
RG4-60-OMCR	19,6	297	"	"	"	"	"	"	"	"	"	
RG3-80-OMCR	27,0	368	236	80	240	80	M12	23	188	42	40	
RG4-80-OMCR	32,0	368	"	"	"	"	"	"	"	"	"	

RG-Types







Additi	ional dir	nensi	ons for	ARG-	Types (mm)		Heavy duty steady bar	Thrust	Technical details Idling torque drive	max. pitch/ shaft rotation
h1	h2	l1 *	r	S	u	х	у	L≥	F _{RG} (N)	M ₀ (Ncm)	h(mm)
91	235 250 ¹⁾	460	95 100 ¹⁾	81	256 271 ¹⁾	190	130	2000	700	70	40
"	""	"	"	"		"	"	"	1400	120	"
140	330 340 ²⁾	580	115	138	352 362 ²⁾	300	180	3000	1000	90	48
"	"	"	"	"	"	"	"	33	2000	150	"
140	350 380 ³⁾	620	130	138	375 405 ³⁾	300	180	3600	1800	300	75
"	"	"	"	"	""	"	"	"	3600	350	"

1) with L \geq 2000, 2) with L \geq 3000, 3) with L \geq 3600



ARG-Types



Direction of shaft rotation as required

 I_1^* = for specific features different dimensions are possible

Dimensions and technical details

Uhing Rolling Ring Drive Types RGK and ARGK



Dimensions for RGK-Types												
Types	Weight (kg)	а	Ь	d	Ødh6	f	h	i	I	0	Р	Øg
RGK3-15-0	0,53	100	63	34	15	30	17,3	53	15,8	70	46	M5
RGK3-20-1	0,90	120	86	42	20	36	17,5	68	20	90	54	M5
RGK3-22-1	0,90	120	86	42	22	36	17,5	68	20	90	54	M5

RGK-Types









Addit	tional din	nensions fo	or ARGK-Ty	/pes (mm)		Thrust	Technical details Idling torgue drive	max. pitch/ shaft rotation
h1	h2	I 1	s	x	*Angle L \geq	Frg(N)	Mo(Ncm)	h(mm)
75	112	150	53	53	750	90	2,0	8
104	147	200	79	63	850	130	2,3	12
104	147	200	79	63	850	130	2,3	13

ARGK-Types







Shaft extension available on left or right hand side as required

Dimensions and technical details

Uhing Rolling Ring Drive Types KI and AKI



Dimensions	Weight	Max. side thrust	Drive torque	Max. pitch
Туре	(kg)	Frg (N)	M0 (Ncm)	h (mm)
KI3-15-6 MCR	0,28	30	6±0,5	6







Direction of shaft rotation to be specified on order

Type AKI3-15-6MCRW



Product Survey and Ordering Information

Product Survey

	Uhing Linear Drives [®]												
Product Group	Rolling Ring Drive										Kinemax		
Type Reference	RG page 8/10/12 RGK p.14									.14	KI page 16		
	ARG page 9/11/13 ARGK p.15										AKI page 16		
Style Number of rolling rings	3 or 4								3			3	
Size Shaft diameter	15	20	22	30	40	50	60	80	15	20	22	15	
Design Category	2	2	2	2	2	0	0	0	0	1	1	6	
Direction of shaft rotation	L, R								RGK	indepe	L, R		
L = left R = right	ARGK L, R												
Features	see page 18 - 19								s. page 18-19				
Customer Specific	see page 19								wipers			see page 19	
Features													
Pitch max. (mm)	11,4	15,9	17,2	26	33	41	49	76	8,5	12,2	13,3	6,2	

Example of Ordering Specification

Type Reference	KI, AKI, RGK, ARGK, RG, ARG,											
Example		RG	3	-	30	-	2	М	С	R	F	X
Type Reference												
Style												
Seperator Symbol												
Size												
Design Category												
Features												
Customer Specific Features *												

* X e.g. Adapter (twist-free coupling), intermediate support bracket, heavy duty steady bar, drive motor, wipers, special paint finish, additional anti-corrosion protection, double bearing support, special pitch, noise dampening, sequence control, etc.

The following is further required:



- bracket when looking at the pitch selection scale
- extending beyond the lefthand la = bracket when looking at the pitch selection scale





Features

Standard

Rolling Ring Drives Types KI, RGK und RG KI 3-15. RGK3-15/20 RG 3/4-15 to RG 3/4-80



Rolling Ring Drives Types AKI, ARGK und ARG Rolling Ring Drive Units KI, RGK and RG with shaft, steady bars, end brackets and end stops



Additional

Attention: The dimensions and technical Details on the pages 8 to 16 are only valid for the features MCRF resp. MCR/MCR1. For different features ask for dimensional drawings.

Reversal

D *2 Two-way shaft rotation

Reversal mechanism suitable for either direction of

shaft rotation.

adjustable



Push-rod not supplied.

H *2 Control lever. double-sided





trol both before and after the reversal.

Μ Instantaneous reversal

Mechanical spring operated trigger action automatic reversal of the direction of travel. Mini-

provide slowdown con-



mum length of stroke = approx.1x shaft diameter.

N*1 Pneumatic

The direction of travel is reversed by the action of a two-way pneumatic

cylinder (operating pressure = 6 bar).

F*1 **Electro-magnetic**

The direction of travel is reversed by switching two solenoids (24 V D.C.) one for each end of the traverse stroke.



No minimum stroke length requirement.

Please Note: The solenoids are designed for 40% energizing. The permissable energizing period should not be exceeded. Due to the good cooling characteristic related to the fitting of the solenoids directly on the drive unit, the energization duration can be multiplied by a factor of 1,7 to give an effective value of 68%.

ED% =<u>Time Period Switched On</u> x 100 Time Period + Time Period Switched On Switched Off

*2 **Reversal slowdown**



Reversal slowdown for slowdown lengths in excess of 15 mm via cam and contact lever system.

Pitch setting

С Scale



Pitch setting via knob (KI/RGK) or the engagement of a lever in a serrated scale (RG). Simultaneous setting of the same pitch in both directions of travel.

S *2 Set scews

Infinetely variable pitch setting - separate settings for each direction.

Z *2 Worm drive

Simultaneous infinitely variable setting of the same pitch in each direction of travel. Types RG: Supplied without wormwheel drive shaft. If required an operation knob is available (X.)



Types ARG: Supplied with worm drive shaft for remote adjustment from either end (to be specified). Also available with adjustment control (X).

Steady rollers

R

Rolls on rear of unit which (in conjunction with a rear steady bar) prevent the rotation of the unit on the shaft.



Standard with RG3/4-15 to RG3/4-80, ARG3-15 to ARG3/4-40 and RGK3-15/20/22 and ARGK3-15/20/22

R1

Rolls fitted to seperate top mounting plate assembly, used in conjunction with a top



steady bar to prevent the rotation of the unit on the shaft. ARG 3/4-50 to ARG3/4-80.

Free-Movement lever

Mechanical F

After operation of the free-movement lever, the unit can be pushed freely along the shaft.



Standard with RG3/4-15 to RG3/4-40 and RGK

P * 2 Pneumatic

Side thrust of the unit is achieved pneumatically, free movement (pushing the unit freely along the shaft) by venting the membran cylinder. System also suitable for remote control. Operating pressure = 6 bar

Please note: In vertical applications, before operating the free-movement lever please ensure that the load cannot fall in an uncontrolled manner. Injury can result!

Attention: All Rolling Ring Drive Units, especially if fitted with feature F or P are not allowed to be rigid connected to a seperate load carrier.

Stroke width adjustment

B * 2 Self-adjusting end stops

For continuously increasing or decreasing the traverse width

during the winding operation. Only recommended



with units having a free-movement lever (F). Please consult supplier if application is vertical.

W *2 Lead screw operated end stops

Remote lead screw adjustment of the traverse width operated from one of the

bracket positions. Can

also be supplied with a handwheel control or with a control motor drive (X).

Stopping on a rotating shaft and restarting

O * 2 Stopping

The Rolling Ring Drive is brought to a standstill position on the rotating shaft by reducing the pitch to 0. Only available in combination with units having reversal type H, K and V. Restart via O1 or 02.

(For information concerning standstill times, please consult supplier)

O1 *2 Pneumatic restart

Restart activated by a single action pneumatic cylinder (operating pressure = 6 bar) which operate the reversal mechanism.

O2 *2 Electro-magnetic restart

Restart activated by solenoids (operating voltage 24 V D.C.) which operate the reversal mechanism.

Load carrier

LΖ

Roller style load carrier designed to accomodate loads and twisting forces (dimensions upon request).

Customer specific special features Х

Adapter (twist-free coupling) Angle bracket Heavy duty steady bar Drive motor Wipers

Special paint finish Anti-corrosion protection Double bearing support Special pitch Noise dampening Sequence control etc.

Reversal characteristics **E** and **N** can be further combined with reversal characteristics H and V and with stopping character (**O**). With such combination, an additional restart system (01) or (O2) is not required as the restart can be activated by operation of the solenoid (E) or pneumatic cylinder (N).

feature is not available for KI and RGK

We reserve the right to make technical alterations.

end



Worldwide

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